Inner Functions and Laminations

Oleg Ivrii and Mariusz Urbański

Abstract

In this paper, we study orbit counting problems for inner functions using geodesic and horocyclic flows on Riemann surface laminations. For a one component inner function of finite Lyapunov exponent with $F(0) = 0$, other than $z \to z^d$, we show that the number of pre-images of a point $z \in \mathbb{D} \setminus \{0\}$ that lie in a ball of hyperbolic radius $R$ centered at the origin satisfies

$$N(z, R) \sim \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\mathbb{D}} \log |F'| \, dm}, \quad \text{as } R \to \infty.$$  

For a general inner function of finite Lyapunov exponent, we show that the above formula holds up to a Cesàro average. Our main insight is that iteration along almost every inverse orbit is asymptotically linear. We also prove analogues of these results for parabolic inner functions of infinite height.

Contents

1 Introduction .......................................................... 4
   1.1 An overview of the proofs .................................. 5

2 Inner functions ...................................................... 6

I Centered One Component Inner Functions .................. 9

3 Background on Laminations ..................................... 9
   3.1 Transverse measures ........................................ 11
   3.2 Linear structure ............................................ 11
11 Area on the Lamination 43
  11.1 Möbius structure 45
  11.2 Möbius decomposition theorem 45

12 Linear structure 48
  12.1 Linear decomposition theorem 49

13 The Geodesic Foliation Theorem 50
  13.1 Trajectories land on the solenoid 51
  13.2 Uniqueness 51
  13.3 Rescaling limits and measures 52
  13.4 Abundance of landing points 52
  13.5 Non-singularity 53

14 Orbit Counting 53
  14.1 A weakly almost invariant function 55

IV Parabolic Inner Functions 56

15 Statements of Results 57
  15.1 Background on parabolic inner functions 58
  15.2 Riemann surface laminations 58

V Appendices 60

A A Shadowing Lemma 60

B A Criterion for Angular Derivatives 62

C Integrating over Leaves 64
  C.1 The case of $\tilde{D}$ 64
  C.2 The case of $S^1$ 68
1 Introduction

A finite Blaschke product $F(z)$ is a holomorphic self-map of the unit disk which extends to a continuous dynamical system on the unit circle. Loosely speaking, an inner function is a holomorphic self-map of the unit disk which extends to a measure-theoretic dynamical system of the unit circle. More precisely, we require that for a.e. $\theta \in [0,2\pi)$, the radial boundary value $F(e^{i\theta}) := \lim_{r \to 1} F(re^{i\theta})$ exists and has absolute value 1.

If the Denjoy-Wolff point of $F$ is in the unit disk, then without loss of generality we may assume that $F(0) = 0$, so that 0 is an attracting fixed point of $F$ and the normalized Lebesgue measure $m = |d\theta|/2\pi$ is invariant under $F$. (In this case, we say that $F$ is centered.)

Let $z \in \mathbb{D} \setminus \{0\}$ be a point on the unit disk, other than the origin. For $R > 0$, we may count the number of repeated pre-images $w$ which lie in the ball of hyperbolic radius $R$ centered at the origin:

$$N(z, R) = \# \{ w \in B_{hyp}(0, R) : F^\circ n(w) = z \text{ for some } n \geq 0 \}.$$

Our first main theorem states:

**Theorem 1.1.** Let $F$ be an inner function of finite Lyapunov exponent

$$\chi_m = \int_{\partial \mathbb{D}} \log |F'(re^{i\theta})| \, dm < \infty,$$

with $F(0) = 0$ which is not a rotation. If $z \in \mathbb{D} \setminus \{0\}$ lies outside a set of Lebesgue zero measure, then

$$\lim_{R \to +\infty} \frac{1}{R} \int_0^R \frac{N(z, S)}{e^S} \, dS = \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| \, dm}. \quad (1.1)$$

According to the original definition of W. Cohn in [Coh82], an inner function $F(z)$ is a one component inner function if the set $\{ z \in \mathbb{D} : |F(z)| < \rho \}$ is connected for some $0 < \rho < 1$. For applications to dynamical systems, it is more useful to say that an inner function is a one component inner function if the set of singular values is compactly contained in the unit disk. This implies that backward iteration along every inverse orbit is asymptotically linear.

Our second main theorem states:
Theorem 1.2. Let $F$ be a one component inner function of finite Lyapunov exponent with $F(0) = 0$, other than $z \to z^d$ for some $d \geq 2$. Suppose $z \in \mathbb{D} \setminus \{0\}$ lies outside a set of countable set. Then,

$$\mathcal{N}(z,R) \sim \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| \, dm} \cdot e^R,$$

(1.2)
as $R \to \infty$.

We also obtain analogous results for finite Lyapunov exponent parabolic inner functions of infinite height (in this case, the Denjoy-Wolff point lies on the unit circle). Precise statements will be given in Part IV of the paper.

Remark. (i) Theorems 1.1 and 1.2 may not hold for every point $z \in \mathbb{D}$. For instance, the inner function

$$f(z) = \exp \left( \frac{z + 1}{z - 1} \right)$$

omits the value 0. Post-composing with a Möbius transformation, we get an inner function $F$ with $F(0) = 0$ which omits a value $p \neq 0$. For $z = p$, the set of repeated pre-images of $z$ is empty.

(ii) For $z \to z^d$, $d \geq 2$, repeated pre-images of a point come in packets, so $\mathcal{N}(z,R)$ is a step function.

(iii) For an alternative approach to orbit counting using thermodynamic formalism, see [Ivr15, Section 7] and [IU23]. The results in this paper are somewhat stronger because they only require the minimal hypotheses on the inner function $F$; however, the techniques are specific to inner functions.

(iv) For an analytic characterization of inner functions of finite Lyapunov exponent, we refer the reader to the works [Ivr19, Ivr20, IK22].

1.1 An overview of the proofs

To prove Theorems 1.1 and 1.2 we study the geodesic flow on the Riemann surface lamination $\hat{X}_F$ associated to $F$, which was described in [McM08] for finite Blaschke products. (Definitions will be given in Section 3.) McMullen’s construction generalizes to one component inner functions without much difficulty. According to Sullivan’s dictionary, the Riemann surface lamination is analogous to the unit tangent bundle of a Riemann surface. McMullen showed
that the geodesic flow on $\hat{X}_F$ is ergodic by relating it to a suspension flow over the solenoid. Applying the ergodic theorem to a particular function on the lamination shows Theorem 1.2 up to taking a Cesàro average.

To give a full proof of Theorem 1.2 one needs to show that the geodesic flow on $\hat{X}_F$ is mixing. As in the case of the geodesic flow on a finite area hyperbolic surface, this is done by first showing that the horocyclic flow is ergodic. The main step is to show that the horocyclic flow on $\hat{X}_F$ has a dense orbit. This uses an argument of A. Glutsyuk [Glu10] which involves examining horocycles on a special leaf of $\hat{X}_F$ associated to a repelling fixed point on the circle. From here, the ergodicity of the horocyclic flow follows from an argument of Y. Coudène [Cou09].

Theorem 1.1 requires more work because one has to manually construct the natural volume form $d\xi$ and the geodesic flow $g_t$ on the lamination $\hat{X}_F$ for a general inner function $F$ of finite Lyapunov exponent. To do this, we first show that iteration along almost every inverse orbit is asymptotically linear. The proof uses a number of concepts from differential geometry such as Gaussian and geodesic curvatures.

Remark. In [McM09, Section 10], one learns that inner functions are close to hyperbolic isometries away from the critical points. Consequently, a generic inverse orbit stays away from the critical points.

2 Inner functions

As is well known, any inner function $F$ can be factored into a Blaschke product and a singular inner function:

$$B(z) = e^{ib} \prod_{a_i \in \mathbb{D}} \frac{z - a_i}{|a_i|} \frac{z - a_i}{1 - \overline{a_i}z},$$

$$S(z) = \exp\left(-\int_{\partial\mathbb{D}} \frac{\zeta + z}{\zeta - z} d\mu(\zeta)\right), \quad \mu \geq 0, \quad \mu \perp m.$$

In this decomposition, the Blaschke product records the zero set of $F$, while the singular factor records the zeros of $F$ “dissolved” on the unit circle.

The above decomposition privileges the set of pre-images of 0. To view an inner function from the perspective of a point $a \in \mathbb{D}$, we consider the Frostman
A point \( a \in \mathbb{D} \) is called exceptional if \( F_a \) has a non-trivial singular factor. Frostman showed that the set of exceptional points in the unit disk has logarithmic capacity \( 0 \), while Ahern and Clark [AC74] observed that for inner functions of finite Lyapunov exponent, the exceptional set is at most countable.

The following identity will play an important role in this work:

**Lemma 2.1.** Suppose \( F \) is an inner function with \( F(0) = 0 \). For a non-exceptional point \( z \in \mathbb{D} \setminus \{0\} \),

\[
\sum_{F(w) = z} \log \frac{1}{|w|} = \log \frac{1}{|z|}.
\]

The \( \leq \) inequality holds for every \( z \in \mathbb{D} \).

A proof can be found in [Ivr20, Lemma A.4]. A holomorphic self-map of the unit disk \( F \) has an angular derivative in the sense of Carathéodory at \( \zeta \in \partial \mathbb{D} \) if

\[
F(\zeta) := \lim_{r \to 1} F(r\zeta) \in \partial \mathbb{D} \quad \text{and} \quad F'(\zeta) := \lim_{r \to 1} F'(r\zeta) < \infty.
\]

We will use the following two lemmas on angular derivatives from [AC74]:

**Lemma 2.2.** If we decompose \( F = BS_\mu \) into a Blaschke product with zero set \( \{a_i\} \) and a singular inner function with singular measure \( \mu \), then

\[
|F'(\zeta)| = \sum \frac{1 - |a_i|^2}{|\zeta - a_i|^2} + \int_{\partial \mathbb{D}} \frac{2d\mu(z)}{|\zeta - z|^2}, \quad \zeta \in \partial \mathbb{D}.
\]

In particular, if \( F(0) = 0 \) and \( F \) is not a rotation, then \( |F'(\zeta)| > c > 1 \).

**Lemma 2.3.** If an inner function \( F \) has an angular derivative at \( \zeta \in \partial \mathbb{D} \), then

\[
|F'(r\zeta)| \leq 4|F'(\zeta)|, \quad 0 < r < 1.
\]

The following lemma is a simple consequence of the Schwarz lemma and the triangle inequality:
Lemma 2.4. Suppose $F$ is an inner function with $F(0) = 0$, which is not a rotation. There exists a number $\gamma = \gamma(F) > 0$ so that for any $z \in \mathbb{D}$ with $d_{\mathbb{D}}(0, z) \geq 1$, the hyperbolic distance
\[ d_{\mathbb{D}}(0, f(z)) \leq d_{\mathbb{D}}(0, z) - 4\gamma. \]

The above lemma shows that any ball $B$ of hyperbolic radius $\gamma$ contained in $\{w \in \mathbb{D} : d_{\mathbb{D}}(0, w) \geq 1\}$ does not intersect its forward orbit, i.e. $F^{\circ n}(B) \cap B = \emptyset$, which implies that its inverse images $\{F^{-n}(B)\}$ are disjoint.

Lemma 2.5. Let $F(z)$ be an inner function with $F(0) = 0$ that is not a rotation. For a point $z \in \mathbb{D}$ in the unit disk with $d_{\mathbb{D}}(0, z) > 1$, we have:
\[ N(z, R - 1, R) := N(z, R) - N(z, R - 1) \leq C e^{R - d_{\mathbb{D}}(0, z)}. \]  
(2.3)

In particular,
\[ N(z, R) \leq C e^{R - d_{\mathbb{D}}(0, z)}, \]  
(2.4)

albeit with a slightly larger constant $C$.

Proof. Since $F$ is not a rotation, by Lemma 2.4
\[ d_{\mathbb{D}}(0, F(w)) \leq d_{\mathbb{D}}(0, w) - \gamma, \]  
(2.5)
for any $w \in \mathbb{D}$ with $d_{\mathbb{D}}(0, w) \geq 1$. Repeated use of Lemma 2.1 shows that for any $R \geq 1$,
\[ \sum \log \frac{1}{|w|} \leq \log \frac{1}{|z|}, \]  
(2.6)
where the sum is over $N(z, R - \gamma, R)$ repeated pre-images $w$ of $z$ for which
\[ R - \gamma \leq d_{\mathbb{D}}(0, w) < R. \]

In terms of hyperbolic distance from the origin, (2.6) says that
\[ N(z, R - \gamma, R) \cdot e^{-R} \lesssim e^{-d_{\mathbb{D}}(0, z)}, \]
which shows (2.3) with $N(z, R - \gamma, R)$ in place of $N(z, R - 1, R)$. To obtain the original statement, one just needs to partition the annulus
\[ \{w \in \mathbb{D} : R - 1 < d_{\mathbb{D}}(0, w) < R\} \]
into $1 + \lceil 1/\gamma \rceil$ concentric annuli of hyperbolic widths $\leq \gamma$. \qed
Part I
Centered One Component Inner Functions

We say that an inner function $F$ is *singular* at a point $\zeta \in \partial \mathbb{D}$ if it does not admit any analytic extension to a neighbourhood of $\zeta$. Let $\Sigma \subset \partial \mathbb{D}$ be the set of singularities of $F$. It is clear from this definition that $\Sigma$ is a closed set. While one usually thinks of inner functions as holomorphic self-maps of the unit disk, one may also view $F$ as a meromorphic function on $\hat{\mathbb{C}} \setminus \Sigma$.

In this work, we say that an inner function $F$ is a one component inner function if there is an annulus $\tilde{A} = A(0; \rho, 1/\rho)$ such that $F : \hat{\mathbb{C}} \setminus \Sigma \to \hat{\mathbb{C}}$ is a covering map over $\tilde{A}$. For the equivalence of this definition with the two definitions from the introduction, we refer the reader to [IU23].

Throughout Part 1 we assume that $F$ is a centered one component inner function of finite Lyapunov exponent that is not a rotation. We denote the class of all such inner functions by $\Lambda$.

In Section 3, we define the Riemann surface lamination $\hat{X}$ associated to $F$, as well as the geodesic and horocyclic flows on $\hat{X}$. In Section 4, we discuss almost invariant functions on the unit disk and explain how one can derive orbit counting results from ergodicity and mixing of the geodesic flow.

In Section 5, we show that the horocyclic flow is ergodic and deduce that the geodesic flow is mixing.

3 Background on Laminations

The *solenoid* associated to an inner function $F \in \Lambda$ is defined as the inverse limit

$$\tilde{S}^1 = \lim_{\leftarrow} (F : S^1 \to S^1) = \{(u_i)_{i=-\infty}^{0} : F(u_i) = u_{i+1}\}.$$ 

In other words, a point on the solenoid is given by a point $u_0$ on the unit circle together with a consistent choice of pre-images $u_{-n} = F^{-n}(u_0)$. 
Similarly, we can form the space of backwards orbits of \( F \) on the unit disk

\[
\hat{D} = \lim_{\leftarrow} (F : \mathbb{D} \to \mathbb{D}) \setminus \{0\} = \{(z_i)_{i=-\infty}^0 : F(z_i) = z_{i+1}\} \setminus \{0\},
\]

where \( 0 = \cdots \leftarrow 0 \leftarrow 0 \leftarrow 0 \) is the constant sequence. As we have removed the constant sequence \( 0 \), each backward orbit tends to the unit circle, i.e. \(|z_i| \to 1\) as \( i \to -\infty \).

For both \( \hat{S}^1 \) and \( \hat{D} \), we write \( \pi_{-n} \) for the projection onto the \((-n)\)-th coordinate, i.e. the map \((z_i)_{i=-\infty}^0 \mapsto z_{-n}\).

Let \( \hat{F} : \hat{D} \to \hat{D} \) be the map which applies \( F \) to each coordinate. Its inverse \((z_i)_{i=-\infty}^0 \mapsto (z_{i-1})_{i=-\infty}^0\) is often called the shift map. The quotient

\[
\hat{X} = \hat{D} \setminus \hat{F}
\]

is called the Riemann surface lamination associated to \( F \).

The term Riemann surface lamination refers to the fact that \( \hat{X} \) is locally homeomorphic to \( \mathbb{D} \times \mathcal{C} \), where \( \mathcal{C} \) is some topological space. By contrast, the solenoid \( \hat{S}^1 \) is locally homeomorphic to \((-1,1) \times \mathcal{C}\). When \( F \) is a finite Blaschke product, the fiber \( \mathcal{C} \) is a Cantor set, while if \( F \) is an infinite-degree one component inner function, then \( \mathcal{C} \) is homeomorphic to the shift space on infinitely many symbols \( \{1, 2, \ldots\}^\mathbb{N} \). In particular, the lamination \( \hat{X} \) is a Polish space, that is, a separable completely metrizable topological space. A particular complete metric compatible with the topology will be given in Section 5.1.

We now describe a particularly convenient collection of local charts or flow boxes for \( \hat{X} \). Take a ball \( \mathcal{B} = B(a, r) \) contained in the annulus \( A(0; 1+\frac{\rho}{2}, 1) \) such that \( F^{\circ n}(\mathcal{B}) \cap \mathcal{B} = \emptyset \) for any \( n \geq 1 \). Under this assumption, the sets \( \{F^{-n}(\mathcal{B})\}_{n \geq 0} \) are disjoint. Furthermore, by Koebe’s distortion theorem, for any \( n \geq 0 \), the connected components of \( F^{-n}(\mathcal{B}) \) are approximately round balls that are conformally mapped onto \( \mathcal{B} \) by \( F^{\circ n} \). Let

\[
\hat{\mathcal{B}} := \pi_0^{-1}(\mathcal{B}) \subset \hat{X},
\]

i.e. \( \hat{\mathcal{B}} \) is the collection of all inverse orbits \( z = (z_i)_{i=-\infty}^0 \) with \( z_0 \in \mathcal{B} \). For a finite Blaschke product, one needs finitely many such flow boxes to cover \( \hat{X} \) but for one component inner functions, which are not finite Blaschke products, one needs countably many.
3.1 Transverse measures

For a point \( z \in \mathbb{D} \), the transversal \( T(z) \) is defined as the collection of inverse orbits \( w \) with \( w_0 = z \). If \( w \) is a repeated pre-image of \( z \), we write \( T(w, z) \subset T(z) \) for the subset of inverse orbits which pass through \( w \). We define the Nevanlinna counting measure on \( T(z) \) by specifying it on the “cylinder” sets \( T(w, z) \subset T(z) \), where \( w \) ranges over repeated pre-images of \( z \):

\[
c_z(T(w, z)) = \log \frac{1}{|w|}.
\]

We also define the normalized counting measure by

\[
\bar{c}_z(T(w, z)) = \frac{\log \frac{1}{|w|}}{\log \frac{1}{|z|}}.
\]

If \( z \in \mathbb{D} \) is not a repeated pre-image of an exceptional point, then \( \bar{c}_z \) is a probability measure on \( T(z) \). By Frostman’s theorem, this holds for all but a logarithmic capacity zero set of points in the unit disk.

3.2 Linear structure

We now show that each connected component or leaf of \( \hat{\mathbb{D}} \) associated to a one component inner function from the class \( \Lambda \) is conformally equivalent to \( (\mathbb{H}, \infty) \), while leaves of the solenoid \( \hat{S}^1 \) are homeomorphic to the real line \( \mathbb{R} \sim \partial \mathbb{H} \).

The marked point at infinity provides \( \mathbb{H} \) with a sense of an upward direction: one can define the upward-pointing vector field \( v_\uparrow(z) = y \cdot \frac{\partial}{\partial y} \) on \( \mathbb{H} \). Indeed, \( v_\uparrow \) is well-defined since it is invariant under

\[
\text{Aut}(\mathbb{H}, \infty) = \{ z \mapsto Az + B : A > 0, B \in \mathbb{R} \}.
\]

As backward iteration is essentially linear near the unit circle, one may define an action of the half-plane \( \mathbb{H} \) on \( \hat{\mathbb{X}} \) by

\[
L(z, w)_j := \lim_{n \to \infty} F^{on}(Z_{j-n}(w)), \quad (3.1)
\]

where

\[
Z_j(w) = \frac{z_j}{|z_j|} + \left( \frac{z_j}{|z_j|} - \frac{z_j}{|z_j|} \right) \frac{w}{i}.
\]
With this definition, \( L(z, i) = z \) while the leaf \( \mathcal{L} \) of \( \hat{X} \) containing \( z \) is given by \( \{ L(z, w) : w \in \mathbb{H} \} \).

By restricting \( w \) to the imaginary axis, we obtain the \textit{geodesic flow} on \( \hat{D} \):
\[
g_t(z) := L(z, e^{ti}), \quad t \in \mathbb{R}.
\] (3.2)
By instead restricting \( w \) to the line \( \{ \text{Im } w = 1 \} \), we obtain the \textit{horocyclic flow} on \( \hat{D} \):
\[
h_s(z) := L(z, i + s), \quad s \in \mathbb{R}.
\] (3.3)
The two flows satisfy the relation
\[
g_{-t}h_s(z) = h_{e^{t} s}g_{-t}(z), \quad s, t \in \mathbb{R}.
\] (3.4)

The leaves of \( \hat{X} \) are hyperbolic Riemann surfaces covered by \( (\mathbb{H}, \infty) \). In fact, most leaves are conformally equivalent to \( (\mathbb{H}, \infty) \). The only exceptions are leaves associated to repelling periodic orbits on the unit circle. In this case, one needs to quotient \( (\mathbb{H}, \infty) \) by multiplication by the multiplier of the repelling periodic orbit. See Section 5.2 for details.

