MAXIMUM FLOW IN (s, t) PLANAR NETWORKS

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It is well known that a minimum cut of an (s, t) planar network can be found by constructing a shortest (s', t') path in a dual network [1, p. 156]. Itai and Shiloach [2] mention that implementation of this method requires O(n log n) time, however it does not produce the flow function itself. They therefore develop another O(n log n) algorithm which also finds the flow function.

This note shows that a tree of shortest paths rooted at s', which can be found in O(n log n) time, defines not only a minimum cut but also a complete (maximum) flow function.

Let N be a network consisting of a (directed or undirected) graph G = (V, E) with a source s and terminal t, and a capacity function c defined on E. Let $G^d = (V', E')$ be a dual graph of G with s' and t' as its source and terminal, respectively.

Each edge (i, j) in G is associated with an edge (i', j') in G^d , where node i corresponds to node i' and $\cdot j$ corresponds to j'. The procedure for dualizing graphs, including the correspondence between the endpoints of the edges, is described in [3, p. 33]. This correspondence is used to define the direction on the edges of the dual of a directed graph.

Let N' be the network consisting of G^d , and a length function d defined on E', such that d(i', j') is equal to the capacity c(i, j) of the corresponding edge in E. Let u(v) be the length of a shortest path from s' to v, for every $v \in V'$.

A maximum flow function f can be constructed as follows: For each edge $(i, j) \in E$, let $(i', j') \in E'$ be

the dual edge associated with it. Then let f(i, j) = u(j') - u(i'). The proof follows from the following observations:

- (1) For every $(i', j') \in E'$ on a shortest (s', t') path, u(j') u(i') = c(i, j). Therefore f saturates the minimum cuts of N.
- (2) For every $(i', j') \in E' u(j') u(i') \le c(i, j)$, therefore $f(e) \le c(e)$ for every $e \in E$.
- (3) For every cycle $C \in E'$, $\Sigma_{(i',j') \in C}(u(j') u(i')) = 0$. Therefore for every $v \in V$, $\Sigma_{(v,w) \in E} f(v,w) \Sigma_{(w,v) \in E} f(w,v) = 0$.

The algorithm developed by Itai and Shiloach [2] has two steps:

- (1) Search for the 'uppermost' augmenting path.
- (2) Modification of the capacities.

Step 2 is in fact, an implementation of a shortest path algorithm in G^d . Step 1 requires $O(\log n)$ time in each iteration and $O(n \log n)$ time altogether. As I have suggested, this step can be replaced by explicitly constructing G^d at the beginning of the computation. This may be done in linear time.

References

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- [3] E.L. Lawler, Combinatorial Optimization: Network and Matroids (Holt, Rinehart and Winston, New York, 1970).