

Geometric reasoning in Machine Learning

Daniel Cohen-Or



Clustering is not easy...

- Clean separation to groups not always possible
- Must make "hard splitting" decisions
- Number of groups not always known, or can be very difficult to determine from data





Hard to determine number of clusters



Hard to determine number of clusters



Hard to decide where to split clusters



Clustering

Hard to decide where to split clusters



Deep Features









... not an elephant



... only part of an elephant



... exaggerated elephant



what is an elephant?

Distillation:

A process of separating the component substances from a liquid mixture.



Distillation:

true object

A process of separating the component substances

from a liquid mixture.

the raw image collection in an unsupervised fashion.



Precision-Recall

- •In distillation, we care just for precision!
- •We aim at being outlier-free.



Related works

Supervised Filtering Methods



Sketch2Photo: Internet Image Montage T. Chen, M.M. Cheng, A. Shamir, S.M. Hu

Unsupervised Object Discovery





Shape Discovery from Unlabeled Image Collections Y. J. Lee, K. Grauman

Discovered Shapes



Co-segmentation

Unsupervised Joint Object Discovery and Segmentation in Internet Images M. Rubinstein, A. Joulin, J. Kopf, C. Liu

The Guiding Principal



Outlier shapes are random in nature, while *inlier* shapes tend to be well supported by similar shapes from other images.

Shape Representation















Grabcut: Interactive foreground extraction usi Menewinal the states of image windows C. Rother, V.TKDeselgers, AF. Brake

Mutual KNN Graph



An *inlier* shape belongs to a tight, non-trivial cluster.

Mutual KNN Graph



Mutual KNN Graph



Choose clusters that are tight and visually informative.

Distilled Collection



Input Collection ("rubber duck")

















Distilled Collection ("rubber duck")



Input Collection ("rocking chair")

















Distilled Collection ("rocking chair")







Outliers are random, inliers are not!













Convex Decomposition by Clustering [SGP13]



Recap of (Exact) Convexity

A convex set of points contains all line segments between each pair of points





No line of sight (within the shape), not convex

Almost Convex..

- Let's relax the definition of convexity, and define "Weak convexity" as:
 - Most of the point pairs on a segment boundary have a line of sight between them



98% lines inside

Weak Convexity

• Convexity rank provides an intuitive weak convexity measure:





Previous Work



Previous Work

• Measure convexity with a convex hull



Weak Convexity

Measure the relative number of mutually visible points!



60% lines inside

90% lines inside

Weak Convex Decomposition

A cluster of mutually visible points is <u>by</u> <u>definition</u> a weakly convex component



Convex Decomposition by Clustering

• We define the weak convexity rank as the degree of mutual visibility in the set

- The convex decomposition is solved by a <u>clustering</u> algorithm
- We avoid over-clustering using the notion of normalized cuts.

Results



How to <u>cluster</u>?



Robust Multi-dimensional Scaling



Constraints as Features





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