It is easy to see that the geodesic and horocyclic flows descend to the Riemann surface lamination \( \hat{X} \). In Section 5 we will see that unless \( F(z) = z^d \) for some \( d \geq 2 \), the geodesic flow on \( \hat{X} \) is mixing, while the horocyclic flow on \( \hat{X} \) is ergodic. In the exceptional case, the geodesic flow will be ergodic but not mixing.

### 3.3 Natural measures

We endow the solenoid with the probability measure \( \hat{m} \) obtained by taking the natural extension of the Lebesgue measure on the unit circle with respect to the map \( F : S^1 \to S^1 \). The measure \( \hat{m} \) which is uniquely characterized by the property that its pushforward under any coordinate function \( \pi_i : \hat{S}^1 \to S^1, \ i \in -\mathbb{N}_0 \), is equal to \( m \). Equivalently, \( \hat{m} \) is the unique \( \hat{F} \)-invariant measure on \( \hat{S}^1 \) whose pushforward under \( \pi_0 \) is equal to \( m \). As the Lebesgue measure \( m \) on the unit circle is ergodic for \( F : S^1 \to S^1 \), the measure \( \hat{m} \) is ergodic for \( \hat{F} : \hat{S}^1 \to \hat{S}^1 \).

We define a natural measure on the Riemann surface lamination \( \hat{X} \) by
\[
d\xi = \hat{m} \times (dy/y) = c_z \times \frac{dx dy}{y^2},
\]
of total mass $\int_{\hat{S}^1} \log |F'| \, dm$, where $x + iy$ is an affine parameter on each leaf of $\hat{X}$. Note that $dy/y$ is a well-defined 1-form on the Riemann surface lamination since it is invariant under $\text{Aut} (\mathbb{H}, \infty)$. By construction, $d\xi$ is invariant under the geodesic and horocyclic flows on $\hat{X}$.

For a measurable set $A$ contained in the unit disk, we write $\hat{A}$ for the collection of inverse orbits $z$ with $z_0 \in A$. By Koebe’s distortion theorem, we have:

**Lemma 3.1.** For a measurable set $A$ contained in the annulus $A(0; \frac{1+\rho}{2}, 1)$,

$$\xi(\hat{A}) \asymp \int_A \frac{dA(z)}{1-|z|}. $$

In fact, for any $\varepsilon > 0$, there exists an $\frac{1+\rho}{2} < \rho' < 1$ so that

$$(1 - \varepsilon) \cdot \frac{1}{2\pi} \int_A \frac{dA(z)}{1-|z|} \leq \xi(\hat{A}) \leq (1 + \varepsilon) \cdot \frac{1}{2\pi} \int_A \frac{dA(z)}{1-|z|}$$

for any measurable set $A \subset A(0; \rho', 1)$.

### 3.4 Exponential coordinates and the suspension flow

In order to show that the geodesic flow $g_s : \hat{X} \to \hat{X}$ is ergodic, McMullen [McM08, Theorem 10.2] relates it to a suspension flow over the solenoid. Let $\rho(z) = \log |F'(z)|$. The suspension space

$$\hat{S}^1_\rho = \hat{S}^1 \times \mathbb{R}_+ / \{(z,t) \sim (F(z), e^{\rho(z)} \cdot t)\}$$

carries a natural measure $\hat{m}_\rho = \hat{m} \times (dt/t)$ that is invariant under the suspension flow $\sigma_s : \hat{S}^1_\rho \to \hat{S}^1_\rho$ which takes $(z,t) \to (z, e^s \cdot t)$.

**Theorem 3.2.** The geodesic flow $(\hat{X}, d\xi, g_s)$ on the Riemann surface lamination is equivalent to the suspension flow $(\hat{S}^1_\rho, \hat{m}_\rho, \sigma_s)$ on the suspension of the solenoid with respect to the roof function $\rho = \log |F'|$.

**Sketch of proof.** The isomorphism between $\hat{S}^1 \times \mathbb{R}_+$ and $\hat{D}$ is given by the exponential map

$$E(u, t) = \lim_{n \to \infty} F^{\text{con}}(u_{i-n} + v_{i-n}), \tag{3.5}$$
where
\[ v_{i-n} = -\frac{t \cdot u_{i-n}}{|(F^{m-1})'(u_{i-n})|}. \]
By Koebe’s distortion theorem,
\[ E(u, t)_i = u_i + v_i + o(|v_i|). \]  (3.6)
In these exponential coordinates, the geodesic flow \( g_s : \hat{D} \to \hat{D} \) takes the form
\[ g_s(E(u, t)) = E(u, e^s \cdot t). \]  (3.7)
As a result, the exponential map descends to an isomorphism between \( \hat{S}^1_\rho \) and \( \hat{X} \) and intertwines the geodesic and suspension flows.

Since \( m \) is ergodic under \( F \) on the unit circle, \( \hat{m} \) is ergodic under \( \hat{F} \) on the solenoid and \( \hat{m}_\rho \) is ergodic under the suspension flow on \( \hat{S}^1_\rho \). The above theorem then implies that the geodesic flow on \( \hat{X} \) is ergodic.

Remark. The presentation of this section is inspired by [McM08, Section 10]. In Part II, we will give another perspective on the measure \( \xi \) and the geodesic and horocyclic flows on \( \hat{X} \), in the context of general inner functions of finite Lyapunov exponent (which may not be one component).

4 Almost Invariant Functions

We say that a function \( h : \hat{D} \to \mathbb{C} \) is almost invariant under \( F \) if
\[ \limsup_{|F^{m}(z)| \to 1} |h(F^m(z)) - h(z)| = 0. \]
In particular, for every backward orbit \( z = (z_i)_{i=-\infty}^0 \in \overline{D} \), \( \lim_{i \to -\infty} h(z_i) \) exists and defines a function on the Riemann surface lamination:
\[ \hat{h}(z) = \lim_{i \to -\infty} h(z_i). \]

4.1 Consequences of ergodicity and mixing

In the following two theorems, we use ergodicity and mixing of the geodesic flow on \( \hat{X} \) to study almost invariant functions. The first theorem is a slight
generalization from [McM08, Theorem 10.6], which was originally stated for finite Blaschke products. For the convenience of the reader, we describe its proof in the setting of one component inner functions.

**Theorem 4.1.** Let \( F \in \Lambda \) be a one component inner function for which the geodesic flow on \( \hat{X} \) is ergodic. Suppose \( h : \mathbb{D} \to \mathbb{C} \) is a bounded almost invariant function that is uniformly continuous in the hyperbolic metric. Then for almost every \( \zeta \in S^1 \), we have

\[
\lim_{r \to 1} \frac{1}{\log(1-r)} \int_0^r h(s\zeta) \cdot \frac{ds}{1-s} = \int_{\hat{X}} \hat{h} \, d\xi.
\]

In particular,

\[
\lim_{r \to 1} \frac{1}{2\pi \log(1-r)} \int_{\mathbb{D}_r} h(z) \cdot \frac{dA(z)}{1-|z|} = \int_{\hat{X}} \hat{h} \, d\xi.
\]

**Proof.** The ergodic theorem tells us that for almost every \( u \in \hat{S}^1 \), the backward time averages

\[
\lim_{T \to 0} \frac{1}{|\log T|} \int_T^1 \hat{h}(E(u,t)) \cdot \frac{dt}{t} = \int_{\hat{X}} \hat{h} \, d\xi.
\]

Write \( z(t) = E(u,t) \). By almost-invariance, we have

\[
\hat{h}(E(u,t)) = h(z_0(t)) + o(1), \quad \text{as } t \to 0^+,
\]

while

\[
h(z_0(t)) = h((1-t)u_0) + o(1), \quad \text{as } t \to 0^+,
\]

by (3.6) and the uniform continuity of \( h \) in the hyperbolic metric. Consequently,

\[
\lim_{T \to 0} \frac{1}{|\log T|} \int_T^1 \hat{h}((1-t)u_0) \cdot \frac{dt}{t} = \int_{\hat{X}} \hat{h} \, d\xi.
\]

The proof is completed after making the change of variables \( s = 1 - t \) and relabeling \( \zeta = u_0 \) and \( T = 1 - r \).

**Theorem 4.2.** Let \( F \in \Lambda \) be a one component inner function for which the geodesic flow on \( \hat{X} \) is mixing. Suppose \( h : \mathbb{D} \to \mathbb{C} \) is a bounded almost invariant function that is uniformly continuous in the hyperbolic metric. Then,

\[
\lim_{r \to 1} \int_{|z|=r} h(z) \, dm = \frac{1}{\int_{S^1} \log |F'| \, dm} \int_{\hat{X}} \hat{h} \, d\xi.
\]
Proof. Consider a thin annulus

\[ A = A_{\text{hyp}}(0; R_0, R_0 + \delta) = \{ w : R_0 < d_\mathbb{D}(0, w) < R_0 + \delta \} \subset \mathbb{D} \]

of hyperbolic width \( \delta \). Let \( \hat{A} \subset \hat{X} \) be the collection of backwards orbits that pass through \( A \). Since the geodesic flow is mixing, we have that

\[
\lim_{t \to \infty} \frac{1}{\xi(A)} \cdot \langle \chi_{\hat{A}} \circ \gamma_t, h \rangle = \frac{1}{\int_{S^1} \log |F'| dm} \int_{\hat{X}} \hat{h} d\xi.
\]  

(4.1)

In view of Lemma 3.1, when \( R_0 > 0 \) is large,

\[
\hat{\xi}(\hat{A}) \approx \frac{1}{2\pi} \int_{A_t} \frac{dA(z)}{1 - |z|} \approx \delta, \quad \chi_{\hat{A}} \circ \gamma_t \approx \chi_{\hat{A}, t},
\]

where \( A_t = A_{\text{hyp}}(0; R_0 + t, R_0 + t + \delta) \). Therefore, by the almost invariance of \( h \), the left hand side of (4.1) is approximately

\[
\frac{1}{2\pi\delta} \int_{A_t} h(z) \frac{dA(z)}{1 - |z|}.
\]

When \( \delta > 0 \) is small, by the uniform continuity of \( h \), this is approximately

\[
\int_{\partial B_{\text{hyp}}(0, R_0 + t)} h(z) dm
\]

as desired. \( \square \)

4.2 Orbit counting in presence of mixing

For a point \( z \in \mathbb{D} \) sufficiently close to the unit circle and \( 0 < \delta < 1 \), we construct an almost invariant function \( h_{z, \delta} \) concentrated on a hyperbolic \( O(\delta) \)-neighbourhood of the inverse images of \( z \):

1. By a box in the unit disk, we mean a set of the form

\[
\square = \{ w \in \mathbb{D} : \theta_1 < \arg w < \theta_2, r_1 < |w| < r_2 \}.
\]

For a point \( z \) with \( |z| > 1/2 \) and \( \delta > 0 \) small, we write \( \square = \square(z, \delta) \) for the box centered at \( z \) of hyperbolic height \( \delta \) and hyperbolic width \( \delta \).
2. Recall that a one component inner function $F$ acts as a covering map over an $\tilde{A} = A(0; \rho, 1/\rho)$. In particular, when $|z|$ is close to 1 and $\delta$ is small, the repeated pre-images $F^{-n}(\square)$ consist of disjoint squares of roughly the same hyperbolic size as the original, albeit distorted by a tiny amount. Define $h_{\text{rough}}(w) = 1$ if $w \in F^{-n}(\square)$ for some $n \geq 0$ and $h_{\text{rough}}(w) = 0$ otherwise.

3. We now smoothen the function from the previous step. To that end, consider a slightly smaller box $\square_2 = \square(z, \delta - \eta)$ with $\eta \ll \delta$. Define $h_{z,\delta}$ to be a smooth function on $\square$ which is 1 on $\square_2$, 0 on $\partial \square$, and takes values between 0 and 1. Extend $h_{z,\delta}$ to $\bigcup_{n \geq 1} F^{-n}(\square)$ by backward invariance. Finally, extend $h_{z,\delta}$ by 0 to the rest of the unit disk. Using the Schwarz lemma, it is not hard to see that $h_{z,\delta}$ is uniformly continuous in the hyperbolic metric.

**Theorem 4.3.** Let $F \in \Lambda$ be a one component inner function for which the geodesic flow on $\tilde{X}$ is mixing. Suppose $z \in \mathbb{D} \setminus \{0\}$ lies outside a set of countable set. Then,

$$N(z, R) \sim \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| \, dm} \cdot e^R,$$

as $R \to \infty$.

**Proof.** We will show (4.2) for any point $z \in \mathbb{D} \setminus \{0\}$ which does not belong to a forward orbit of an exceptional point of $F$. From the results of Ahern and Clark discussed in Section 2, it is easy to see that this set is at most countable.

Below, we write $A \sim \varepsilon, \delta, R$ to denote that

$$(1 - o(1))(1 - C\varepsilon) \leq A/B \leq (1 + o(1))(1 + C\varepsilon)$$

as $\delta \to 0^+$ and $R \to \infty$.

**Step 1.** Suppose $z \in A(0; 1 - \varepsilon, 1)$ where $\varepsilon > 0$ is sufficiently small so the function $h_{z,\delta}$ is defined. In this step, we show that

$$N(z, R) \sim \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| \, dm} \cdot e^R.$$
To this end, we apply Theorem 4.2 with $h = h_{z,\delta}$. In view of Lemma 3.1,

$$\frac{1}{\int_{S^1} \log |F'| dm} \int_{\tilde{X}} h_{z,\delta} d\xi \sim_{\varepsilon,\delta} \frac{1}{\int_{S^1} \log |F'| dm} \cdot \frac{\delta^2}{2\pi} \cdot \log \frac{1}{|z|}.$$ 

Since hyperbolic distance $\delta$ along the circle $\partial B_{\text{hyp}}(0, R)$ corresponds to Euclidean distance of roughly $(2/e^R)\delta$,

$$\int_{\partial B_{\text{hyp}}(0, R)} h_{z,\delta} dm \sim_{\varepsilon,\delta, R} \frac{1}{2\pi} \cdot \frac{2\delta}{e^R} \cdot N(z, R - \delta, R),$$

where

$$N(z, R - \delta, R) = \#\{w \in A_{\text{hyp}}(0; R - \delta, R) : F^{\circ n}(w) = z \text{ for some } n \geq 0\}.$$ 

Comparing the two equations above, we see that

$$N(z, R - \delta, R) \sim_{\varepsilon,\delta, R} \frac{\delta}{\int_{S^1} \log |F'| dm} \cdot \frac{1}{|z|} \cdot e^R.$$ 

Integrating with respect to $R$ and taking $\delta \to 0$ shows (4.3).

**Step 2.** Let $z \in \mathbb{D} \setminus \{0\}$ be an arbitrary point in the punctured unit disk, which is not contained in the forward orbit of an exceptional point. In view of Lemma 2.4 for any $\varepsilon > 0$, one can find an integer $m \geq 0$, so that any $m$-fold pre-image of $z$ is contained in $A(0; 1 - \varepsilon, 1)$.

By Lemma 2.1

$$\sum_{F^{\circ m}(w) = z} \log \frac{1}{|w|} = \log \frac{1}{|z|}.$$ 

We choose a finite set of $m$-fold pre-images $G_m$ so that

$$\sum_{w \in G_m} \log \frac{1}{|w|} > \log \frac{1}{|z|} - \varepsilon.$$ 

By Step 1, there exists a constant $C > 0$ (depending on $F$) so that

$$N(z, R) \geq \sum_{w \in G_m} N(w, R) \geq (1 - C\varepsilon) \cdot \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| dm} \cdot e^R,$$

for any $R > R_0(F, z)$ sufficiently large, depending on the inner function $F$ and the point $z \in \mathbb{D} \setminus \{0\}$. 

18
**Step 3.** It remains to prove a matching upper bound. We use the same $m \geq 0$ as in the previous step. For any $0 \leq k \leq m$, let $T_k$ denote the set of repeated pre-images of $z$ of order $k$. Since

\[
\sum_{w \in T_k} \log \frac{1}{|w|} = \log \frac{1}{|z|}
\]

is finite by Lemma 2.1, one can find a finite set $G_k \subset T_k$ so that

\[
\sum_{w \in T_k \setminus G_k} \log \frac{1}{|w|} < \varepsilon/m.
\] (4.4)

Let $G = \bigcup_{k=0}^{m} G_k$ and $B = \bigcup_{k=0}^{m} (T_k \setminus G_k)$. A somewhat crude estimate shows that

\[
\mathcal{N}(z, R) \leq |G| + \sum_{w \in G_m} \mathcal{N}(w, R) + \sum_{w \in B} \mathcal{N}(w, R).
\]

By Step 1,

\[
\sum_{w \in G_m} \mathcal{N}(w, R) \leq (1 + C\varepsilon) \cdot \frac{1}{2} \log \frac{1}{|z|} \cdot \int_{\partial D} \log |F'| dm \cdot e^R,
\]

while $\sum_{w \in B} \mathcal{N}(w, R)$ can be estimated using (4.4) and Lemma 2.5. □

### 4.3 Orbit counting in presence of ergodicity

We now explain how to use the ergodicity of the geodesic flow to show orbit counting up to a Cesàro average:

**Theorem 4.4.** Let $F \in \mathcal{A}$ be a one component inner function for which the geodesic flow on $\hat{X}$ is ergodic. If $z \in \mathbb{D} \setminus \{0\}$ lies outside a countable set, then

\[
\lim_{R \to +\infty} \frac{1}{R} \int_0^R \frac{\mathcal{N}(z, S)}{e^S} dS = \frac{1}{2} \log \frac{1}{|z|} \cdot \int_{\partial D} \log |F'| dm \cdot e^R.
\] (4.5)

As the proof follows the same pattern as that of Theorem 4.3, we only sketch the differences.

**Sketch of proof. Step 0.** The theorem boils down to showing

\[
\frac{1}{R} \sum_{\substack{F^n(w) = z, n \geq 0 \\
w \in B_{hyp}(0, R)}} e^{-d_\mathbb{D}(0,w)} \to \frac{1}{2} \log \frac{1}{|z|} \cdot \int_{\partial D} \log |F'| dm,
\] (4.6)
as $R \to \infty$. Indeed, once we show (4.6), the theorem follows from the following computation:

\[
\frac{1}{R} \int_0^R \frac{N(z,S)}{e^S} \, dS = \frac{1}{R} \sum_{\substack{F^n(w) = z, \\ n \geq 0, \\ w \in B_{hyp}(0,R) \}} \int_{d_2(0,w)} e^{-S} \, dS \\
= \frac{1}{R} \sum_{\substack{F^n(w) = z, \\ n \geq 0, \\ w \in B_{hyp}(0,R) \}} (e^{-d_2(0,w)} - e^{-R}) \\
= \frac{1}{R} \sum_{\substack{F^n(w) = z, \\ n \geq 0, \\ w \in B_{hyp}(0,R) \}} e^{-d_2(0,w)} + o(1),
\]

where in the last step we have used the a priori bound (2.3) to estimate the number of terms.

**Step 1.** Suppose $z \in A(0; 1 - \varepsilon, 1)$ where $\varepsilon > 0$ is sufficiently small so the function $h_{z,\delta}$ is defined. In this step, we show that

\[
\frac{1}{R} \sum_{\substack{F^n(w) = z, \\ n \geq 0, \\ w \in B_{hyp}(0,R) \}} e^{-d_2(0,w)} \sim_{\varepsilon, R} \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| \, dm}.
\]

Applying Theorem 4.1 to the almost invariant function $h = h_{z,\delta}$, we get

\[
\lim_{R \to \infty} \left\{ \frac{1}{2\pi R} \int_{B_{hyp}(0,R)} h(x) \frac{dA(x)}{1 - |x|} \right\} = \frac{1}{\int_{\partial \mathbb{D}} \log |F'| \, dm} \int_{\mathbb{X}} \hat{h}d\xi.
\]

The left hand side of (4.8) is approximately

\[
\sim_{\varepsilon, R} \frac{1}{2\pi R} \sum_{\substack{F^n(w) = z, \\ n \geq 0, \\ w \in B_{hyp}(0,R) \}} \int_{\square(w,\delta)} h(x) \cdot \frac{dA(x)}{1 - |x|} \]

\[
\sim_{\varepsilon, R} \frac{1}{\pi R} \sum_{\substack{F^n(w) = z, \\ n \geq 0, \\ w \in B_{hyp}(0,R) \}} e^{-d_2(0,w)} \cdot \int_{\square(w,\delta)} h(x) \cdot \frac{dA(x)}{(1 - |x|^2)^2}.
\]

Meanwhile, by Lemma 3.1, the right hand side of (4.8) is more or less

\[
\sim_{\varepsilon, \delta} \frac{1}{2\pi} \int_{\partial \mathbb{D}} \log |F'| \, dm \int_{\square(\varepsilon,\delta)} h(x) \cdot \frac{dA(x)}{1 - |x|} \\
\sim_{\varepsilon, \delta} \frac{1}{2\pi} \int_{\partial \mathbb{D}} \log |F'| \, dm \cdot \log \frac{1}{|z|} \cdot \int_{\square(\varepsilon,\delta)} h(x) \cdot \frac{dA(x)}{(1 - |x|^2)^2}.
\]
As \( h \) is almost invariant, we have

\[ \int_{\mathbb{D}(w, \delta)} h(x) \frac{dA(x)}{(1 - |x|^2)^2} \sim_{\varepsilon, \delta} \int_{\mathbb{D}(z, \delta)} h(x) \frac{dA(x)}{(1 - |x|^2)^2}, \]

for any repeated pre-image \( w \) of \( z \). Putting the above equations together and taking \( \delta \to 0^+ \), we get (4.7).

**Step 2.** Let \( z \in \mathbb{D} \setminus \{0\} \) be an arbitrary point in the punctured unit disk, which is not contained in the forward orbit of an exceptional point. Arguing as in Step 2 of Theorem 4.3, one can show that for any \( \varepsilon > 0 \),

\[ \frac{1}{R} \sum_{\substack{F^n(w) = z, \ n \geq 0 \\ w \in B_{\text{hyp}}(0, R)}} e^{-d_\delta(0, w)} \geq (1 - C\varepsilon) \cdot \frac{1}{2} \cdot \log \frac{1}{|z|} \cdot \frac{1}{\partial D} \log |F'| \, dm, \tag{4.9} \]

provided that \( R > R_0(F, z) \) is sufficiently large, which may depend on the inner function \( F \) and the point \( z \in \mathbb{D} \setminus \{0\} \).

**Step 3.** Arguing as in Step 3 of Theorem 4.3, it is not difficult to find a matching upper bond

\[ \frac{1}{R} \sum_{\substack{F^n(w) = z, \ n \geq 0 \\ w \in B_{\text{hyp}}(0, R)}} e^{-d_\delta(0, w)} \leq (1 + C\varepsilon) \cdot \frac{1}{2} \cdot \log \frac{1}{|z|} \cdot \frac{1}{\partial D} \log |F'| \, dm, \tag{4.10} \]

for \( R > R_0(F, z) \) is sufficiently large. As \( \varepsilon > 0 \) was arbitrary in Steps 2 and 3, the proof is complete.

\[ \square \]

## 5 Mixing of the Geodesic Flow

In this section, \( F \in \Lambda \) will be a centered one component inner function of finite Lyapunov exponent, which is not \( z \to z^d \) for some \( d \geq 2 \). We will show that the horocyclic flow on \( \hat{X} \) is ergodic and the geodesic flow on \( \hat{X} \) is mixing. The proof proceeds in four steps.

1. One first shows that the multipliers of the repelling periodic orbits are not contained in a discrete subgroup of \( \mathbb{R}^+ \). This step has been completed in [U23 Section 5]. This provides a large supply of homoclinic orbits.
2. We use an argument of Glutsyuk [Glu10] to show that the horocyclic flow has a dense trajectory.

3. We use an argument of Coudène [Cou09] to promote the existence of a dense horocycle to the ergodicity of the horocyclic flow.

4. Finally, we use the ergodicity of the horocyclic flow to show the mixing of the geodesic flow. This can be done as in the case of a hyperbolic toral automorphism.

5.1 A metric on the lamination

In order to discuss uniformly continuous functions on \( \hat{X} \), we endow \( \hat{X} \) with a metric that is compatible with the topology described in Section 3. For \( z, w \in \hat{D} \), we define

\[
d_{\hat{X}}(z, w) := \min_{n \in \mathbb{Z}} \left\{ \max(1 - |z_n|, 1 - |w_n|) + d_D(z_n, w_n) \right\}.
\]

To define a metric on the lamination, we try to align the indices as closely as possible:

\[
d_{\hat{X}}(z, w) := \min_{m \in \mathbb{Z}} d_{\hat{D}}(z, \hat{F}^m(w)).
\]

As the above metric is complete and separable, \( \hat{X} \) is a Polish space, but it is not locally compact unless \( F \) is a finite Blaschke product.

**Lemma 5.1.** Any leaf \( \mathcal{L} \) is dense in \( \hat{X} \).

**Proof.** Suppose \( z \in \mathcal{L} \) and we want to show that \( w \in \hat{X} \) lies in the closure of \( \mathcal{L} \). For all \( n \geq 0 \) sufficiently large, the points \( z_{-n} \) and \( w_{-n} \) lie in the annulus \( A(0; \rho, 1) \). Connect \( z_{-n} \) and \( w_{-n} \) by a curve \( \gamma \) that lies in \( A(0; \rho, 1) \). Following the inverse orbit \( z \) along the curve \( \gamma \), we come to a point \( z'_{-n} = w_{-n} \). From the definition of \( d_{\hat{X}} \), it is clear that as \( n \to \infty \), these inverse orbits converge to \( w \). \( \square \)

5.2 Finding a dense horocycle

Pick a repelling fixed point \( \xi \) on the unit circle. Let \( r = F'(\xi) \) be its multiplier; it is real and positive. The leaf \( \mathcal{L}_\xi \) which consists of all backwards orbits that
tend to $\xi$ is conformally equivalent to $\mathbb{H}/(\cdot r)$. Let $z \in \mathcal{L}_\xi$ be a point in this leaf and consider the horocycle $H(z) = \{h_s(z) : s \in \mathbb{R}\}$ passing through $z$. The horocycle is just a horizontal line in $\mathcal{L}_\xi \cong \mathbb{H}/(\cdot r)$. Lifting to the upper half-plane $\mathbb{H}$, we get countably many horizontal lines.

**Lemma 5.2.** The horocycle $H(z)$ is dense in the leaf $\mathcal{L}_\xi$ and hence dense in the lamination $\hat{\mathcal{X}}$.

We may view $\text{Im} H(z)$ as a number in $\mathbb{R}^+/(\cdot r)$. Glutsyuk’s idea was to modify the backward orbit $z \in L_\xi$ to obtain a new orbit $w \in \mathcal{L}_\xi$ with $d_\xi(z, w)$ small, so that $\text{Im} H(w)$ is close to any given number in $\mathbb{R}^+/(\cdot r)$.

By a $\xi$-homoclinic orbit $x \in \hat{S}^1$, we mean an inverse orbit

$$\cdots \rightarrow x_{-3} \rightarrow x_{-2} \rightarrow x_{-1} \rightarrow x_0, \quad x_{-n} \in S^1,$$

on the unit circle so that

$$x_0 = \xi, \quad \lim_{n \to \infty} x_{-n} = \xi.$$ 

We can view the “multiplier”

$$m(x) = \lim_{n \to \infty} \frac{(F^n)'(x_{-n})}{r^n}$$

as an element of $\mathbb{R}^+/(\cdot r)$.

**Lemma 5.3.** The multipliers of $\xi$-homoclinic orbits are dense in $\mathbb{R}^+/(\cdot r)$.

**Proof.** As explained in [IU23], if $F \in \Lambda$ is a centered one component inner function of finite Lyapunov exponent, which is not $z \to z^d$ for some $d \geq 2$, then the multipliers of repelling periodic orbits on the unit circle span a dense subgroup of $\mathbb{R}^+$.

For simplicity of exposition, assume that there is a single repelling periodic orbit $F^{ok}(\eta) = \eta$ on the unit circle such that $(F^{ok})'(\eta)$ and $r$ span a dense subgroup of $\mathbb{R}^+$. As the inverse iterates of a point are dense on the unit circle [IU23, Lemma 3.4], for any $\varepsilon > 0$, one can find a $\xi$-homoclinic orbit $x$ which passes within $\varepsilon$ of $\eta$:

$$\cdots \rightarrow x_{-3} \rightarrow x_{-2} \rightarrow x_{-1} \rightarrow x_0, \quad |x_{-n} - \eta| < \varepsilon.$$
We can form a new ξ-homoclinic orbit $x^{(p)}$ which starts with

$$x_{-n} \rightarrow \cdots \rightarrow x_{-3} \rightarrow x_{-2} \rightarrow x_{-1} \rightarrow x_0,$$

then follows the periodic orbit $F^{pk}(\eta) = \eta$ for $pk$ steps, where $p \geq 1$ is a positive integer, and then follows the tail of $x$:

$$\cdots \rightarrow x_{-n-3} \rightarrow x_{-n-2} \rightarrow x_{-n-1} \rightarrow x_{-n} \rightarrow \cdots.$$ 

Above, “to follow an inverse orbit” means to use the same branches of $F^{-1}$ defined on balls $B(\zeta, 1-\rho)$, centered on the unit circle. By construction, for any given $p \geq 1$, we can make $m(x^{(p)})$ as close to $(F^{pk})'(\eta)\cdot m(x)$ as we want by requesting $\varepsilon > 0$ to be small. By the assumption on the multiplier of $\eta$, the numbers $(F^{pk})'(\eta)^p \cdot m(x)$ are dense in $\mathbb{R}^+/(\cdot \cdot r)$.

**Proof of Lemma 5.2** Let $z \in L_\xi$ be a backward orbit in the unit disk. We can form a new backward orbit $w$ by keeping

$$z_{-n+1} \rightarrow \cdots \rightarrow z_{-3} \rightarrow z_{-2} \rightarrow z_{-1} \rightarrow z_0$$

and approximating

$$\cdots \rightarrow z_{-n-3} \rightarrow z_{-n-2} \rightarrow z_{-n-1} \rightarrow z_{-n}$$

with a ξ-homoclinic orbit

$$\cdots \rightarrow x_{-3} \rightarrow x_{-2} \rightarrow x_{-1} \rightarrow x_0.$$ 

In other words, for $m \geq 0$, we replace $z_{-n-m}$ with a point close to $x_{-m}$. By choosing $n \geq 0$ sufficiently large and the ξ-homoclinic orbit appropriately, this construction produces inverse orbits $w \in L_\xi$ as close to $z \in L_\xi$ as we want with $\text{Im} H(w)$ prescribed to arbitrarily high accuracy in $\mathbb{R}^+/(\cdot \cdot r)$.

**5.3 Ergodicity of the horocyclic flow**

**Lemma 5.4.** Suppose $F \in \Lambda$ is a centered one component inner function of finite Lyapunov exponent, other than $F(z) \neq z^d$ with $d \geq 2$. The horocyclic flow $h_s$ on the Riemann surface lamination $\hat{X}$ is ergodic.
Following Coudène, for \( t > 0 \), we define the operators

\[
\mathcal{M}_t f(z) = \int_0^1 f(g_{-\log t}(h_s(z))) ds \tag{5.1}
\]

on the space of uniformly continuous functions \( UC(\hat{X}) \). Let

\[
S_t f(z) = \int_0^t f(h_s(z)) ds
\]

denote the integral along the trajectory of the horocyclic flow up to time \( t \). The motivation for the operators (5.1) is the relation

\[
\frac{S_t f(z)}{t} = \mathcal{M}_t f(g_{\log t}(z)),
\]

which follows from (3.4) and a change of variables.

**Lemma 5.5.** Suppose \( F \in \Lambda \) is a centered one component inner function of finite Lyapunov exponent, other than \( F(z) \neq z^d \) with \( d \geq 2 \). If \( f \) is a bounded uniformly continuous function on \( \hat{X} \), then the functions \( \{\mathcal{M}_t f\}_{t \geq 0} \), defined on \( \hat{X} \), form a uniformly equicontinuous family.

**Sketch of proof.** The point is that if we do not change the point \( z \) much, we also do not change the horocycle of length \( t \) from the point \( g_{-\log t}(z) \) much. While the length of the horocycle is increasing (we are running it for time \( t \)), we are also starting it from the point \( g_{-\log t}(z) \). Koebe’s distortion theorem implies that the horocycles of length \( t \) started at points \( g_{-\log t}(w) \), with \( d_{\hat{X}}(z, w) < \varepsilon \), are within \( O(\varepsilon) \) of one another. \( \square \)

**Proof of Lemma 5.4.** In view of Lemma 5.5, the Arzela-Ascoli theorem tells us that any sequence of functions \( \mathcal{M}_{tk} f \) with \( tk \rightarrow \infty \) contains a subsequence that converges uniformly on compact subsets of \( \hat{X} \) to a function in \( UC(\hat{X}) \). Our goal is to show that for a positive function \( f \in UC(\hat{X}) \), any accumulation point \( \mathcal{J} \) of \( \mathcal{M}_t f \) as \( t \rightarrow \infty \) is a constant function \( c = c(f) \), which would necessarily be \( c f d\xi \). Once we have done this, the rest is easy: as the functions \( \mathcal{M}_t f \) converge uniformly on compact subsets of \( \hat{X} \) to \( c \) as \( t \rightarrow \infty \), they also converge to \( c \) in \( L^2(\hat{X}, d\xi) \). Here we are using that the metric space \( \hat{X} \) is Polish, which implies that the measure \( \xi \) is inner regular on open sets and so there exists
an increasing sequence of compact sets $K_n \subset \hat{X}$ such that $\xi(K_n) \to \xi(\hat{X})$. Consequently, $S_t(f)/t \to c$ in $L^2(\hat{X}, d\xi)$ and the flow $h_s$ is ergodic.

Let $\{t_k\}$ be a sequence of times tending to infinity for which $\mathcal{M}_{t_k}f$ converges uniformly on compact subsets to an accumulation point $\tilde{f} \in UC(\hat{X})$. Using the invariance of the measure $\xi$ under geodesic flow, we see that

$$\lim_{k \to \infty} \|(1/t_k)S_{t_k}(f) - \tilde{f} \circ g_{\log t_k}\|_{L^2(\hat{X}, d\xi)} = 0.$$  

According to von Neumann's ergodic theorem, there is an $h_s$-invariant $L^2$ function $Pf$ on $\hat{X}$ such that

$$\lim_{t \to \infty} \|(1/t)S_t(f) - Pf\|_{L^2(\hat{X}, d\xi)} = 0.$$  

From these two observations and the $g_t$-invariance of $\xi$, we get:

$$\|\tilde{f} - Pf \circ g_{-\log t_k}\|_{L^2(\hat{X}, d\xi)} = \|\tilde{f} \circ g_{\log t_k} - Pf\|_{L^2(\hat{X}, d\xi)} \to 0, \; \text{as} \; k \to \infty.$$  

The commutativity property of the geodesic and horocyclic flows (3.4) shows that $Pf \circ g_{-\log t_k}$ is invariant under the horocyclic flow $h_s$. Therefore, $\tilde{f}$ must also be invariant under $h_s$. As $\tilde{f}$ is a continuous function with a dense $h_s$-orbit, it must be constant. The proof is complete. \hfill $\square$

### 5.4 Mixing of the geodesic flow

We now deduce the mixing of the geodesic flow from the ergodicity of the horocyclic flow:

**Lemma 5.6.** If $F \in \Lambda$ is a centered one component inner function of finite Lyapunov exponent, other than $F(z) \neq z^d$ with $d \geq 2$, then the geodesic flow $g_{-t}$ on the Riemann surface lamination $\hat{X}$ with respect to the measure $\xi$ is mixing.

**Proof.** For $t \in \mathbb{R}$, the Koopman operator $[g_{-t}]u = u \circ g_{-t}$ acts isometrically on $L^2(\hat{X})$. For $r > 0$, let $S_r(u)$ be the average of $u \circ h_s$ over $s \in [-r, r]$, i.e.

$$S_r(u)(x) = \frac{1}{2r} \int_{-r}^r u(h_s(x))ds.$$  

26
This defines a bounded linear operator $S_r : L^2(\hat{X}) \to L^2(\hat{X})$. The commutation relation (3.4) tells us that

$$S_r[g_{-t}] = [g_{-t}]S_{e^{r}}$$

as operators on $L^2(\hat{X})$.

Let $u, v \in C_b(\hat{X})$ be two bounded continuous functions of zero mean with respect to the measure $\xi$. Since $\xi$ is invariant with respect to both the horocyclic flow $h_s$ and the geodesic flow $g_{-t}$, by using Fubini’s Theorem, we get for every $r > 0$ and $t \in \mathbb{R}$ that

$$\langle S_r u, [g_{-t}]v \rangle = \langle u, S_r[g_{-t}]v \rangle = \langle u, [g_{-t}]S_{e^{r}}v \rangle = \langle [g_t]u, S_{e^{r}}v \rangle.$$ (5.3)

As $\int_{\hat{X}} v d\xi = 0$, it follows from the ergodicity of the horocyclic flow and von Neumann’s Ergodic Theorem that $S_{e^{r}}v \to 0$ in $L^2(\hat{X})$ as $t \to +\infty$. Since the set $\{[g_t]u : t \in \mathbb{R}\}$ is bounded in $L^2(\hat{X})$, (5.3) tells us that

$$\lim_{t \to +\infty} \langle S_r u, [g_{-t}]v \rangle = 0,$$

for any $r > 0$. As

$$\lim_{r \to 0} \|u - S_r u\|_{L^2(\hat{X})} = 0,$$

we also have

$$\lim_{t \to +\infty} \langle u, [g_{-t}]v \rangle = 0.$$

The result now follows from the density of $C^b(\hat{X})$ in $L^2(\hat{X})$. 

\begin{proof}

\end{proof}

\textbf{Part II}

\textbf{Background in Geometry and Analysis}

In this part of the manuscript, we gather some facts from differential geometry and complex analysis that will allow us to study the dynamics of inner functions with finite Lyapunov exponent.
In Section II we see use (hyperbolic) geodesic curvature to estimate how much a curve in the unit disk deviates from a radial ray \([0, \zeta]\). In Section 7 we define the M"obius distortion of a holomorphic self-map \(F\) of the unit disk and use it to estimate the curvature of \(F([0, \zeta])\).

In Section 8 we give another interpretation of the M"obius distortion in terms of how much \(F^{-1}\) expands the hyperbolic metric and define the linear distortion of \(F\). Finally, in Section 9 we give a bound on the total linear distortion of \(F\) along \([0, \zeta]\) in terms of the angular derivative \(|F'(\zeta)|\), from which we conclude that if \(F\) is an inner function with finite Lyapunov exponent then the total linear distortion of \(F\) on the unit disk is finite.

6 Curves in Hyperbolic Space

We first recall the definition and basic properties of geodesic curvature in the Euclidean setting. Suppose \(\gamma: [a, b] \to \mathbb{R}^2\) is a \(C^2\) curve, parameterized with respect to arclength. Its curvature \(\kappa_{\text{Euc}}(\gamma; t) = \|\gamma''(t)\|\) measures the rate of change of the tangent vector of \(\gamma\). The signed curvature \(\kappa_{\text{s, Euc}}(\gamma; t) = \pm \kappa_{\text{Euc}}(\gamma; t)\) also takes into account if \(\gamma\) is turning left or right. It is well known that a curve is uniquely determined (up to an isometry) by its signed curvature, e.g. see [Pre10, Theorem 2.1].

Example. A circle of radius \(R\) has constant curvature \(1/R\). The signed curvature is either \(-1/R\) or \(1/R\) depending on the orientation of \(\gamma\).

We now turn our attention to the hyperbolic setting. Let \(\gamma: [a, b] \to \mathbb{D}\) be a \(C^2\) curve, parametrized with respect to hyperbolic arclength. The hyperbolic geodesic curvature \(\kappa_{\text{hyp}}(\gamma; t)\) measures how much \(\gamma\) deviates from a hyperbolic geodesic at \(\gamma(t)\).

We now describe a convenient way to compute \(\kappa_{\text{hyp}}(\gamma; t)\). Suppose first \(\gamma\) passes through the origin, e.g. \(\gamma(t_0) = 0\) for some \(t_0 \in [a, b]\). As the hyperbolic metric osculates the Euclidean metric to order 2 at the origin, but is twice as large there, the hyperbolic geodesic curvature of \(\gamma\) is half the Euclidean geodesic curvature of \(\gamma\). One may compute the hyperbolic geodesic curvature at other points by means of \(\text{Aut}(\mathbb{H})\) invariance.
Example. (i) Hyperbolic geodesics have zero geodesic curvature.

(ii) To compute the curvature of a horocycle, we may assume that the horocycle passes through the origin and compute its curvature there. Since a horocycle which passes through the origin is a circle of Euclidean radius $1/2$, its Euclidean geodesic curvature at the origin is 2. Consequently, every horocycle has constant hyperbolic geodesic curvature 1.

(iii) Curves of constant hyperbolic geodesic curvature $\kappa \in (0, 1)$ are circular arcs which cut the unit circle at two points at an angle $\theta \in (0, \pi/2)$ with $\kappa = \cos \theta$.

The following two lemmas are well-known:

**Lemma 6.1.** If $\gamma : [a, b] \to \mathbb{D}$ is a $C^2$ curve with hyperbolic geodesic curvature $\kappa_{\text{hyp}}(\gamma; t) \leq 1$, then $\gamma$ is a simple curve.

**Lemma 6.2.** If $\gamma : [a, b] \to \mathbb{D}$ is a $C^2$ curve with hyperbolic geodesic curvature $\kappa_{\text{hyp}}(\gamma; t) \leq c < 1$, then $\gamma$ lies within a bounded hyperbolic distance of some geodesic.

We also record the following comparison theorem:

**Theorem 6.3.** Suppose $\gamma : [a, \infty) \to \mathbb{D}$ is a $C^2$ curve with hyperbolic geodesic curvature $\kappa_{\text{hyp}}(\gamma; t) \leq \kappa \leq 1$. Let $\gamma_1, \gamma_2 : [a, \infty) \to \mathbb{D}$ be curves with constant signed geodesic curvatures $\kappa$ and $-\kappa$ respectively that have the same tangent vector at $t = a$, i.e.

$$\gamma_1(a) = \gamma_2(a) = \gamma(a), \quad \gamma'_1(a) = \gamma'_2(a) = \gamma'(a).$$

Then, $\gamma$ lies between $\gamma_1$ and $\gamma_2$.

### 6.1 Inclination from the Vertical Line

We now switch to the upper half-plane model of hyperbolic geometry. In this section, we assume that $\gamma : [a, \infty) \to \mathbb{H}$ is a $C^2$ curve of curvature $\kappa \leq 0.2$, parametrized with respect to arclength. For any $a \leq t < \infty$, we can look at the tangent vector $\gamma'(t)$ to $\gamma$ at the point $\gamma(t)$. We define $\alpha(t) \in [0, \pi]$ to be the angle that $\gamma'(t)$ makes with the downward pointing vector field $v_\perp = -y \cdot \frac{\partial}{\partial y}$.
We first describe the behaviour of \( \alpha(t) \) when \( \gamma \) is a hyperbolic geodesic in the upper half-plane. Inspection shows that the derivative \( \alpha'(t) \leq 0 \), where equality holds if and only if \( \gamma \) is a vertical line, pointing straight up or straight down. If \( \gamma \) is not a vertical line, then \( \alpha(t) \) satisfies the differential equation

\[
\alpha'(t) = -G(\alpha(t)),
\]

for some non-negative differentiable function \( G : [0, \pi] \to \mathbb{R} \), which vanishes only at the endpoints. (The function \( G \) does not depend on the geodesic \( \gamma \) since any two non-vertical geodesics in the upper half-plane are related by a mapping of the form \( z \to Az + B \) with \( A > 0 \) and \( B \in \mathbb{R} \).) For future reference, we note that \( G'(0) > 0 \).

**Lemma 6.4.** Suppose \( \gamma : [a, b] \to \mathbb{H} \) is a piece of a hyperbolic geodesic. If \( \alpha(a) \leq 2\pi/3 \), then

\[
\int_a^b \alpha(t) \lesssim \alpha(a),
\]

(6.1)

where the implicit constant is independent of \( b \).

**Proof.** From the discussion above, it follows that \( \alpha(t) \) satisfies the differential inequality

\[
\alpha'(t) \leq -c_1 \alpha(t), \quad t \in [a, \infty),
\]

for some \( c_1 > 0 \). In view of Grönwall’s inequality, \( \alpha(t) \) decreases exponentially quickly, which clearly implies \( \square \).
Lemma 6.5. If \( \gamma : [a, \infty) \to \mathbb{H} \) is a \( C^2 \) curve parametrized with respect to hyperbolic arclength with curvature \( \kappa \leq 0.2 \). If \( \alpha(a) < 2\pi/3 \), then
\[
\alpha(t) \leq 2\pi/3
\]
for all \( t \in [a, \infty) \).

Sketch of proof. From the discussion above, a straight line in the upper half-plane with \( \alpha(t) = 2\pi/3 \) has constant curvature \( \kappa = \sqrt{3/2} > 0.2 \). By Theorem 6.3, if \( \alpha(t) = 2\pi/3 \) then \( \alpha'(t) \leq 0 \). Consequently, \( \alpha(t) \) cannot rise above \( 2\pi/3 \).

Lemma 6.6. If \( \gamma \subset \mathbb{H} \) is a \( C^2 \) curve parametrized with respect to hyperbolic arclength, with curvature \( \leq 0.2 \), then
\[
\alpha'(t) \leq -G(\alpha(t)) + 4 \kappa_{\text{hyp}}(\gamma; t).
\]

Sketch of proof. We have seen that at the origin, the hyperbolic metric is twice as large as the Euclidean metric. As a result, the parametrization with respect to the hyperbolic arclength is twice as fast as with Euclidean arclength. In addition, the Euclidean geodesic curvature is twice as large as the hyperbolic geodesic curvature. Consequently, the intrinsic change in the direction of the tangent vector \( \gamma'(t) \) is four times the signed hyperbolic geodesic curvature.

However, in hyperbolic geometry, we must also account for the fact that geodesics naturally change direction with respect to the vertical, which is described by the first term in the equation above.

To conclude this section, we extend Lemma 6.4 to the case of small geodesic curvature:

Lemma 6.7. Suppose \( \gamma : [a, b] \to \mathbb{H} \) has geodesic curvature at most 0.2. If \( \alpha(a) \leq 2\pi/3 \), then
\[
\int_a^b \alpha(t) \lesssim \alpha(a) + \int_a^b \kappa_{\text{hyp}}(\gamma; t).
\]

Proof. From the lemma above, it follows that
\[
\alpha'(t) \leq -c_1 \alpha(t) + 4 \kappa_{\text{hyp}}(\gamma; t), \quad (6.2)
\]
for some $c_1 > 0$. Grönwall’s inequality shows that
\[ \alpha(t) \leq e^{-c_1 t} \left( \alpha(a) + 4 \int_a^t e^{c_1 s} \cdot \kappa_{\text{hyp}}(\gamma; s) \, ds \right), \]
for all $t \in [a, b]$. Integrating over $t$ proves the result.

\section{Möbius Distortion}

Let $\lambda_{\mathbb{D}} = \frac{2}{1-|z|^2}$ be the hyperbolic metric on the unit disk. A holomorphic self-map $F$ of the unit disk naturally defines the pullback metric
\[ \lambda_F = F^* \lambda_{\mathbb{D}} = \frac{2|F'(z)|}{1 - |F(z)|^2}. \]
With the above definition, if $\gamma \subset \mathbb{D}$ is a rectifiable curve, then the hyperbolic length of $F(\gamma)$ is $\int_\gamma \lambda_F$.

By the Schwarz lemma, $\mu(z) := 1 - (\lambda_F / \lambda_{\mathbb{D}})(z)$ is zero if and only if $F$ is a Möbius transformation. In general, the \textit{Möbius distortion} $\mu(a)$ measures how much $F$ deviates from being a Möbius transformation near $a$. A normal families argument shows that when $\mu(a)$ is small, then $F$ is close to a Möbius transformation $m \in \text{Aut}(\mathbb{D})$ near $a$. The following lemma provides a more quantitative estimate:

\textbf{Lemma 7.1.} Let $F$ be a holomorphic self-map of the unit disk. For any $R, \varepsilon > 0$, there exists a $\delta > 0$, so that if $\mu(a) < \delta$ then $F$ is univalent and $d_{\mathbb{D}}(F(z), m(z)) < \varepsilon$ on $B_{\text{hyp}}(a, R)$, for some Möbius transformation $m \in \text{Aut}(\mathbb{D})$ which takes $a$ to $F(a)$. Furthermore, for a fixed $R > 0$, $\delta$ can be taken to be comparable to $\varepsilon$.

The argument below is taken from [McM09, Proposition 10.9]:

\textbf{Proof.} By Möbius invariance, we may assume that $a = F(a) = 0$ and $0 \leq F'(0) \leq 1$. For convenience, we abbreviate $\mu = \mu(0) = 1 - F'(0)$. Applying the Schwarz lemma to $F(z)/z$ shows that the hyperbolic distance
\[ d_{\mathbb{D}}(F(z)/z, F'(0)) = O(1), \quad \text{for } z \in B_{\text{hyp}}(0, R + 1). \]
Taking note of the location of $F'(0) \in \mathbb{D}$, this implies that $|F(z) - z| = O(\mu)$ on $B_{\text{hyp}}(0, R + 1)$. Cauchy’s integral formula then tells us that $|F'(z) - 1| = O(\mu)$, $|F''(z)| = O(\mu)$, for $z \in B_{\text{hyp}}(0, R)$.

From here, the lemma follows from the definition of the Möbius distortion and some arithmetic. \hfill \square

**Lemma 7.2.** Suppose $\gamma$ is a hyperbolic geodesic in the unit disk passing through $z \in \mathbb{D}$. Let $F(\gamma)$ be the image of $\gamma$ under a holomorphic self-map $F$ of the unit disk. The geodesic curvature of $F(\gamma)$ at $F(z)$ is bounded by

$$\min(1, \kappa_{F(\gamma)}(F(z))) \lesssim \mu(z).$$

**Proof.** By Möbius invariance, one can consider the case when $\gamma = [-1, 1]$, $z = 0$, $F(0) = 0$ and $F'(0) > 0$. Arguing as in the proof of Lemma 7.1, we get $|F''(0)| = O(\mu)$ where $\mu = 1 - F'(0)$. Therefore, $F(\gamma)$ lies in a wedge

$$\{ x + iy : |y| < C\mu x^2 \}$$

near $z = 0$, which gives the desired curvature bound. \hfill \square

The same argument shows:

**Lemma 7.3** (Stability of $\mu$ under perturbations). There exists a constant $K > 0$ so that any holomorphic self-map $F$ of the unit disk,

$$|\nabla_{\text{hyp}} \mu(a)| \leq K \mu(a), \quad a \in \mathbb{D}.$$ 

In particular, for any two points $a, b \in \mathbb{D}$, we have

$$e^{-Kd_\mathbb{D}(a,b)} \mu(a) \leq \mu(b) \leq e^{Kd_\mathbb{D}(a,b)} \mu(a).$$

For the sharp exponent, we refer the reader to [BM07, Corollary 5.7].

**Hyperbolic expansion factor.** Suppose $F$ is a holomorphic self-map of the unit disk. By the Schwarz lemma, the hyperbolic expansion factor $E(a) := \|F'(a)\|_{\text{hyp}}^{-1} \geq 1$. The hyperbolic expansion factor could be infinite if $a$ is a critical point of $F$. The hyperbolic expansion factor is related to the Möbius distortion via

$$E(a) = \frac{1}{1 - \mu(a)}.$$ 

As a result, the two quantities are essentially interchangeable.
8 Linear Distortion

Recall that the downward pointing vector field \( v_\downarrow = -y \cdot \frac{\partial}{\partial y} \) assigns each point in \( \mathbb{H} \) a vector of hyperbolic length 1 which points toward the real axis. By the Schwarz lemma, the quotient
\[
p(z) = \frac{F_* v_\downarrow(z)}{v_\downarrow(F(z))} \in \mathbb{D}.
\]

We consider the following quantities:
- Möbius distortion: \( \mu = 1 - |p| \).
- Linear distortion: \( \delta = |1 - p| \).
- Vertical inefficiency: \( \eta = \text{Re}(1 - p) \).
- Vertical inclination: \( \alpha = |\text{arg} p| \in [0, \pi) \).

![Figure 1: Notions of distortion](image)

In practice, estimating \( \delta(a) \) directly is rather difficult. From the picture above, it is clear that \( \alpha(a) + \eta(a) \geq \delta(a) \), which allows us to estimate linear distortion by estimating the vertical inefficiency and vertical inclination separately.

For a holomorphic self-map of the upper half-plane \( F \), the linear distortion \( \delta_F(a) \) measures how much \( F \) deviates from the unique linear map \( L_{a \to F(a)} \in \text{Aut}(\mathbb{H}, \infty) \) which takes \( a \) to \( F(a) \). Evidently, the linear distortion is zero if and only if \( F = L_{a \to F(a)} \). Similar to Lemma 7.1, we have:
Lemma 8.1. Let $F$ be a holomorphic self-map of the upper half-plane. For any $R, \varepsilon > 0$, there exists a $\delta > 0$, so that if $\delta_F(a) < \delta$ then $F$ is univalent and $d_{\mathbb{H}}(F(z), L_{a \rightarrow F(a)}(z)) < \varepsilon$ on $B_{\text{hyp}}(a, R)$, for some linear mapping $L_{a \rightarrow F(a)} \in \text{Aut}(\mathbb{H}, \infty)$. Furthermore, for a fixed $R > 0$, $\delta$ can be taken to be comparable to $\varepsilon$.

Proof. By $\text{Aut}(\mathbb{H}, \infty)$ invariance, we may assume that $a = F(a) = i$. In view of Lemma 7.1, $F$ is injective on the ball $B_{\text{hyp}}(a, R)$, where it resembles an elliptic Möbius transformation in $\text{Aut}(\mathbb{H})$ which fixes $i$. We need to show that $F$ is close to the identity mapping. Let $m_{\mathbb{D} \rightarrow \mathbb{H}}$ be a Möbius transformation which maps $\mathbb{D}$ to $\mathbb{H}$ and takes the tangent vector $(\partial/\partial x)(0)$ to $v_1(i)$. As $\delta_F(i) < \delta$, the composition $G = m_{\mathbb{D} \rightarrow \mathbb{H}} \circ F \circ m_{\mathbb{D} \rightarrow \mathbb{H}}$ defines a holomorphic self-map of the unit disk with $G(0) = 0$ and $|G'(0) - 1| = O(\delta(i))$. Following the proof of Lemma 7.1, we see that $|G(z) - z| = O(\delta(i))$ for $z \in B_{\text{hyp}}(0, R)$, which in the upper half-plane translates to

$$|F(w) - w| = O(\delta(i)), \quad \text{for } w \in B_{\text{hyp}}(i, R),$$

as desired. \hfill \Box

Lemma 8.2 (Stability of $\delta$ under perturbations). There exists a constant $K > 0$ such that any holomorphic self-map $F$ of the upper half-plane, we have

$$|\nabla_{\text{hyp}} \delta(a)| \leq K \delta(a), \quad a \in \mathbb{H}.$$

In particular, for any two points $a, b \in \mathbb{H}$, we have

$$e^{-Kd_{\mathbb{D}}(a, b)} \delta(a) \leq \delta(b) \leq e^{Kd_{\mathbb{D}}(a, b)} \delta(a).$$

Proof. Since we have already estimated $|\nabla_{\text{hyp}} \mu(a)|$ in Lemma 7.3, it remains to control the gradient of the angular inclination $|\nabla_{\text{hyp}} \alpha(a)|$. By $\text{Aut}(\mathbb{H}, \infty)$ invariance, we may assume that $a = F(a) = i$. We may also assume that $\delta(i) < 1/2$, otherwise the lemma is trivial, in which case, $|F'(i)| \asymp 1$ and the gradient $|\nabla \alpha(i)| = |\nabla \arg F'(i)|$ is controlled by the second derivative $|F''(i)|$.

As in the proof of Lemma 8.1, we have $|F(w) - w| = O(\delta(i))$ for $w \in B_{\text{hyp}}(i, 1)$. An application of Cauchy’s integral formula gives the desired estimate $|F''(i)| = O(\delta(i))$. \hfill \Box
Working in the unit disk. For a centered holomorphic self-map $F$ of the unit disk, one can define the notions of $\delta, \eta, \alpha$ using the radial vector field $v_{\text{rad}}(z) = \frac{2}{1-\tau^2} \cdot \frac{\partial}{\partial r}$, which assigns each point in $\mathbb{D} \setminus \{0\}$ an outward pointing vector of hyperbolic length 1. Note that $\delta, \eta, \alpha$ are only defined when $a, F(a) \neq 0$ and as a result are somewhat awkward to work with. Nevertheless, near the unit circle, $\delta, \eta, \alpha$ resemble their counterparts in the upper half-plane.

Assuming that $a, F(a) \neq 0$, the radial distortion $\delta_F(a)$ measures how much $F$ deviates from $m_{a \to F(a)}$ near $a$, the “straight” M"{o}bius transformation which takes $a \to F(a)$ and $\frac{a}{|a|} \to \frac{F(a)}{|F(a)|}$ on $B_{\text{hyp}}(a, R)$, we will often ask that $1 - |F(a)| < \delta/e^R$ in addition to $\delta(a) < \delta$.

9 Distortion Along Radial Rays

Suppose $F$ is a holomorphic self-map of the unit disk. Recall that $F$ has an angular derivative at $\zeta \in \partial \mathbb{D}$ in the sense of Carathéodory if $F(\zeta) := \lim_{r \to 1} F(r\zeta)$ belongs to the unit circle and $F'(\zeta) := \lim_{r \to 1} F'(r\zeta)$ is finite. The following theorem says that the logarithm of the angular derivative at $\zeta$ controls the total linear distortion along the radial geodesic $[0, \zeta]$:

**Theorem 9.1.** Suppose $F$ is a holomorphic self-map of the disk with $F(0) = 0$. If $F$ has an angular derivative at $\zeta \in \partial \mathbb{D}$, then

$$\int_0^\zeta \delta \, d\rho \lesssim \log |F'(|\zeta|).$$

(9.1)

In particular, if $F$ is an inner function with finite Lyapunov exponent,

$$\int_{\mathbb{D}} \delta(z) \cdot \frac{dA(z)}{1 - |z|} \lesssim \int_{\partial \mathbb{D}} \log |F'(re^{i\theta})| \, dm.$$

(9.2)

In view of the inequality $\alpha(z) + \eta(z) \geq \delta(z)$, we may split the proof Theorem 9.1 into two lemmas:
Lemma 9.2. Suppose $F$ is a holomorphic self-map of the disk with $F(0) = 0$. If $F$ has an angular derivative at $\zeta \in \partial \mathbb{D}$, then
\[
\int_0^\zeta \eta \, d\rho \leq \log |F'(\zeta)|.
\] (9.3)

Lemma 9.3. Suppose $F$ is a holomorphic self-map of the disk with $F(0) = 0$. If $F$ has an angular derivative at $\zeta \in \partial \mathbb{D}$, then
\[
\int_0^\zeta \alpha \, d\rho \lesssim \log |F'(\zeta)|.
\] (9.4)

9.1 Bounding the radial inefficiency

We first estimate the radial inefficiency:

Proof of Lemma 9.2. Let $\zeta$ be a point on the unit circle where $F$ has an angular derivative. Join the points 0 and $\zeta$ by a hyperbolic geodesic $\gamma = [0, \zeta]$. The image $F(\gamma)$ is a curve which connects 0 to $F(\zeta) \in \partial \mathbb{D}$. From the definition of the radial inefficiency, it is clear that
\[
\int_0^\zeta \eta \, d\rho \leq \lim_{r \to 1} \left\{ d_\mathbb{D}(0, r\zeta) - d_\mathbb{D}(0, F(r\zeta)) \right\} = \log |F'(\zeta)|,
\] as desired.

In view of the elementary estimate $\mu \leq \eta$ and Lemma 7.2, the total Möbius distortion and geodesic curvature are finite along $F([0, \zeta])$:

Corollary 9.4. Suppose $F$ is a holomorphic self-map of the disk with $F(0) = 0$. If $F$ has an angular derivative at $\zeta \in \partial \mathbb{D}$, then
\[
\int_0^\zeta \mu \, d\rho \leq \log |F'(\zeta)|.
\] and
\[
\int_0^\zeta \min(1, \kappa_{F([0, \zeta])}(F(z))) \, d\rho(z) \lesssim \log |F'(\zeta)|.
\]

Below, we will use the following lemma which follows from compactness:

Lemma 9.5. There exists a $\delta > 0$ so that for any holomorphic self-map $F$ of the unit disk and point $z \in \mathbb{D}$ with $d_\mathbb{D}(0, z) \geq 1$,
\[
\eta(z) < 0.1 \quad \Rightarrow \quad \eta(w) < 0.15, \quad w \in B_{\mathbb{H}}(z, \delta).
\]
9.2 Bounding the radial inclination

To complete the proof of Theorem 9.1 it remains to estimate the radial inclination. We parametrize the radial geodesic $\gamma(t) = [0, \zeta)$ with respect to arclength. We break up $(\gamma(1), \gamma(\infty))$ into a union of thick and thin intervals. By a thin interval $(\gamma(p_i), \gamma(q_i)) \subset (\gamma(1), \gamma(\infty))$, we mean a maximal interval for which $\eta(\gamma(p_i)) < 0.1$ and $\eta(\gamma(q_i)) < 0.2$. The thick intervals are then defined as the connected components of the complement of the thin intervals.

In view of Lemma 9.5, the hyperbolic length of a thin interval is bounded from below. Therefore, by Lemma 9.2, the number of thin intervals $n(\zeta) \lesssim \log |F'(\zeta)|$. As thin and thick intervals alternate, the number of thick intervals is also $\lesssim \log |F'(\zeta)|$.

Proof of Lemma 9.3 Since $\eta(t) \geq 0.1$ on any thick interval, by Lemma 9.2 the sum of the hyperbolic lengths of the thick intervals is $\lesssim \log |F'(\zeta)|$, so that

$$\sum_{\gamma_i \text{thick}} \int_{\gamma_i} \alpha \, d\rho \lesssim \log |F'(\zeta)|.$$

From the definitions of the radial inclination and the radial inefficiency, it follows that on a thin interval $\alpha(t) \leq |\arg(0.8 + 0.2i)| \approx 0.644 < 2\pi/3$, so that Lemma 6.7 is applicable (see the remark below). Together with Corollary 9.4 this shows

$$\sum_{\gamma_i \text{thin}} \int_{\gamma_i} \alpha \, d\rho \lesssim n(\zeta) + \sum_{i=1}^{n} \int_{\gamma_i} \kappa \, d\rho \lesssim \log |F'(\zeta)|.$$ 

The proof is complete.

Remark. Actually, one needs to be a bit more precise in the proof above since Lemma 6.7 is stated on the upper half-plane. On the unit disk, one can only apply Lemma 6.7 as long as one is working sufficiently close to the unit circle. As $\eta(z) < 0.2$ on a thin interval, $F(z)$ moves towards the unit circle at a definite rate, so after $O(1)$ time, Lemma 6.7 will indeed be applicable. The waiting time contributes at most $O(1)$ to each integral $\int_{\gamma_i} \alpha \, d\rho$ over a thin interval $\gamma_i$. 

38
Part III
General Centered Inner Functions of Finite Lyapunov Exponent

In this part, $F$ will denote an arbitrary centered inner function of finite Lyapunov exponent, other than a rotation. In Section 10, we define the Möbius and linear laminations $\hat{X}_{\text{mob}}$ and $\hat{X}_{\text{lin}}$ associated to $F$ and describe the geodesic and horocyclic flows on $\hat{X}_{\text{lin}}$. To be fair, the term “lamination” is not entirely accurate here as $\hat{X}_{\text{lin}}$ and $\hat{X}_{\text{mob}}$ may not locally be product sets.

In Section 11, we construct a natural volume form $d\xi$ on $\hat{X}$. According to Theorem 11.2, the total volume of $\hat{X}$ is just the Lyapunov exponent of $F$. From the finiteness of volume, it follows that iteration along almost every backward orbit is asymptotically Möbius, i.e. $\xi(\hat{X} \setminus \hat{X}_{\text{mob}}) = 0$. In Section 12, we improve this to asymptotically linearity, i.e. $\xi(\hat{X} \setminus \hat{X}_{\text{lin}}) = 0$.

In Section 13, we study how the trajectories of the geodesic flow foliate $\hat{D}_{\text{lin}}$ and conclude that the geodesic flow on $\hat{X}_{\text{lin}}$ is ergodic. Finally, in Section 14, we apply the ergodic theorem to a slight modification of the almost invariant function from Section 4.2 to prove Theorem 1.2.

10 Möbius and Linear Laminations

For a general centered inner function, the lamination $\hat{X} = \hat{D} / \hat{F}$ defined in Section 3 has limited use. In this section, we describe two subsets

$$\hat{X}_{\text{mob}} = \hat{D}_{\text{mob}} / \hat{F} \quad \text{and} \quad \hat{X}_{\text{lin}} = \hat{D}_{\text{lin}} / \hat{F},$$

which we refer to as the Möbius and linear laminations of $F$ respectively. Here, $\hat{D}_{\text{mob}} \subset \hat{D}$ is the collection of inverse orbits $z = (z_{-n})_{n=0}^{\infty}$ on which backward iteration is asymptotically Möbius:

$$\mu_{F^{\circ m}}(z_{-m-n}) \to 0, \quad \text{as } m, n \to \infty,$$
while $\hat{X}_{\text{lin}} \subset \hat{D}$ consists of inverse orbits on which backward iteration is asymptotically linear:
\[
\delta_{F^m}(z_{-m-n}) \to 0, \quad \text{as } m, n \to \infty.
\]
(As $\delta_{F^m}(z_{-m-n})$ is small, $F^m$ is close to a straight Möbius transformation near $z_{-m-n}$. Asymptotic linearity follows from the fact that $|z_n| \to 1$.) Since $\mu \leq \delta$, it is clear that $\hat{X}_{\text{lin}} \subset \hat{X}_{\text{mob}} \subset \hat{X}$.

On the set $\hat{X}_{\text{mob}} \subset \hat{X}$, one can define a leafwise hyperbolic Laplacian and study mixing properties of hyperbolic Brownian motion, but we will not pursue this here. On $\hat{X}_{\text{lin}} \subset \hat{X}$, one can define geodesic and horocyclic flows as in Section 3.

10.1 Rescaling along inverse orbits

Inspection shows that a backward orbit $z = (z_{-n})_{n=0}^{\infty} \in \hat{D}$ belongs to $\hat{X}_{\text{mob}}$ if and only if there exists a sequence of Möbius transformations $m_{-N} \in \text{Aut}(D)$, $N \in \mathbb{N}$, with
\[
m_{-N}(0) = z_{-N}
\]
for which the sequence
\[
(F \circ m_{-N})_{N=0}^{\infty}
\]
converges uniformly on compact subsets of the unit disk as $N \to \infty$. In this case, we denote the limiting map by $F_{z,0}$. In fact, when $F_{z,0}$ exists, so does
\[
F_{z,-n} = \lim_{N \to \infty} F^{(N-n)} \circ m_{-N}, \quad \text{for any } n \in \mathbb{N},
\]
and $(F_{z,-n}(w))_{n=0}^{\infty}$ defines an inverse orbit in $\hat{X}_{\text{mob}}$ for any $w \in D$.

We say that a backward orbit $w = (w_{-n})_{n=0}^{\infty}$ lies in the same leaf of $\hat{X}_{\text{mob}}$ as $z = (z_{-n})_{n=0}^{\infty}$ if there is a $w \in D$ such that
\[
w_{-n} = F_{z,-n}(w),
\]
for all integers $n \in \mathbb{N}$.

For a point $p \in D \setminus 0$, we write $M_p$ for the conformal map from $\mathbb{H}$ to $D$ which takes
\[
0 \to \frac{p}{|p|}, \quad i \to p, \quad \infty \to -\frac{p}{|p|}.
\]

40
Similarly, a backward orbit \( z = (z_n)_{n=0}^\infty \in \hat{\mathbb{D}} \) belongs to \( \hat{\mathbb{D}}_{\text{lin}} \) if and only if for some (and hence any) \( n \in \mathbb{N} \), the sequence of rescaled iterates

\[
F^{(N-n)} \circ M_{z-N},
\]

converges uniformly on compact subsets of \( \mathbb{H} \) as \( N \to \infty \). We denote the limiting maps by

\[
F_{z,-n} := \lim_{N \to \infty} F^{(N-n)} \circ M_{z-N}.
\]

We partition \( \hat{\mathbb{D}}_{\text{lin}} \) into a union of leaves analogously to \( \hat{\mathbb{D}}_{\text{mob}} \).

**Lemma 10.1.** Two inverse orbits \( z = (z_n)_{n=0}^\infty \) and \( z' = (z'_n)_{n=0}^\infty \) in \( \hat{\mathbb{D}}_{\text{lin}} \) belong to the same leaf \( L \subset \hat{\mathbb{D}}_{\text{lin}} \) if and only if \( (d_D(z_n, z'_n))_{n=0}^\infty \) is uniformly bounded. In this case, the leafwise hyperbolic distance

\[
d_L(z, z') = \lim_{n \to \infty} d_D(z_n, z'_n).
\]

We define the geodesic and horocyclic flows on \( \hat{\mathbb{D}}_{\text{lin}} \) by the following formulas:

\[
g_t(z)_-n := F_{z,-n}(e^t \cdot i), \quad t \in \mathbb{R}
\]

and

\[
h_s(z)_-n := F_{z,-n}(i + s), \quad s \in \mathbb{R}.
\]

Clearly, the \((-n)\)-th coordinates of geodesic trajectories which foliate the leaf \( \mathcal{L}(z) \subset \hat{\mathbb{D}}_{\text{lin}} \) containing \( z \) are images of vertical geodesics \( \{w \in \mathbb{H} : \text{Re} \, w = x\} \) under \( F_{z,-n} \).

The choices of basepoints \( 0 \in \mathbb{D} \) and \( i \in \mathbb{H} \) in the definitions above are of course arbitrary.

**Remark.** For a general centered inner function, the laminations \( \hat{\mathcal{X}}_{\text{mob}} \) and \( \hat{\mathcal{X}}_{\text{lin}} \) could be empty. For instance, there exists a centered inner function \( F \) whose critical set forms a net, i.e. there exists an \( R > 0 \) so that any point in the unit disk is within hyperbolic distance \( R \) of a critical point. However, in view of Jensen’s formula, \( F \) does not have a finite Lyapunov exponent.
10.2 Cumulative distortion

We now introduce some notions which allow us to check whether an inverse orbit $z$ lies in $\hat{D}_{\text{mob}}$ or $\hat{D}_{\text{lin}}$.

We denote the cumulative hyperbolic expansion factor by

$$E(w, z) = \| (F^n)'(w) \|_{\text{hyp}}^{-1}$$

if $F^n(w) = z$ and

$$E(w) = E(w, z) = \lim_{n \to \infty} \| (F^n)'(w-n) \|_{\text{hyp}}^{-1}$$

if $w = (w_n)_{n=0}^\infty \in \hat{D}$ is an inverse orbit with $w_0 = z$. It is easy to see that $w \in \hat{D}_{\text{mob}}$ if and only if $E(w) < \infty$.

We denote the cumulative linear distortion along an inverse orbit $z \in \hat{D}$ by

$$\hat{\delta}_F(z) := \sum_{n=1}^\infty \delta_F(z - n). \quad (10.1)$$

**Lemma 10.2.** Suppose $F$ and $G$ are holomorphic self-maps of the unit disk. For a point $a \in \mathbb{D}$ such that $a, G(a), F(G(a)) \neq 0$, we have

$$\delta_{F \circ G}(a) \leq \delta_F(G(a)) + \delta_F(a).$$

In particular, if $a, F(a), \ldots, F^{n-1}(a) \neq 0$, then

$$\delta_{F^n}(a) \leq \sum_{k=0}^{n-1} \delta_F(F^k(a)).$$

**Proof.** Notice that if $p, q \in \mathbb{D}$, then

$$|1 - pq| = |1 - p| + |p - pq| \leq |1 - p| + |1 - q|.$$

The lemma follows from the above identity, with

$$p = \frac{G_* v_{\text{rad}}(a)}{v_{\text{rad}}(G(a))} \quad \text{and} \quad q = \frac{F_* v_{\text{rad}}(G(a))}{v_{\text{rad}}(F(G(a)))},$$

as $\delta_G(a) = |1 - p|$, $\delta_F(G(a)) = |1 - q|$ and $\delta_{F \circ G}(a) = |1 - pq|$. \qed

From the lemma above, it is clear that if $\hat{\delta}_F(z) < \infty$, then $z \in \hat{D}_{\text{lin}}$.  

42
11 Area on the Lamination

Throughout this section, $F$ will be a centered inner function with finite Lyapunov exponent. For a measurable set $A$ compactly contained in the unit disk, we write $\hat{A}$ for the collection of inverse orbits $z$ with $z_0 \in A$. We define an $\hat{F}$-invariant measure $\xi$ on $\hat{D}$ by specifying it on sets of the form $\hat{A} \subset \hat{D}$ in a consistent manner:

$$\xi(\hat{A}) = \lim_{n \to \infty} \frac{1}{2\pi} \int_{F^{-n}(A)} \log \frac{1}{|z|} \, dA_{\text{hyp}}(z).$$  \hspace{1cm} (11.1)

In order to show that the limit in (11.1) exists, we check that the numbers

$$\int_{F^{-n}(A)} \log \frac{1}{|z|} \, dA_{\text{hyp}}$$

are increasing and uniformly bounded above. This follows from Lemma 11.1 and Theorem 11.2 below:

**Lemma 11.1.** For a measurable subset $E$ of the unit disk,

$$\int_{F^{-1}(E)} \log \frac{1}{|z|} \, dA_{\text{hyp}} \geq \int_E \log \frac{1}{|z|} \, dA_{\text{hyp}}.$$ 

**Proof.** A change of variables shows that

$$\int_{F^{-1}(E)} \log \frac{1}{|w|} \, dA_{\text{hyp}}(w) = \int_E \left\{ \sum_{F(w)=z} \|F'(w)\|^2_{\text{hyp}} \log \frac{1}{|w|} \right\} \, dA_{\text{hyp}}(z).$$

By the Schwarz lemma and Lemma 2.1 this is

$$\geq \int_E \left\{ \sum_{F(w)=z} \log \frac{1}{|w|} \right\} \, dA_{\text{hyp}}(z) = \int_E \log \frac{1}{|z|} \, dA_{\text{hyp}}$$

as desired. \hfill \Box

**Theorem 11.2.** The total mass $\xi(\hat{X}) = \int_{S^1} \log |F'(z)| \, dm$.

**Proof.** Since $F$ has an angular derivative a.e. on the unit circle, for any $\varepsilon > 0$, there is a Borel set $A_\varepsilon \subset S^1$ with $m(A_\varepsilon) \geq 1 - \varepsilon$ and an $0 < r_0 = r_0(\varepsilon) < 1$ so that

$$|F(re^{i\theta}) - F(e^{i\theta}) - (1 - r)F'(e^{i\theta})| < \varepsilon(1 - r),$$
for all $e^{i\theta} \in A_\varepsilon$ and $r \in [r_0, 1)$. Consider the set

$$\tilde{A}_\varepsilon = \left\{ re^{i\theta} \in \mathbb{D} : e^{i\theta} \in A_\varepsilon, r_0 \leq r \leq 1 - \frac{1 - r_0}{|F'(e^{i\theta})| - \varepsilon} \right\},$$

where we use the convention that $|F'(e^{i\theta})| = \infty$ if the angular derivative does not exist. By construction, the image $F(\tilde{A}_\varepsilon)$ is contained in the ball $B(0, r_0)$ so that $\tilde{A}_\varepsilon$ does not intersect any of its forward iterates. Therefore, by Lemma 11.1,

$$\xi(\hat{X}) \geq \frac{1}{2\pi} \int_{\tilde{A}_\varepsilon} \log \frac{1}{|z|} \, dA_{\text{hyp}} \geq \int_{A_\varepsilon} (\log |F'(e^{i\theta})| - \varepsilon) \, dm.$$

Taking $\varepsilon \to 0$ proves the lower bound.

For the upper bound, suppose that $E$ is a subset of the unit disk which is disjoint from its backward iterates. We want to show that

$$\frac{1}{2\pi} \int_{E} \log \frac{1}{|z|} \, dA_{\text{hyp}} \leq \int_{S^1} \log |F'(z)| \, dm.$$

Truncating $E$ if necessary, we may assume that $E$ is contained in a ball $B(0, r_0)$ for some $0 < r_0 < 1$. Consider the set $E^* = F^{-1}(B(0, r_0)) \setminus B(0, r_0)$. By construction,

$$\int_{E} \log \frac{1}{|z|} \, dA_{\text{hyp}} \leq \int_{E^*} \log \frac{1}{|z|} \, dA_{\text{hyp}}.$$

By Lemma 2.3, the set $E^*$ is contained in the union of

$$E_1^* = \left\{ re^{i\theta} \in \mathbb{D} : e^{i\theta} \in A_\varepsilon, r_0 \leq r \leq 1 - \frac{1 - r_0}{|F'(e^{i\theta})| + \varepsilon} \right\}$$

and

$$E_2^* = \left\{ re^{i\theta} \in \mathbb{D} : e^{i\theta} \notin A_\varepsilon, r_0 \leq r \leq 1 - \frac{1 - r_0}{4|F'(e^{i\theta})|} \right\},$$

so that

$$\frac{1}{2\pi} \int_{E^*} \log \frac{1}{|z|} \, dA_{\text{hyp}} \leq \frac{1}{2\pi} \int_{E_1^*} \log \frac{1}{|z|} \, dA_{\text{hyp}} + \frac{1}{2\pi} \int_{E_2^*} \log \frac{1}{|z|} \, dA_{\text{hyp}}.$$

The theorem follows after taking $\varepsilon \to 0$. \qed
11.1 Möbius structure

We will deduce the following theorem from the finiteness of the area of the Riemann surface lamination:

**Theorem 11.3** (Möbius structure). Backward iteration along \( \xi \) a.e. inverse orbit is asymptotically close to a Möbius transformation, i.e. \( \xi(\hat{D} \setminus \hat{D}_{\text{mob}}) = 0 \).

Suppose \( z \in \hat{D} \) is a point in the unit disk, which is not contained in the forward orbit of an exceptional point so that \( \bar{c}_z \) is a probability measure on \( T(z) \), see Section 3.1 for the relevant definitions. We fix a constant \( 0 < \gamma \leq 1 \) for which Lemma 2.4 holds. Then for any ball \( B = B_{\text{hyp}}(z, \gamma) \) with \( d_{\text{hyp}}(0, z) > 1 + \gamma \), the natural projection from \( \hat{D} \to \hat{X} \) is injective on \( \hat{B} \).

**Proof.** From the definition of the measure \( \xi \), we have

\[
\xi(\hat{B}) = \int_{\hat{B}} \Psi(z') \log \frac{1}{|z'|} \, dA_{\text{hyp}}(z')
\]

where

\[
\Psi(z') = \lim_{n \to \infty} \sum_{F^{\text{con}}(w') = z'} \log \frac{1}{|w'|} \cdot \|(F^{\text{con}})'(w')\|_{\text{hyp}}^{-2}
\]

\[
= \int_{T(z')} E(w', z')^2 \, d\bar{c}_z(w')
\]

is the average area expansion factor. Since \( \xi \) is a finite measure, \( \Psi(z') < \infty \) for Lebesgue a.e. \( z' \in \hat{B} \) and \( E(w', z') < \infty \) for \( \xi \) a.e. \( w' \in \hat{B} \). As discussed in Section 7, this implies that \( w' \in \hat{D}_{\text{mob}} \).

The theorem follows from the observation that countably many sets of the form \( \hat{B} \) cover \( \hat{X} \). \( \square \)

11.2 Möbius decomposition theorem

We say that a repeated pre-image \( w \) of \( z \) is \( \varepsilon \)-(Möbius good) if the hyperbolic expansion factor

\[
1 \leq \|(F^{\text{con}})'(w)\|_{\text{hyp}}^{-1} < 1 + \varepsilon,
\]

where \( F^{\text{con}}(w) = z \).

In view of Lemma 7.1, when \( \varepsilon > 0 \) is sufficiently small, the connected component of \( F^{-n}(\hat{B}) \) containing \( w \) maps conformally onto \( B \) under the dynamics
of $F$. Naturally, we call it $\mathcal{R}_w$. By shrinking $\varepsilon > 0$ further, we may assume that
\[ 1 \leq \|(F^n)'(q)\|_{\text{hyp}}^{-1} < 2, \quad \text{for any } q \in \mathcal{R}_w. \]
Similarly, we say that an inverse orbit $w \in T(z)$ is $\varepsilon$-(Möbius good) if
\[ 1 \leq \|(F^n)'(w_{-n})\|_{\text{hyp}}^{-1} < 1 + \varepsilon, \]
for any integer $n \in \mathbb{N}$. We define
\[ \hat{\mathcal{R}}_{\varepsilon, \text{M.good}} := \bigcup_{w \in T_{\varepsilon, \text{M.good}}(z)} \mathcal{R}_w, \]
where $w$ ranges over $T_{\varepsilon, \text{M.good}}(z)$, the set of $\varepsilon$-(Möbius good) inverse orbits with $w_0 = z$. On $\hat{\mathcal{R}}_{\varepsilon, \text{M.good}}$, the measure $\xi$ is comparable to the product measure
\[ \log \frac{1}{|q|} \frac{dA_{\text{hyp}}(q)}{\text{on } \mathcal{R}} \times \frac{c_z}{\text{on } T_{\varepsilon, \text{M.good}}(z)}. \quad (11.2) \]

**Remark.** In the one component case, the Riemann surface lamination $\hat{X}$ is locally a product space. The “charts” $\hat{\mathcal{R}}_{\varepsilon, \text{M.good}}$ may be viewed as substitutes of the product sets $\hat{\mathcal{R}}$ from the one component setting.

We say that a point $z \in \mathbb{D}$ is $\varepsilon$-(Möbius nice) if most inverse branches $w \in T(z)$ are $\varepsilon$-(Möbius good):
\[ \tau_z(T_{\varepsilon, \text{M.good}}(z)) > 1 - \varepsilon, \]
which is the same as asking that
\[ \sum_{\substack{F^m(w) = z, \ n \geq 0 \ \text{w is } \varepsilon-\text{M.good}}} \log \frac{1}{|w|} > (1 - \varepsilon) \log \frac{1}{|z|}, \]
for any $n \geq 0$.

**Theorem 11.4** (Möbius decomposition theorem). For a centered inner function $F$ with finite Lyapunov exponent, the following two assertions hold:

(a) For any $\varepsilon > 0$ and almost every point $z \in \mathbb{D}$, there exists an $n \geq 0$ so that
\[ \sum_{\substack{F^m(w) = z \ \text{w is } \varepsilon-\text{M.nice}}} \log \frac{1}{|w|} > (1 - \varepsilon) \log \frac{1}{|z|}. \quad (11.3) \]
For any \( \varepsilon > 0 \), one can find finitely many \( \varepsilon \)-(Möbius nice) points \( z_1, z_2, \ldots, z_N \), so that the sets
\[
\hat{B}_{i, \varepsilon\text{-M.good}}, \quad i = 1, 2, \ldots, N,
\]
cover \( \hat{X} \) up to \( \varepsilon \)-measure, i.e.
\[
\xi(\hat{X} \setminus \bigcup_{i=1}^{N} \hat{B}_{i, \varepsilon\text{-M.good}}) < \varepsilon.
\]

Proof. (a) Suppose \( w \in T(z) \) is a backward orbit. By the Schwarz lemma, the numbers \( E(w_{-n}, z) \) increase to \( E(w, z) \) as \( n \to \infty \), which may be infinite. Consequently, if (11.3) fails at a point \( z \in \mathbb{D} \) for all \( n \geq 0 \), then for at least \( \varepsilon \) measure backward orbits \( w \in T(z) \), the area expansion factor \( E(w, z) = \infty \). In this case, the average area expansion factor \( \Psi(z) = \infty \). However, in the proof of Theorem 11.3 we saw that \( \Psi(z) < \infty \) a.e., so (11.3) can only fail on a set of Lebesgue measure zero.

(b) If \( z \in \mathbb{D} \) is not \( \varepsilon \)-(Möbius nice), then
\[
\xi(\hat{B}_{\text{hyp}}(z, \gamma)) > \Theta \int_{B_{\text{hyp}}(z, \gamma)} \log \frac{1}{|z|} dA_{\text{hyp}},
\]
for some \( \Theta(\varepsilon) > 1 \). An examination of the proof of Theorem 11.2 shows that for any \( \eta > 0 \),
\[
\int_{E^*} \log \frac{1}{|z|} dA_{\text{hyp}} \geq (1 - \eta) \int_{S^1} \log |F'(z)| dm,
\]
where \( E^* = F^{-1}(B(0, r_0)) \setminus B(0, r_0) \) and \( 0 < r_0 < 1 \) is sufficiently close to 1.

Therefore, by asking for \( r_0 \) to be sufficiently close to 1, we can make the
\[
\log \frac{1}{|z|} dA_{\text{hyp}}(z)
\]
area of
\[
S = \{ z \in E^* : z \text{ is not } \varepsilon\text{-M.nice} \}
\]
as small as we wish. We may choose finitely many \( \varepsilon \)-(Möbius nice) points \( \{z_i\}_{i=1}^{N} \) in \( E^* \setminus S \) such that the balls of hyperbolic radius \( \gamma \) centered at these points cover \( E^* \setminus S \) up to small \( \log \frac{1}{|z|} dA_{\text{hyp}}(z) \) measure. Consequently, the sets
\[
\hat{B}_{\text{hyp}}(z_i, \gamma), \quad i = 1, 2, \ldots, N,
\]
cover \( \hat{X} \) up to small measure. \( \square \)
12 Linear structure

In this section, we show that backward iteration along almost every inverse orbit is asymptotically linear:

**Theorem 12.1** (Linear structure). Let \( z = (z_i)_{i=0}^{\infty} \in \hat{D} \) be a generic backwards orbit. For any \( R, \varepsilon > 0 \), there exists an \( n_0 = n_0(z, \varepsilon, R) > 0 \), so that the inverse branch
\[
F^{m-n} : z_m \to z_n, \quad n > m \geq n_0,
\]
is defined on the ball \( B_{hyp}(z_m, R) \), where it is within hyperbolic distance \( O(\varepsilon) \) of the linear map in \( \text{Aut}(\mathbb{C}) \) which takes
\[
z_m \to z_n \quad \text{and} \quad \frac{z_m}{|z_m|} \to \frac{z_n}{|z_n|}.
\]
In particular, \( \xi(\hat{D} \setminus \hat{D}_{lin}) = 0 \).

**Proof.** The main effort of the proof is to show that the cumulative linear distortion \( \hat{\delta}(w) < \infty \) for a.e. inverse orbit \( w \in \hat{D} \). In view of Theorem 11.4 it is enough to check that \( \hat{\delta}(w) < \infty \) for a.e. inverse orbit \( w \in \hat{B}_{M, \text{good}} \) where \( \hat{B} = B_{hyp}(z, \gamma) \) is a ball centered at an \( \varepsilon \)-Möbius nice point \( z \in \mathbb{D} \).

Let \( \hat{B}_{M, \text{good}} \subset \mathbb{D} \) be the union of topological disks \( \hat{B}_w \), where \( w \) ranges over the repeated pre-images of \( z \) with \( E(w, z) < 1 + \varepsilon \). We may assume that \( \varepsilon > 0 \) is sufficiently small so that \( E(w, z) < 1 + \varepsilon \) implies that \( E(\hat{w}, \hat{z}) < 2 \) for any \( \hat{w} \in \hat{B}_w \) and \( \hat{z} \in \hat{B} \). By Theorem 9.1 we have
\[
\int_{\hat{B}_{M, \text{good}}} \hat{\delta}(w) d\xi \leq 4 \int_{\hat{B}_{M, \text{good}}} \hat{\delta}(w) \cdot \log \frac{1}{|w|} \, dA_{hyp}(w)
\leq \int_{\mathbb{D}} \hat{\delta}(z) \cdot \log \frac{1}{|w|} \, dA_{hyp}(w)
\leq \int_{\partial \mathbb{D}} \log |F'(re^{i\theta})| \, dm
< \infty,
\]
and the claim follows. From the discussion in Section 10.2 we see that \( \xi \) gives full mass to \( \hat{D}_{lin} \subset \hat{D} \).

For an inverse orbit \( z = (z_i)_{i=0}^{\infty} \) with \( \hat{\delta}(z) < \infty \), we pick \( n_0 = n_0(z, \varepsilon, R) \) sufficiently large so that \( \sum_{n=n_0+1}^{\infty} \delta(z_i) < \varepsilon \) and \( 1 - |z_{-n_0}| < \varepsilon/e^R \). The
bound on the cumulative distortion ensures that a branch of $F^{m-n}$ is defined on $B_{hys}(z_m, R)$, where it is within hyperbolic distance $O(\varepsilon)$ of the straight Möbius transformation which sends

$$z_m \to z_n, \quad \frac{z_m}{|z_m|} \to \frac{z_n}{|z_n|}, \quad -\frac{z_m}{|z_m|} \to -\frac{z_n}{|z_n|}.$$ 

The second condition $1 - |z_{-n_0}| < \varepsilon/e^R$ makes $F^{m-n}$ close to linear. 

12.1 Linear decomposition theorem

We say that a point $z \in \mathbb{D}$ is $\varepsilon$-(linear nice) if $1 - |z| < \varepsilon/e^\gamma$ and for most inverse branches, backward iteration is close to a linear mapping:

$$c_z(\{w \in T(z) : \hat{\delta}(w) < \varepsilon\}) > (1 - \varepsilon) \cdot \log \frac{1}{|z|},$$

where $\hat{\delta}(w)$ is the cumulative linear distortion defined in Section 10.2.

**Theorem 12.2** (Linear decomposition theorem). (a) For any $\varepsilon > 0$ and almost every point $z \in \mathbb{D}$, there exists an $n \geq 0$ so that

$$\sum_{F^{\circ n}(w) = z} \log \frac{1}{|w|} > (1 - \varepsilon) \cdot \log \frac{1}{|z|}. \quad (12.1)$$

(b) For any $\varepsilon > 0$, one can find finitely many $\varepsilon$-(linear nice) points $z_1, z_2, \ldots, z_N$ so that

$$\xi(\bigcup_{i=1}^N \{z \in \mathbb{D} : \hat{\delta}(z) < \varepsilon\}) < \varepsilon.$$

**Proof.** (a) For a point $z' \in \mathbb{D}$, let $\Delta_{z'}$ denote the set of inverse orbits $w' \in T(z')$ for which the cumulative linear distortion $\hat{\delta}(w') = \infty$. If (12.1) fails at $z' \in \mathbb{D}$, then $\hat{\tau}_{z'}(\Delta_{z'}) \geq \varepsilon$.

For the sake of contradiction, assume that (12.1) fails on a set of positive Lebesgue measure $A$ in the unit disk. However, by the Schwarz lemma, this would imply that

$$\int_A \chi_{\{w : \hat{\delta}(w) = \infty\}} d\xi(w) = \int_A \int_{T(z')} \chi_{\{w : \hat{\delta}(w) = \infty\}} E(w', z')^2 d\tau_{z'}(w') \log \frac{1}{|z'|} dA_{hys}(z')$$

$$\geq \int_A \hat{\tau}_{z'}(\Delta_{z'}) \log \frac{1}{|z'|} dA_{hys}(z') > 0,$$

49
contradicting Theorem 12.1 which says that \( \delta(z') < \infty \) for Lebesgue a.e. \( z' \in \hat{D} \).

(b) The proof is similar to that of part (b) in Theorem 11.4.

\[ \square \]

13 The Geodesic Foliation Theorem

In this section, we show the following theorem which describes the structure of geodesic trajectories in \( \hat{D}_{\text{lin}} \):

**Theorem 13.1.** (i) For \( \xi \) a.e. backward orbit \( z \in \hat{D}_{\text{lin}} \) and \( n \geq 0 \), the limit

\[ \zeta_{-n}(z) := \lim_{t \to \infty} (g_{-t}(z))_{-n} \]

exists and \( (\zeta_{-n}(z)) \) belongs to the solenoid.

(ii) Let \( \gamma(t) = (g_{-t}(z))_0 \). If \( \gamma(t) \) is the radial geodesic that connects 0 with \( \zeta_0 = \zeta_0(z) \) parametrized with respect to unit hyperbolic speed, then

\[ \frac{1}{T} \int_0^T \min\{1, d_D(\gamma(t), \gamma(t_0 + t))\} dt \to 0, \quad \text{as } T \to \infty, \]

for some offset \( t_0 \in \mathbb{R} \) depending on \( z \).

(iii) For \( \hat{m} \) a.e. \( x \in \hat{S}^1 \), there exists a unique backward orbit in \( \hat{D}_{\text{lin}} \) that lands at \( x \).

(iv) If \( E \subset \hat{S}^1 \) has \( \hat{m} \) measure zero, then \( \zeta^{-1}(E) \subset \hat{D}_{\text{lin}} \) has \( \xi \) measure zero.

As a consequence, we deduce that the geodesic flow is ergodic:

**Corollary 13.2.** The geodesic flow on the Riemann surface lamination \( \hat{X}_{\text{lin}} \) is ergodic.

**Proof.** Suppose \( A \subset \hat{X}_{\text{lin}} \) is a \( g_t \)-invariant set. Lifting to \( \hat{D}_{\text{lin}} \), we get a \( (g_t, \hat{F}) \)-invariant set \( \tilde{A} \), which is a necessarily a union of geodesic trajectories. The endpoints of these trajectories under the backward geodesic flow form an \( \hat{F} \)-invariant set \( \zeta_0(\tilde{A}) \) in the solenoid. Since the action of \( \hat{F} \) on the solenoid is ergodic, either \( \zeta_0(\tilde{A}) \) or its complement has \( \hat{m} \) measure 0. By Theorem 13.1(iv), either \( \tilde{A} \) or its complement has \( \xi \) measure 0, and thus the same is true of \( A \).  \[ \square \]
13.1 Trajectories land on the solenoid

For $0 < r < 1$, we define the function $\hat{\delta}_r : \hat{X}_{\text{lin}} \to \mathbb{R}$ by

$$\hat{\delta}_r(z) := \max \left\{ 1, \sum \delta(z-k) \right\},$$

where we sum over the part of the inverse orbit contained in the annulus $A(0; r, 1)$. For any $0 < r < 1$, the function $\hat{\delta}_r(z)$ belongs to $L^2(\hat{X}_{\text{lin}})$, and the functions $\hat{\delta}_r(z)$ decrease pointwise a.e. to 0 as $r \to 1$.

By the ergodic theorem for invariant measures, for $\xi$ a.e. $z \in \hat{X}_{\text{lin}}$, the backward time average

$$\hat{\delta}_r, - (z) := \lim_{T \to \infty} \frac{1}{T} \int_0^T \hat{\delta}_r(g^{-t}(z)) dt$$

is the orthogonal projection of $\hat{\delta}_r$ onto the subspace of $g_t$-invariant functions in $L^2(\hat{X}_{\text{lin}})$. This implies that for $\xi$ a.e. $z \in \hat{X}_{\text{lin}}$, we have

$$\lim_{T \to \infty} \frac{1}{T} \int_0^T \hat{\delta}(g^{-t}(z)) = 0,$$

which implies (i) and (ii) by Theorem A.1.

13.2 Uniqueness

Suppose $z, z' \in \hat{D}_{\text{lin}}$ are two generic inverse orbits with respect to the measure $\xi$ for which $\zeta(z) = \zeta(z')$. By part (ii), we know that for each $n \geq 0$, the trajectories $g^{-t}(z)_{-n}$ and $g^{-t}(z')_{-n}$ both weakly shadow the same radial ray $[0, \zeta_{-n}]$. By Lemma 10.1, the trajectories $g^{-t}(z)$ and $g^{-t}(z')$ belong to the same leaf, which means that there exists a vertical geodesic

$$V_{z'} = \{ z \in \mathbb{H} : \text{Re} x = \xi' \} \subset \mathbb{H}$$

so that $\{ g_t(z')_{-n} : t \in \mathbb{R} \} = F_{z_{-n}}(V_{z'})$. Weak shadowing forces $\xi' = 0$, i.e. $z$ and $z'$ belong to the same geodesic trajectory, which proves the uniqueness statement in (iii).
13.3 Rescaling limits and measures

A set $A \subset \mathcal{B}_{\varepsilon,\text{L-good}}$ is naturally decomposed as a union of slices:

$$A = \bigcup_{z \in T_{\varepsilon,\text{L-good}}(z)} A_z,$$

with the slice $A_z \subset \mathcal{B}_z$ consisting of inverse orbits $w$ which follow $z$, i.e. $w_{-n}$ lies in the same connected component of $F^{-n}(\mathcal{B})$ as $z_{-n}$ for any $n \in \mathbb{N}$.

Via rescaling maps, we may view the slices of $A$ as subsets of the upper half-plane. More precisely, for $z \in T_{\varepsilon,\text{L-good}}(z)$, we may define the sets

$$A^*_z \subset \mathcal{B}^*_z = F_{z,0}^{-1}(\mathcal{B}) \subset \mathbb{H}.

Theorem 13.3. The following equalities hold:

$$\xi(A) = \int_{T_{\varepsilon,\text{L-good}}(z)} \left\{ \int_{A^*_z} \frac{dA(w)}{\text{Im } w} \right\} dc_z$$

and

$$\hat{m}(\zeta(A)) = \int_{T_{\varepsilon,\text{L-good}}(z)} \ell(\Pi_{\mathbb{H} \rightarrow \mathbb{R}}(A^*_z)) dc_z,$$

where $\Pi_{\mathbb{H} \rightarrow \mathbb{R}}$ is the orthogonal projection onto the real line and $\ell$ is the Lebesgue measure on the real line.

The proof of the above theorem is somewhat involved and will be given in Appendix C.

13.4 Abundance of landing points

We now show that the landing points of backward trajectories of the geodesic flow cover a positive $\hat{m}$ measure of the solenoid $\hat{S}$. Since $\hat{m}$ is ergodic with respect to the action of $\hat{F}$, it will then follow that landing points of backward trajectories cover the solenoid up to measure zero, proving the existence statement in (iii).

For this purpose, we take $A = \mathcal{B}_{\varepsilon,\text{L-good}}$ in Theorem 13.3. By the Schwarz lemma, each $A^*_z$ with $z \in T_{\varepsilon,\text{L-good}}(z)$ contains the ball $B_{\text{hyp}}(i, \gamma)$, while by $\varepsilon$-linearity, $A^*_z$ is contained in the larger ball $B_{\text{hyp}}^*(i, 2\gamma)$. Consequently,

$$\hat{m}(\zeta(A)) = \int_{T_{\varepsilon,\text{L-good}}(z)} \ell(\Pi_{\mathbb{H} \rightarrow \mathbb{R}}(A^*_z)) dc_z \gtrsim c_z(T_{\varepsilon,\text{L-good}}(z)),$$

which is certainly positive if $z \in \mathbb{D}$ is $\varepsilon$-(linear nice).
13.5 Non-singularity

Finally, we show that if a set \( A \subset \hat{D} \) has positive \( \xi \) measure, then its projection \( \zeta(A) \) to the solenoid has positive \( \hat{m} \) measure. As the intersection of \( A \) with some set of the form \( \hat{B}_{\gamma-L,good} \) has positive \( \xi \) measure, we may assume that \( A \) is contained in a single \( \hat{B}_{\gamma-L,good} \). Since

\[
\int_K \frac{dA(w)}{\text{Im} w} \lesssim \ell(\Pi_{\mathbb{H} \to \mathbb{R}}(K)),
\]

for any measurable set \( K \subset B_{\text{hyp}}(i,2\gamma) \subset \mathbb{H} \), we have

\[
\xi(A) \lesssim \hat{m}(\zeta(A)),
\]

so \( \hat{m}(\zeta(A)) > 0 \) as well, which proves (iv).

14 Orbit Counting

In this section, we prove Theorem 1.1 on averaged orbit counting for centered inner functions of finite Lyapunov exponent.

**Theorem 14.1.** Let \( F \) be an inner function of finite Lyapunov exponent with \( F(0) = 0 \) for which the geodesic flow is ergodic on the Riemann surface lamination \( \hat{X}_{\text{lin}} \). Suppose \( z \in \mathbb{D} \setminus \{0\} \) lies outside a set of measure zero. Then,

\[
\lim_{R \to +\infty} \frac{1}{R} \int_0^R \frac{N(z,S)}{e^S} dS = \frac{1}{2} \log \frac{1}{|z|} \cdot \frac{1}{\int_{\partial \mathbb{D}} \log |F'| dm}.
\]

(14.1)

We say that a function \( h : \mathbb{D} \to \mathbb{C} \) is weakly almost invariant under \( F \) if for a.e. every backward orbit \( z = (z_i)_{i=-\infty}^{-0} \in \hat{D} \), \( \lim_{i \to -\infty} h(z_i) \) exists and defines a function on the Riemann surface lamination:

\[
\hat{h}(z) = \lim_{i \to -\infty} h(z_i).
\]

**Theorem 14.2.** Let \( F \) be a centered inner function of finite Lyapunov exponent for which the geodesic flow on \( \hat{X}_{\text{lin}} \) is ergodic. Suppose \( h : \mathbb{D} \to \mathbb{C} \) is a bounded weakly-almost invariant function that is uniformly continuous in the hyperbolic metric. Then for almost every \( \zeta \in S^1 \), we have

\[
\lim_{r \to 1} \frac{1}{|\log(1-r)|} \int_0^r h(s\zeta) \cdot \frac{ds}{1-s} = \int_X \hat{h} d\xi.
\]
In particular,
\[
\lim_{r \to 1} \frac{1}{2\pi \log(1 - r)} \int_{D_r} h(z) \cdot \frac{dA(z)}{1 - |z|} = \int_{\hat{X}} \hat{h}d\xi.
\]

Proof. For simplicity, we first consider the case when \( h : D \to \mathbb{C} \) is eventually invariant under \( F \), i.e. there exists a \( 0 < \rho < 1 \) such that
\[
h(F^n(z)) = h(z), \quad |F^n(z)| > \rho.
\]

By the ergodic theorem, for \( \xi \) a.e. inverse orbit \( z \in \hat{X}_{lin} \), we have
\[
\lim_{T \to \infty} \frac{1}{T} \int_0^T \hat{h}(g^{-t}(z))dt = \int_{\hat{X}} \hat{h}d\xi. \tag{14.2}
\]

By Theorem 13.1(ii), for \( \xi \) a.e. \( z \in \hat{D}_{lin} \), \( \{g^{-t}(z) : t > 0\} \) weakly shadows a radial ray \([0, \zeta_0(z)]\). Since \( h \) is eventually invariant and \( \{g^{-t}(z) : t > 0\} \) is eventually contained in the annulus \( A(0; \rho, 1) \),
\[
\lim_{T \to \infty} \frac{1}{T} \int_0^T \hat{h}(g^{-t}(z))dt = \lim_{T \to \infty} \frac{1}{T} \int_0^T h(g^{-t}(z_0))dt. \tag{14.3}
\]

By the weak shadowing and the uniform continuity of \( h \) in the hyperbolic metric,
\[
\lim_{r \to 1} \frac{1}{|\log(1 - r)|} \int_0^r h(s \cdot \zeta_0(z)) \cdot \frac{ds}{1 - s} = \int_{\hat{X}} \hat{h}d\xi. \tag{14.4}
\]

According to Theorem 13.1(iv), endpoints \( \zeta(z) \) of inverse orbits \( z \in \hat{D}_{lin} \) satisfying (14.4) cover the solenoid up to a \( m \) measure zero set. Projecting onto the 0-th coordinate, we see that (14.4) holds for \( m \)-a.e. \( \zeta \in S^1 \).

We now turn to the general case when \( h \) is only a weakly almost invariant function. The missing step is to show that (14.3) holds for \( \xi \) almost every inverse orbit \( z \in \hat{D}_{lin} \).

Given \( \varepsilon > 0 \) and \( 0 < \rho < 1 \), let \( E(\varepsilon, \rho) \subset \hat{X}_{lin} \) be the complement of the set of the inverse orbits \( z = (z_n)_{n=-\infty}^{\infty} \) for which
\[
|h(z_n) - \hat{h}(z)| < \varepsilon,
\]
for all \( n \in \mathbb{Z} \) with \( |z_n| > \rho \). By the definition of a weakly almost invariant function, for any fixed \( \varepsilon > 0 \), \( \xi(E(\varepsilon, \rho)) \to 0 \) as \( \rho \to 1 \). We may therefore choose \( \rho = \rho(\varepsilon) \) so that \( \xi(E(\varepsilon, \rho)) < \varepsilon \).
By the ergodic theorem, a generic backward trajectory \( \{g_{-t}(z) : t > 0 \} \) spends little time in \( E(\varepsilon, \rho) \), i.e.
\[
\lim_{T \to \infty} \frac{1}{T} \int_0^T \chi_{E(\varepsilon, \rho)}(g_{-t}(z)) \, dt < \varepsilon.
\]
As \( \{g_{-t}(z)_0 : t > 0 \} \) is eventually contained in the annulus \( A(0; \rho, 1) \), the difference
\[
\limsup_{T \to \infty} \frac{1}{T} \int_0^T \left\{ \hat{h}(g_{-t}(z)) - h(g_{-t}(z)_0) \right\} \, dt \lesssim \varepsilon + \varepsilon \|h\|_{\infty},
\]
which can be made arbitrarily small by requesting that \( \varepsilon > 0 \) is small, thereby justifying (14.3).

14.1 A weakly almost invariant function

To prove Theorems 14.1, we will use a slight modification \( h_{\text{nice}} \) of the almost invariant function \( h_{\text{smooth}} \) from Section 4.2 which was constructed by first defining \( h_{\text{smooth}} \) on a box \( \Box = \Box(z, \delta) \) and then extending it to the repeated pre-images of \( \Box = \Box(z, \delta) \) by invariance.

On the box \( \Box = \Box(z, \delta) \), we set \( h_{\text{nice}} = h_{\text{smooth}} \). Let \( w \) be a repeated pre-image of \( z \), i.e. \( F^n(w) = z \) for some \( n \geq 0 \). Recall that \( w \) is an \( \varepsilon \)-(linear good) pre-image if \( e^{\gamma}(1 - |z|) < \varepsilon \) and
\[
\hat{\delta}(w, z) := \sum_{i=0}^{n} \delta(w) \leq \varepsilon.
\]
When \( \varepsilon > 0 \) is sufficiently small, the connected component
\[
\Box_w = F^{-1}(\Box(z, \delta))
\]
containing \( w \) is a topological disk which has roughly the same hyperbolic size and shape as \( \Box \). On each such good box \( \Box_w \), we define \( h_{\text{nice}} \) by invariance. Outside the good boxes, we set \( h_{\text{nice}} \) to be zero.

In view of Theorem 12.2, \( h_{\text{nice}} \) is a weakly almost invariant function on the unit disk. Recall from Section 4.2 that \( h_{\text{nice}} = h_{\text{smooth}} \) was chosen to be uniformly continuous in the hyperbolic metric on \( \Box \). By the Schwarz lemma,
$h_{nice}$ is uniformly continuous in the hyperbolic metric on $\mathbb{D}$. We denote its natural extension to the Riemann surface lamination by $\hat{h}_{nice}$.

The proof of Theorems [14.1] is nearly the same as that of Theorem [4.4]. We therefore point out the differences: In Step 1, we assume that $z \in A(0; 1 - \varepsilon, 1)$ is an $\varepsilon$-(linear nice) point and we show that

$$\frac{1}{R} \sum_{F^n(w) = z, \ n \geq 0} e^{-d_{\mathbb{D}}(0,w)} \sim_{\varepsilon, R} \frac{1}{2} \log \frac{1}{|z|} \cdot \int_{\partial \mathbb{D}} \log |F'| \text{d}m,$$

where we only count the number of $\varepsilon$-(linear good) pre-images. Steps 2 and 3 proceed as before for $\varepsilon$-(linearly decomposable) points, i.e. points satisfying (12.1).

**Part IV**

**Parabolic Inner Functions**

By a parabolic inner function, we mean an inner function $F$ whose Denjoy-Wolff fixed point $p \in \partial \mathbb{D}$ with $F'(p) := \lim_{r \to 1} F'(rp) = 1$.

We view parabolic inner functions as holomorphic self-maps of the upper half-plane, with the parabolic fixed point at infinity. In this case, Lebesgue measure $\ell$ on the real line is invariant, e.g. see [DM91]. We say that a parabolic inner function $F : \mathbb{H} \to \mathbb{H}$ has finite Lyapunov exponent if

$$\chi_{\ell} = \int_{\mathbb{R}} \log |F'(x)| \text{d}\ell < \infty.$$

By Julia’s lemma, for any point $z_0 \in \mathbb{H}$, the imaginary parts $\{\text{Im } F^{\circ n}(z_0)\}$ are increasing. We say that $F$ has finite height if $\{\text{Im } F^{\circ n}(z_0)\}$ are uniformly bounded and infinite height if $\text{Im } F^{\circ n}(z_0) \to \infty$. In view of the Schwarz lemma, this definition is independent of the choice of the starting point $z_0 \in \mathbb{H}$.

In this final part of the paper, we discuss orbit counting theorems for parabolic inner functions of infinite height. As the proofs are essentially the same, we only give a brief description of the results and leave the details to the reader.
15 Statements of Results

For a bounded interval $I \subset \mathbb{R}$ and a real number $R > 0$, consider the counting function

$$N_I(z, R) = \# \{ w \in I \times [e^{-R}, 1] : F^n(w) = z \text{ for some } n \geq 0 \}.$$

**Theorem 15.1.** Let $F : \mathbb{H} \to \mathbb{H}$ be an infinite height parabolic inner function of finite Lyapunov exponent. Suppose $z \in \mathbb{H}$ lies outside a set of zero measure. Then,

$$\frac{1}{R} \int_0^R N_I(z, S) e^S dS \sim |I| \cdot \frac{1}{\int_\mathbb{R} \log |F'| d\ell}$$

as $R \to \infty$.

When a parabolic inner function $F : \mathbb{D} \to \mathbb{D}$ is holomorphic in a neighbourhood of the Denjoy-Wolff point $p \in \partial \mathbb{D}$, we can classify it as *singly parabolic* or *doubly parabolic* depending on whether the Taylor expansion is

$$F(z) = p + (z - p) + a_2(z - p)^2 + \ldots, \quad a_2 \neq 0$$

or

$$F(z) = p + (z - p) + a_3(z - p)^3 + \ldots, \quad a_3 \neq 0.$$

Singly and doubly parabolic inner functions on the upper half-plane are defined by conjugating with a Möbius transformation that takes $\mathbb{D}$ to $\mathbb{H}$. For example, $z \mapsto z - 1/z + T$ is doubly-parabolic for $T = 0$, while singly-parabolic for $T \in \mathbb{R} \setminus \{0\}$. Singly parabolic functions have finite height, while doubly parabolic functions have infinite height.

**Theorem 15.2.** Let $F : \mathbb{H} \to \mathbb{H}$ be a doubly-parabolic one component inner function of finite Lyapunov exponent. For all $z \in \mathbb{H}$ lying outside a countable set, we have

$$N_I(z, R) \sim |I| \cdot \frac{1}{\int_\mathbb{R} \log |F''| d\ell},$$

as $R \to \infty$. 

57
15.1 Background on parabolic inner functions

In the upper half-plane, Lemmas 2.1, 2.2 and 2.3 read as follows:

**Lemma 15.3.** Suppose $F$ is a parabolic inner function with the parabolic fixed point at infinity. For a non-exceptional point $z \in \mathbb{H}$,

$$\text{Im } z = \sum_{F(w)=z} \text{Im } w. \quad (15.1)$$

An inner function viewed as self-mapping of the upper half-plane can be expressed as

$$F(z) = \alpha z + \beta + \int_{\mathbb{R}} \frac{1 + zw}{w - z} d\mu(w),$$

for some constants $\alpha > 0$, $\beta \in \mathbb{R}$ and a finite positive singular measure $\mu$ on the real line, e.g., see [Tsu59]. Differentiating, we get

$$F'(z) = \alpha + \int_{\mathbb{R}} \frac{w(w - z) + (1 + wz)}{(w - z)^2} d\mu(w),$$

$$= \alpha + \int_{\mathbb{R}} \frac{w^2 + 1}{(w - z)^2} d\mu(w).$$

Since $\alpha = \lim_{t \to \infty} F'(it)$, an inner function has a parabolic fixed point at infinity if and only if $\alpha = 1$. The following two lemmas are straightforward consequences of the above formula:

**Lemma 15.4.** If $F$ is a parabolic inner function with the parabolic fixed point at infinity, then for a bounded interval $J$ in the real line, there exists a constant $c_J > 1$ such that $F'(\zeta) > c_J$ for all $\zeta \in J$.

**Lemma 15.5.** If $F(z)$ is an inner function, viewed as a map of the upper half-plane to itself, then

$$|F'(x + iy)| \leq |F'(x)| \quad (15.2)$$

for all $x + iy \in \mathbb{H}$.

15.2 Riemann surface laminations

For a parabolic inner function $F$, we may form the space of backward orbits

$$\hat{\mathbb{H}} = \lim_{\leftarrow} (F : \mathbb{H} \to \mathbb{H}) = \{(z_i)_{i=-\infty}^0 : F(z_i) = z_{i+1}\}.$$
The Riemann surface lamination is then defined as $\tilde{X} = \mathbb{H}/\mathbb{F}$. In view of Lemma 15.3, the natural measure $d\xi$ on $\tilde{X}$ is now given by the formula

$$\xi(\tilde{F}) = \lim_{n \to \infty} \int_{F^{-n}(\mathbb{B})} \frac{|dz|^2}{\text{Im} z}. \quad (15.3)$$

Adapting the proof of Theorem 11.2 to the current setting shows that

$$\xi(\tilde{X}) = \int_{\mathbb{R}} \log|F'(x)|d\ell.$$

*Remark.* (i) The infinite height condition guarantees that every inverse orbit passes through a backward fundamental domain of the form $F^{-1}(\mathbb{H}_t) \setminus \mathbb{H}_t$, where $\mathbb{H}_t = \{z \in \mathbb{H} : \text{Im} z > t\}$.

(ii) Without the infinite height condition, the Riemann surface lamination $\tilde{X}$ may not have finite volume. For instance, for the singly parabolic Blaschke product $z \to z - 1/z + T$ with $T \in \mathbb{R} \setminus \{0\}$, the volume of $\tilde{X}$ is infinite, even though

$$\int_{\mathbb{R}} \log\left(1 + \frac{1}{z^2}\right) d\ell(z) = 2\pi.$$

(iii) By Lemma 15.4, a generic inverse orbit $(z_i)$ does not converge to infinity, and therefore $\text{Im} z_i \to 0$.

As in Section 12, one can show:

**Lemma 15.6.** For a finite Lyapunov exponent inner function $F : \mathbb{H} \to \mathbb{H}$ with a parabolic fixed point at infinity,

$$\int_{\mathbb{H}} \delta(x + iy) \cdot \frac{dxdy}{y} < \infty.$$

The above lemma implies that iteration along a.e. inverse orbit is essentially linear and therefore a.e. leaf of $\tilde{X}$ is covered by $(\mathbb{H}, \infty)$, which allows one to define geodesic and horocyclic flows on $\tilde{X}$.

The following theorems are analogues of Theorems 4.1 and 4.2 respectively:

**Theorem 15.7.** For an infinite height parabolic inner function $F : \mathbb{H} \to \mathbb{H}$ of finite Lyapunov exponent, the geodesic flow on $\tilde{X}$ is ergodic. In particular, if
$h : \mathbb{H} \to \mathbb{C}$ is a bounded almost invariant function that is uniformly continuous in the hyperbolic metric, then for almost every $x \in \mathbb{R}$, we have

$$\lim_{t \to 0} \frac{1}{|\log t|} \int_t^1 h(x + iy) \cdot \frac{dy}{y} = \frac{1}{\int_{\mathbb{R}} |F'|d\ell} \int_{\hat{X}} \hat{h}d\xi.$$  

**Theorem 15.8.** For a doubly parabolic one component inner function $F : \mathbb{H} \to \mathbb{H}$ of finite Lyapunov exponent, the geodesic flow on $\hat{X}$ is mixing. In particular, if $h : \mathbb{H} \to \mathbb{C}$ is a bounded almost invariant function that is uniformly continuous in the hyperbolic metric and $I \subset \mathbb{R}$ is a bounded interval, then

$$\lim_{y \to 0} \int_I h(x + iy)d\ell(x) = \frac{|I|}{\int_{\mathbb{R}} |F'|d\ell} \int_{\hat{X}} \hat{h}d\xi.$$  

Again, the proofs are similar to the case when the Denjoy-Wolff point is inside the disk. (To show the mixing of the geodesic flow, we use that for doubly parabolic one component inner functions, the multipliers of the repelling periodic orbits on the real line do not belong to a discrete subgroup of $\mathbb{R}^+$, for a proof, see [1223, Section 9.4].)

**Part V**

**Appendices**

**A A Shadowing Lemma**

The following theorem roughly says that if you drive a car in the upper half-plane with the desire to reach the real axis, and you are able to steer the car for most of the time, then on average, your path will be close to a vertical geodesic:

**Theorem A.1.** Let $\gamma : [0, \infty) \to \mathbb{H}$ be a $C^1$ parametrized curve in the upper half-plane with $\|\gamma'(t)\|_{\text{hyp}} \leq 1$. Suppose $[0, \infty) = G \cup B$ is partitioned into good and bad times such that at good times, $\gamma'(t) = v_{\perp} = -y \cdot \frac{\partial}{\partial y}$, while at bad times, $\gamma'(t)$ can point in any direction.
(i) If the upper density of bad times

\[ \limsup_{T \to \infty} \frac{|\{0 < t < T : t \in B\}|}{T} = 0, \quad (A.1) \]

then the limit \( \zeta = \lim_{t \to \infty} \gamma(t) \) exists and lies on the real axis.

(ii) Furthermore, if \( \overline{\gamma}(t) \) is the vertical geodesic to \( \zeta \), then

\[ \frac{1}{T} \int_0^T \min\{1, d_H(\gamma(t), \overline{\gamma})\} \, dt \to 0, \quad \text{as } T \to \infty. \quad (A.2) \]

Remark. The above theorem remains true if during a good time, we allow \( \gamma'(t) \) to be only approximately equal to \( \nu_\bot \), rather than exactly equal: it is enough to require that \( \|\gamma'(t) - \nu_\bot\| < c \) for some \( c < 1/2 \).

The proof of Theorem [A.1] is based on the following simple observation:

**Lemma A.2.** Suppose \( \sigma \geq 0 \) is a locally finite singular measure on \([0, \infty)\) such that \( \sigma([0,T])/T \to 0 \) as \( T \to \infty \). The function

\[ \Delta_\infty(t) = \int_t^{\infty} e^{-(\tau-t)}d\sigma(\tau) \]

is sub-linear: \( \Delta_\infty(T)/T \to 0 \) as \( T \to \infty \).

The above lemma easily follows from Fubini’s theorem. In the proof below, we will also use the function

\[ \Delta_T(t) = \int_t^T e^{-(\tau-t)}d\sigma(\tau). \]

**Proof of Theorem [A.1] Step 1.** For clarity, we first examine the case when during a bad time, \( \gamma'(t) = v_\bot = y \cdot \frac{\partial}{\partial x} \). Consider the map \( q : [0, \infty) \to [0, \infty) \) which “collapses” the set of bad times:

\[ q(t) = |\{0 \leq s \leq t : s \notin B\}|. \]

and let \( \sigma = q_*(\chi_B \, d\ell) \) be the push-forward of the part of the Lebesgue measure supported on \( B \). By assumption \( [A.1] \) on the bad set, we have

\[ \frac{q(t)}{t} \to 1 \quad \text{and} \quad \frac{\sigma([0, T])}{T} \to 0, \quad \text{as } T \to \infty. \]
From the definitions, is clear that $\Delta_T(q(t))$, with $0 < t \leq T < \infty$, is the hyperbolic length of the horizontal segment between $\gamma(t)$ and the vertical geodesic $\gamma_T$ which passes through $\gamma(T)$. Lemma [A.2] prevents the geodesic $\gamma_T$ from moving too much, so it converges as $T \to \infty$. We denote the limiting vertical geodesic by $\overline{\gamma}$. Lemma [A.2] also shows that restricted to good times, the average distance from $\gamma(t)$ to $\overline{\gamma}$ is small.

**Step 2.** We now assume that during a bad time

$$\gamma'(t) = v_\uparrow + v_\downarrow = y \cdot \left\{ \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right\},$$

which is worse than the worst case scenario allowed in Theorem [A.1]. Let $B^* \supset B$ be the set of $s > 0$ for which there exists $t > s$ so that

$$|[s,t] \cap B| \geq \frac{1}{3} \cdot |t - s|.$$

In view of the Hardy-Littlewood Maximal Theorem,

$$|[0,T] \cap B^*| \leq C |[0,T] \cap B|,$$

for some $C > 0$, and therefore,

$$\frac{|\{0 < t < T : t \in B^*\}|}{T} \to 0.$$

This time, we define

$$q(t) = |\{0 \leq s \leq t : s \notin B^*\}|$$

and $\sigma = q_*(\chi_{B^*} \, d\ell)$. Inspection shows that $\Delta_T(q(t))$ provides an upper bound for the hyperbolic length of the horizontal segment between $\gamma(t)$ and the vertical geodesic $\gamma_T$. The proof is completed by Lemma [A.2] as in Step 1.

---

**B A Criterion for Angular Derivatives**

In this appendix, we show:

**Theorem B.1.** A holomorphic self-map of the unit disk $F$ has a finite angular derivative at $\zeta \in \partial \mathbb{D}$ in the sense of Carathéodory if and only if

$$\int_0^\zeta \mu(z) \, d\rho = \int_0^\zeta \left( 1 - \frac{1 - |z|^2}{1 - |F(z)|^2} \right) 2 |dz| \frac{1 - |z|^2}{1 - |z|^2} < \infty. \quad (B.1)$$
By composing with a Möbius transformation, we may assume that $F(0) = 0$. By the Schwarz lemma, the function

$$L(r) = \{d_D(0, r\zeta) - d_D(0, F(r\zeta))\}, \quad 0 < r < 1,$$

is increasing. The limit

$$\lim_{r \to 1} L(r) < \infty$$

is finite if and only if $F$ has an angular derivative at $\zeta$, in which case,

$$\lim_{r \to 1} L(r) = \log |F'(\zeta)|.$$

In other words, $F$ possesses an angular derivative at $\zeta$ if when moving from 0 to $\zeta$ along the radial geodesic ray $\gamma = [0, \zeta]$ at unit hyperbolic speed, the image point efficiently moves toward the unit circle. Expressed infinitesimally, this says that $F$ has a finite angular derivative at $\zeta \in \partial D$ if and only if

$$\int_0^\zeta \eta(z) \, d\rho < \infty.$$  \hfill (B.2)

The main difficulty in proving Theorem B.1 is replacing the radial inefficiency $\eta$ with the Möbius distortion $\mu$.

**Proof of Theorem B.1.** Since $\mu \leq \eta \leq \mu + \alpha$, it is enough to show that

$$\int_0^\zeta \mu(z) \, d\rho < \infty \quad \implies \quad \int_0^\zeta \alpha(z) \, d\rho < \infty.$$

**Step 1.** A compactness argument shows that for every $\varepsilon > 0$, there is a $\delta > 0$ so that if $\mu(z) < \delta$ then $\mu(w) < \varepsilon$ for all $w \in B_{\text{hyp}}(z, 1)$.

As a result, the Möbius distortion $\mu(r\zeta) \to 0$ as $r \to 1$. Lemma 7.2 tells us that the geodesic curvature

$$\kappa_{F(\gamma)}(F(r\zeta)) \to 0, \quad r \to 1.$$

Therefore, by Lemma 6.2, $F(\gamma)$ lies within a bounded hyperbolic distance of the geodesic ray $[0, F(\zeta)]$. In particular, this shows that $F$ possesses a radial boundary value at $\zeta$ somewhere on the unit circle.

**Step 2.** By Lemma 7.2, the total geodesic curvature of $F(\gamma)$ is finite:

$$\int_0^\zeta \kappa_{F(\gamma)}(F(z)) \, d\rho < \infty.$$
Since $F(\gamma)$ lies within a bounded hyperbolic distance of the geodesic ray $[0, F(\zeta)]$, there is a sequence of $r_n$'s tending to 1 so that $\alpha_{F(r_n\zeta)} < 2\pi/3$. (It is not possible for $F(\gamma)$ to approach the unit circle if the tangent vector always points away from the unit circle.)

Therefore, there exists an $0 < r_n < 1$ so that

$$\alpha_{F(r_n\zeta)} < 2\pi/3 \quad \text{and} \quad \int_{r_n\zeta}^\zeta \kappa_{F(\gamma)}(F(z)) \, d\rho < 0.1.$$ 

Lemma 6.7 tells us

$$\int_{r_n\zeta}^\zeta \alpha(z) \, d\rho = O(1),$$

which is what we wanted to show. \qed

## C Integrating over Leaves

In this appendix, we prove Theorem 13.3, which describes the measures $\xi$ and $\hat{m}$ in terms of integration along leaves, similar to McMullen’s original definitions of these measures given in Section 3.3.

### C.1 The case of $\hat{D}$

We define a $\sigma$-finite measure $\xi_{\text{leaf}}$ on the solenoid $\hat{X}$ so that its restriction to any “chart” of the form $\hat{B}_{\epsilon, \text{good}} \subset \hat{X}$ is given by

$$\xi_{\text{leaf}}(A) = \int_{T_{\epsilon, \text{good}}(z)} \left\{ \int_{A_z^\epsilon} \frac{dA(w)}{\text{Im} w} \right\} \, dc_z,$$

while the set of points not contained in any chart have $\xi_{\text{leaf}}$ measure zero. After lifting to $\hat{D}$, we obtain an $\hat{F}$-invariant measure on $\hat{D}$, which we also denote by $\xi_{\text{leaf}}$. Our objective is to show that $\xi = \xi_{\text{leaf}}$:

**Theorem C.1.** The measures $\xi$ and $\xi_{\text{leaf}}$ on $\hat{D}$ are equal.

We begin by checking that the measure $\xi_{\text{leaf}}$ is well-defined:

**Lemma C.2.** If $B' = B_{\text{hyp}}(z', \gamma)$ is another ball of hyperbolic radius $\gamma$ which intersects $B$ and $A \subset \hat{B} \cap \hat{B}'$ then

$$\int_{T_{\epsilon, \text{good}}(z)} \left\{ \int_{A_z^\epsilon} \frac{dA(w)}{\text{Im} w} \right\} \, dc_z = \int_{T_{\epsilon, \text{good}}(z')} \left\{ \int_{A_z^\epsilon} \frac{dA(w)}{\text{Im} w} \right\} \, dc_{z'}.$$
Proof. Given an inverse orbit $z \in T(z)$, we can select an inverse orbit $z' \in T(z')$ which follows $z$ by using the same inverse branches. As the dynamics is asymptotically linear, the limit

$$\rho_{z,z'} = \lim_{n \to \infty} \frac{1 - |z'_{-n}|}{1 - |z_{-n}|}$$

exists. Inspection shows that $\rho_{z,z'} = dc'_{z'}/dc_{z}$ is just the Radon-Nikodym derivative of the transverse measures $c_{z}$ and $c'_{z}$.

Recall from Section 10 that when we define the slice $A^*_z \subset \mathbb{H}$, we rescale by a Möbius transformation so that $z_{-n} \in \mathbb{D}$ maps to $i \in \mathbb{H}$, while when we define the slice $A^*_{z'} \subset \mathbb{H}$, we rescale so that $z'_{-n} \in \mathbb{D}$ maps to $i \in \mathbb{H}$. Consequently, when changing from $z$ to $z'$, the integrand $\int_{A^*_z} \frac{dA(w)}{\lim w}$ decreases by the factor $\rho_{z,z'}$, compensating for the Radon-Nikodym derivative. As a result, the expression for $\xi_{\text{leaf}}(A)$ remains unchanged.

Lemma C.3. The measure $\xi_{\text{leaf}}$ is absolutely continuous with respect to $\xi$.

Proof. To prove the lemma, it is enough to show that $\xi_{\text{leaf}}(\hat{A}) = 0$ for any Borel set $A \subset \mathbb{D}$ with $\xi(\hat{A}) = 0$, as sets of this form generate the $\sigma$-algebra of Borel subsets of $\hat{\mathbb{D}}$. From the definition of the measure $\xi$ given in Section 11, it is easy to see that one has \(\xi(\hat{A}) = 0\) if and only if \(A\) has 2-dimensional Lebesgue measure zero. As a result, we need to show that $\xi_{\text{leaf}}(\hat{A}) = 0$ for any measurable set $A \subset \mathbb{D}$ with 2-dimensional Lebesgue measure zero.

For this purpose, consider a chart $\hat{\mathcal{B}}_{\varepsilon, \text{L-good}}$ where $\mathcal{B} = B_{\text{hyp}}(z, \gamma)$. As the slice $(\hat{A} \cap \hat{\mathcal{B}}_{\varepsilon, \text{L-good}})_{z} \subset \mathbb{H}$ along any inverse orbit $z \in T(z)$ also has zero 2-dimensional Lebesgue measure, $\xi_{\text{leaf}}(\hat{A} \cap \hat{\mathcal{B}}_{\varepsilon, \text{L-good}}) = 0$. Since the chart $\hat{\mathcal{B}}_{\varepsilon, \text{L-good}}$ was arbitrary, $\xi_{\text{leaf}}(\hat{A}) = 0$ as desired.

For a measurable set $A$ contained in a ball $\mathcal{B} = B_{\text{hyp}}(z, \gamma)$, we write

$$\hat{A}_{\varepsilon, \text{L-good}} = \hat{A} \cap \hat{\mathcal{B}}_{\varepsilon, \text{L-good}}.$$ 

Perhaps, the main difficulty in showing that $\xi = \xi_{\text{leaf}}$ is that the measure $\xi$ was defined in terms of the “full” cylinders $\hat{A}$ while the measure $\xi_{\text{leaf}}$ is given in terms of the “partial” cylinders $\hat{A}_{\varepsilon, \text{L-good}}$. 65
In the following two lemmas, we evaluate $\xi(\hat{A}_{\varepsilon-L,\text{good}})$ and $\xi_{\text{leaf}}(\hat{A}_{\varepsilon-L,\text{good}})$ up to multiplicative error $\varepsilon$. As before, we use $A \sim_\varepsilon B$ to denote that

$$1 - C\varepsilon \leq A/B \leq 1 + C\varepsilon,$$

for some constant $C > 0$ depending only on the inner function $F$.

**Lemma C.4.** We have

$$\xi(\hat{A}_{\varepsilon-L,\text{good}}) = \lim_{n \to \infty} \sum_{\substack{w \in \varepsilon-L,\text{good} \cap F^{-n}(A) = z}} \int_{A_w} \log \frac{1}{|z|} \, dA_{\text{hyp}}$$

and

$$\sim_\varepsilon \tau_z(T_{\varepsilon-L,\text{good}}(z)) \int_A \log \frac{1}{|z|} \, dA_{\text{hyp}}.$$  

**(C.1)**

**(C.2)**

**Proof.** Step 1. We may write $F^{-j}(A) = G_j \cup B_j$, where $G_j$ is the union of the $\varepsilon$-(linear good) pre-images of $A$ of generation $j$ and $B_j$ be the union of the “bad” pre-images. Then,

$$\hat{A}_{\varepsilon-L,\text{good}} = \hat{A} \setminus \bigcup_{j=1}^\infty \hat{B}_j,$$

where we are slightly abusing notation by viewing $\hat{B}_j$ as a subset of $\hat{A}$. (We should really be writing $\hat{F}^{-j}(\hat{B}_j)$ in place of $\hat{B}_j$.) Consequently,

$$\hat{\xi}(\hat{A}_{\varepsilon-L,\text{good}}) = \xi(\hat{A}) - \sum_{j=1}^\infty \xi(\hat{B}_j).$$

Step 2. From the definition of the measure $\xi$ on the cylindrical sets $\hat{A}$ and $\hat{B}_j$ and Lemma 11.1, it follows that for any $n \in \mathbb{N}$, we have

$$\xi(\hat{A}) - \sum_{j=1}^n \xi(\hat{B}_j) \geq \sum_{w \in \varepsilon-L,\text{good} \cap F^{-n}(A) = z} \int_{A_w} \log \frac{1}{|z|} \, dA_{\text{hyp}},$$

where $A_w = F^{-n}(A) \cap B_w$ ranges over the $\varepsilon$-(linear good) pre-images of $A$ of generation $n$. In Section 11, we saw that the error

$$\text{Err}(n, \hat{A}) := \xi(\hat{A}) - \int_{F^{-n}(A)} \log \frac{1}{|z|} \, dA_{\text{hyp}}.$$
decreases to 0 as \( n \to \infty \). As \( \text{Err}(n, \hat{G}_n) \leq \text{Err}(n, \hat{A}) \),

\[
\xi(\hat{A}) - \sum_{j=1}^{n} \xi(\hat{B}_j) \leq \text{Err}(n, \hat{A}) + \sum_{w \in \mathcal{L}, \text{good}} \int_{A_w} \frac{1}{|z|} dA_{\text{hyp}},
\]

(C.4)

Taking \( n \to \infty \) in (C.3) and (C.4), we obtain (C.1).

**Step 3.** For \( j \geq 1 \), let \( T^{(j)}_{\varepsilon}(z) \subset T(z) \) denote the set of inverse orbits \( w \in T(z) \) which are \( \varepsilon \)-(linear good) for the first \( j \) steps, i.e. \( \hat{\delta}(w_{-j}, z) \leq \varepsilon \).

Since

\[
T_{\varepsilon}(z) = \bigcap_{n=1}^{\infty} T^{(n)}_{\varepsilon}(z)
\]

is a decreasing intersection, \( \mathcal{L}(T^{(n)}_{\varepsilon}(z)) \) decreases to \( \mathcal{L}(T_{\varepsilon}(z)) \). With this in mind, (C.2) follows from (C.1) and \( \varepsilon \)-linearity.

**Lemma C.5.** For a measurable set \( A \) contained in \( \mathcal{B} = B_{\text{hyp}}(z, \gamma) \),

\[
\xi_{\text{leaf}}(\hat{A}_{\varepsilon}, \text{good}) \sim \varepsilon \int_{A} \log \frac{1}{|z|} dA_{\text{hyp}}.
\]

**Proof.** The lemma follows from the definition of the measure \( \xi_{\text{leaf}} \) and \( \varepsilon \)-linearity.

With help of Theorem 12.2, one may express a cylinder set as a countable union of partial cylinders:

**Lemma C.6.** For any measurable set \( A \) in the unit disk and \( \varepsilon > 0 \), there exists countably many disjoint partial cylinders \( \hat{A}_{k, \varepsilon, \text{good}} \) which cover \( \hat{A} \) up to a set of \( \xi \) measure zero:

\[
\hat{A} = \bigcup_{k} \hat{A}_{k, \varepsilon, \text{good}} \sqcup N.
\]

We are now ready to show that the measures \( \xi \) and \( \xi_{\text{leaf}} \) are equal:

**Proof of Theorem C.1.** To show that the measures \( \xi \) and \( \xi_{\text{leaf}} \) are equal, it is enough to show that they agree on sets of the form \( \{ \hat{A} : A \subset \mathbb{D} \text{ Borel} \} \) as these generate the Borel \( \sigma \)-algebra of Borel subsets of \( \hat{\mathbb{D}} \). For a cylinder \( \hat{A} \subset \hat{\mathbb{D}} \), examine the decomposition given by Lemma C.6. As \( \xi_{\text{leaf}} \) is absolutely

67
continuous with respect to \( \xi \), we also have \( \xi_{\text{leaf}}(N) = 0 \). Lemmas C.4 and C.5 imply that

\[
\xi(\hat{A}_{k, \varepsilon-\text{good}}) \sim_{\varepsilon} \xi_{\text{leaf}}(\hat{A}_{k, \varepsilon-\text{good}})
\]

for any \( k \). Summing over \( k \) shows that \( \xi(\hat{A}) \sim_{\varepsilon} \xi_{\text{leaf}}(\hat{A}) \). Since \( \varepsilon > 0 \) was arbitrary, \( \xi(\hat{A}) = \xi_{\text{leaf}}(\hat{A}) \) as desired.

\[\Box\]

C.2 The case of \( \hat{S}^1 \)

We define a measure \( \hat{m}_{\text{leaf}} \) on the solenoid \( \hat{S}^1 \) so that its restriction to any "chart" \( \zeta(\hat{B}_{\varepsilon-\text{L}} - \text{good}) \subset \hat{S}^1 \) is given by

\[
\hat{m}_{\text{leaf}}(E) = \int_{T_{\varepsilon-\text{L}} - \text{good}(z)} \ell(E^*z)dc_z,
\]

while the set of points in the solenoid which are not contained in any chart have \( \hat{m}_{\text{leaf}} \) measure zero. As in the case of \( \xi_{\text{leaf}} \) considered previously, \( \hat{m}_{\text{leaf}} \) is a \( \sigma \)-finite \( \hat{F} \)-invariant measure. Our objective is to show:

**Theorem C.7.** The measures \( \hat{m}_{\text{leaf}} \) and \( \hat{m} \) on \( \hat{S}^1 \) are equal.

We begin by noticing:

**Lemma C.8.** The measure \( \hat{m}_{\text{leaf}} \) is absolutely continuous with respect to \( \hat{m} \).

The proof below uses Löwner’s lemma which says that if \( \varphi : (\mathbb{D}, a) \to (\mathbb{D}, b) \) is a holomorphic self-map of the unit disk then for any measurable set \( E \subset S^1 \),

\[
\omega_a(\varphi^{-1}(E)) \leq \omega_b(E),
\]

where \( \omega_a \) and \( \omega_b \) are harmonic measures on the unit circle as viewed from \( a \) and \( b \) respectively. Evidently, Löwner’s lemma also applies to maps between arbitrary simply-connected domains.

**Proof.** Let \( E \subset S^1 \) be a Borel set with \( m(E) = 0 \). Consider a chart \( \zeta(\hat{B}_{\varepsilon-\text{L}} - \text{good}) \) where \( \hat{B} = B_{\text{hyp}}(z, \gamma) \). For any inverse orbit \( z \in T_{\varepsilon-\text{L}} - \text{good}(z) \), we can apply Löwner’s lemma to the map \( F_{z,0} : (\mathbb{H}, i) \to (\mathbb{D}, z) \) to conclude that

\[
\ell((\hat{E} \cap \zeta(\hat{B}_{\varepsilon-\text{L}} - \text{good}))^*_z) = 0.
\]

As the chart \( \zeta(\hat{B}_{\varepsilon-\text{L}} - \text{good}) \) and inverse orbit \( z \in T_{\varepsilon-\text{L}} - \text{good}(z) \) were arbitrary, we have \( \hat{m}_{\text{leaf}}(\hat{E}) = 0 \).
Since \( \hat{m}_{\text{leaf}} \) is \( \tilde{F} \)-invariant and \( \hat{m} \) is ergodic, the above lemma tells us that:

**Corollary C.9.** The measure \( \hat{m}_{\text{leaf}} \) is finite. In fact, \( \hat{m}_{\text{leaf}} = c \cdot \hat{m} \) for some \( c \geq 0 \).

To complete the proof of Theorem C.7, it remains to show that \( c = 1 \). Unfortunately, we do not have a simple proof of this fact and the argument below is somewhat involved.

**Step 1.** We say that a trajectory of the geodesic flow \( \{ g_t(z) : t \in \mathbb{R} \} \) is *generic* if

\[
\lim_{t \to \infty} \frac{1}{t} \int_0^t \delta(F^n[g_{-s}(w)]) \, ds = 0, \quad \text{for any } n \in \mathbb{Z}.
\]

Let \( \mathcal{G}_0 \) be the set of generic trajectories. Recall that in Section 13.1, we used the ergodic theorem to show that \( \mathcal{G}_0 \) foliates \( \hat{\mathbb{D}} \) up to \( \xi \) measure zero. We also saw that under the backward geodesic flow, a generic trajectory lands on the solenoid.

We define the measure \( \hat{m}_{\text{gen}} \) as the restriction of \( \hat{m}_{\text{leaf}} \) to the set \( \zeta(\mathcal{G}_0) \) of landing points of generic trajectories. Since \( \mathcal{G}_0 \) is \( \tilde{F} \)-invariant (by definition), so are \( \zeta(\mathcal{G}_0) \) and \( \hat{m}_{\text{gen}} \). Notice that \( \hat{m}_{\text{leaf}} - \hat{m}_{\text{gen}} \perp \hat{m}_{\text{gen}} \) as the two measures are supported on different sets: \( \hat{m}_{\text{gen}} \) gives full mass to \( \zeta(\mathcal{G}_0) \), while \( \hat{m}_{\text{leaf}} - \hat{m}_{\text{gen}} \) gives full mass to \( \hat{S}^1 \setminus \zeta(\mathcal{G}_0) \).

**Lemma C.10.** The measure \( \hat{m}_{\text{gen}} \) is a probability measure.

Once we prove the above lemma, \( c = 1 \) follows almost immediately: As \( \hat{m} \) is ergodic and \( \hat{m}_{\text{gen}} \ll \hat{m} \), the two measures must be equal: \( \hat{m} = \hat{m}_{\text{gen}} \). As the difference \( \hat{m}_{\text{leaf}} - \hat{m}_{\text{gen}} \ll \hat{m} = \hat{m}_{\text{gen}} \), it must be zero. Hence, \( \hat{m} = \hat{m}_{\text{gen}} = \hat{m}_{\text{leaf}} \) as desired.

**Step 2.** For \( 0 < \varepsilon < 0.1 \), we define \( \mathcal{A}_\varepsilon \subset \hat{\mathbb{D}} \) as the set of inverse orbits \( w = (w_{-n})_{n=0}^\infty \) which satisfy the following three conditions:

1. \( \delta(w) < \varepsilon \).
2. For any \( t > 0 \), the hyperbolic distance \( d_\mathbb{D}(g_{-t}(z)_0, 0) > d_\mathbb{D}(z_0, 0) \).
3. The geodesic trajectory passing through \( w \) is generic.
For each $1 - \varepsilon/e^\gamma < r < 1$, we define the auxiliary measure

$$\hat{m}_{r,\varepsilon} = \hat{m}_{\text{leaf}}|_{\zeta(A_{r,\varepsilon})},$$

where $A_{r,\varepsilon} = A_\varepsilon \cap \{|z| = r\}$. From Condition 3, it is clear that

$$\hat{m}_{r,\varepsilon} \leq \hat{m}_{\text{gen}} \leq \hat{m}_{\text{leaf}}.$$

Recall from Section 3.1 that the set of points $z \in \mathbb{D}$ for which $\overline{c}_z$ is not a probability measure has logarithmic capacity zero. In particular, the intersection with any circle $\{|z| = r\}$ has zero 1-dimensional Lebesgue measure. The main difficulty towards proving Lemma C.10 is to show that the measures $\hat{m}_{r,\varepsilon}$ exhaust $\hat{m}_{\text{gen}}$ as $r \to 1$:

**Lemma C.11.** For any $0 < \varepsilon < 0.1$,

$$\lim_{r \to 1} \int_{|z| = r} \overline{c}_z(A_\varepsilon^c \cap T(z)) \, |dz| = 0. \quad \text{(C.5)}$$

We now explain how to derive Lemma C.10 (and Theorem C.7) from Lemma C.11. By Condition 2 above, for each non-exceptional $0 < r < 1$, $\zeta$ is injective on $A_{r,\varepsilon}$. By $\varepsilon$-linearity, the mass of $\hat{m}_{r,\varepsilon}$ is approximately

$$\hat{m}_{r,\varepsilon}(S^1) \sim \frac{1}{2\pi} \int_{|z| = r} \overline{c}_z(A_\varepsilon \cap T(z)) \, |dz|.$$

Together with Lemma C.11, this implies that

$$\hat{m}_{r,\varepsilon}(S^1) \sim \varepsilon 1. \quad \text{(C.6)}$$

Since any generic geodesic trajectory participates in “density 1” measures $\hat{m}_{s,\varepsilon}$, i.e.

$$\frac{1}{|\log(1 - r)|} \int_0^r \chi_{A_\varepsilon}(g_s(z)) \frac{ds}{s} \to 1, \quad \text{as } r \to 1,$$

we have:

**Lemma C.12.** For any $0 < \varepsilon < 0.1$,

$$\hat{m}_{\text{gen}} = \lim_{r \to 1} \frac{1}{|\log(1 - r)|} \int_0^r \hat{m}_{s,\varepsilon} \frac{ds}{s}, \quad \text{(C.7)}$$

in the sense of strong limits of measures.

Combining (C.6) and (C.7), we see that $\hat{m}_{\text{gen}}$ is a probability measure.
Step 3. By Lemmas 8.2 and 10.2, there exists a universal constant $0 < \gamma_0 < \gamma$ so that if $z \in \hat{D}$ is an inverse orbit with $\hat{\delta}(z) < 0.1$ then $\hat{\delta}(w) < 2\hat{\delta}(z) < 0.2$ for any inverse orbit $w \in \hat{B}_{\varepsilon-L, \text{good}}$ which follows $z$ with $d_D(z_0, w_0) < \gamma_0$. In particular,

$$d_D(g_{-t}(z)_{-n}, 0) > d_D(z_{-n}, 0), \quad t \in (0, \gamma_0] \quad \text{(C.8)}$$

and

$$d_D(g_{-\gamma_0}(z)_{-n}, 0) > d_D(z_{-n}, 0) + 0.8 \gamma_0, \quad \text{(C.9)}$$

for any $n \geq 0$.

We define the set $\tilde{A}_\varepsilon \subset A_\varepsilon \subset \hat{D}$, where Condition 2 is replaced with a slightly stronger condition $(2 + 2')$, where we additionally require

$2'$. For any $t > \gamma_0$, we have $d_D(0, g_{-t}(w)_0) > d_D(0, w_0) + \gamma_0/2$.

In view of the buffer provided by $(2')$, we have:

Lemma C.13. Suppose $0 < \varepsilon < 0.05$. There exists $0 < \gamma_1 < \gamma_0$ so that if $z \in \tilde{A}_\varepsilon$ then any generic orbit $z' \in \hat{B}_{\varepsilon-L, \text{good}}$ which follows $z$ with $d_D(z_0, z'_0) < \gamma_1$ belongs to $A_{2\varepsilon}$.

Step 4. The following lemma says that from some point on, almost every inverse orbit belongs to $\tilde{A}_\varepsilon$:

Lemma C.14. For $\xi$ a.e. inverse orbit $w \in \hat{D}$, there exists an $N(w) \geq 0$ such that $\hat{F}^{-n}(w) \in \tilde{A}_\varepsilon$ for all $n \geq N(w)$.

Proof. Recall that by Theorem 12.1, for $\xi$ a.e. inverse orbit, we have $\hat{\delta}(w) < \infty$ and therefore, $\hat{\delta}(\hat{F}^{-n}(w)) \to 0$ as $n \to \infty$. Consequently, for $n$ sufficiently large, $\hat{\delta}(\hat{F}^{-n}(w)) < \varepsilon$ and Condition 1 holds.

Condition 3 is also easy to check since $\xi$ a.e. inverse orbit is generic and the property of an inverse orbit belonging to a generic trajectory is $\hat{F}$-invariant by definition.

To verify Condition $(2 + 2')$, we examine three cases:

1. For $t \in (0, \gamma_0]$. Condition $2'$ for $\hat{F}^{-n}(w)$ follows from Condition 1 for $\hat{F}^{-n}(w)$ and (C.8).
2. By the definition of a generic trajectory, there exists a $T = T(w) > 0$ sufficiently large so that
\[
\frac{1}{t} \int_0^t \tilde{\delta}(g_{-s}(w)) ds < 1/2, \quad t > T.
\]
As a result, for $t > T$, we have
\[
d_D(0, g^{-t}(w)) > d_D(0, g_0(w)) + t/2.
\]
3. Finally, to handle the case when $t \in [\gamma_0, T]$, we use that the sequence of functions
\[
\Delta_n(t) = \tilde{\delta}(\tilde{F}^{-n}[g^{-t}(w)]) = \sum_{k=n+1}^{\infty} \delta(g^{-t}(w))_{-k},
\]
decreases pointwise to 0.

The proof is complete. \qed

For an inverse orbit $w = (w_n)_{n=-\infty}^{\infty} \in \hat{D}$ and $0 < r < 1$, we write $w_r$ for the last point of the orbit that lies in the annulus $A(0; r, 1)$, that is, $w_r = w_n(r)$ where $n(r) \in \mathbb{Z}$ is the largest integer for which $w_n(r) \in A(0; r, 1)$. One may interpret Lemma (C.14) as saying that
\[
\int_{\hat{X}} \chi_{\{w_r \in \tilde{A}\epsilon\}} d\xi(w) \to 0, \quad \text{as } r \to 1.
\] (C.10)

With the above preparations, we are now ready to prove Lemma (C.11).

**Proof of Lemma (C.11)**. Suppose that one could find a sequence of $r$’s tending to 1 so that
\[
\int_{|z|=r} \tilde{e}_z(A^\epsilon_c \cap T(z)) |dz| \geq \delta,
\]
for some $\delta > 0$. By Lemma (C.13), we would also have
\[
\int_{|z|=s} \tilde{e}_z(A^\epsilon_c \cap T(z)) |dz| \geq \delta,
\]
for any $0 < s < 1$ with $d_D(r, s) < \gamma_1/2$. Consequently,
\[
\frac{1}{\gamma_0} \int_A \tilde{e}_z(A^\epsilon_c \cap T(z)) \cdot \frac{2dA(z)}{1 - |z|^2} \geq \delta, \quad \text{(C.11)}
\]
where $A = \{z \in \hat{D} : d_D(|z|, r) < \gamma_1/2\}$ is an annulus of hyperbolic width $\gamma_1$. Since we requested that $\gamma_1 < \gamma$, the quotient map $\pi : \hat{D} \to \hat{X}$ is injective on $\hat{A}$ and (C.11) contradicts (C.10) if $r$ is sufficiently close to 1. \qed
Acknowledgements

The authors wish to thank Mikhail Lyubich for bringing the work of Glutsyuk to our attention. This research was supported by the Israeli Science Foundation (grant no. 3134/21) and the Simons Foundation (grant no. 581668).

References


