

# Inner Regularization of Log-Concave Measures and Small-Ball Estimates

Bo'az Klartag<sup>1</sup> and Emanuel Milman<sup>2</sup>

## Abstract

In the study of concentration properties of isotropic log-concave measures, it is often useful to first ensure that the measure has super-Gaussian marginals. To this end, a standard preprocessing step is to convolve with a Gaussian measure, but this has the disadvantage of destroying small-ball information. We propose an alternative preprocessing step for making the measure seem super-Gaussian, at least up to reasonably high moments, which does not suffer from this caveat: namely, convolving the measure with a random orthogonal image of itself. As an application of this “inner-thickening”, we recover Paouris’ small-ball estimates.

## 1 Introduction

Fix a Euclidean norm  $|\cdot|$  on  $\mathbb{R}^n$ , and let  $X$  denote an isotropic random vector in  $\mathbb{R}^n$  with log-concave density  $g$ . Recall that a random vector  $X$  in  $\mathbb{R}^n$  (and its density) is called isotropic if  $\mathbb{E}X = 0$  and  $\mathbb{E}X \otimes X = Id$ , i.e. its barycenter is at the origin and its covariance matrix is equal to the identity one. Taking traces, we observe that  $\mathbb{E}|X|^2 = n$ . Here and throughout we use  $\mathbb{E}$  to denote expectation and  $\mathbb{P}$  to denote probability. A function  $g : \mathbb{R}^n \rightarrow \mathbb{R}_+$  is called log-concave if  $-\log g : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$  is convex. Throughout this work,  $C, c, c_2, C'$ , etc. denote universal positive numeric constants, independent of any other parameter and in particular the dimension  $n$ , whose value may change from one occurrence to the next.

Any high-dimensional probability distribution which is absolutely continuous has at least one super-Gaussian marginal (e.g. [13]). Still, in the study of concentration properties of  $X$  as above, it is many times advantageous to know that *all* of the one-dimensional marginals of  $X$  are super-Gaussian, at least up to some level (see e.g. [24, 9, 14]). By this we mean that for some  $p_0 \geq 2$ :

$$\forall 2 \leq p \leq p_0 \quad \forall \theta \in S^{n-1} \quad (E|\langle X, \theta \rangle|^p)^{\frac{1}{p}} \geq c(E|G_1|^p)^{\frac{1}{p}}, \quad (1.1)$$

<sup>1</sup>School of Mathematical Sciences, Tel-Aviv University, Tel Aviv 69978, Israel. Supported in part by the Israel Science Foundation and by a Marie Curie Reintegration Grant from the Commission of the European Communities. Email: klartagb@tau.ac.il

<sup>2</sup>Department of Mathematics, Technion - Israel Institute of Technology, Haifa 32000, Israel. Supported by ISF, GIF, the Taub Foundation (Landau Fellow) and the E. and J. Bishop Research Fund. Email: emilman@tx.technion.ac.il.

where  $G_1$  denotes a one-dimensional standard Gaussian random variable and  $S^{n-1}$  is the Euclidean unit sphere in  $\mathbb{R}^n$ . It is convenient to reformulate this using the language of  $L_p$ -centroid bodies, which were introduced by E. Lutwak and G. Zhang in [16] (under a different normalization). Given a random vector  $X$  with density  $g$  on  $\mathbb{R}^n$  and  $p \geq 1$ , the  $L_p$ -centroid body  $Z_p(X) = Z_p(g) \subset \mathbb{R}^n$  is the convex set defined via its support functional  $h_{Z_p(X)}$  by:

$$h_{Z_p(X)}(y) = \left( \int_{\mathbb{R}^n} |\langle x, y \rangle|^p g(x) dx \right)^{1/p}, \quad y \in \mathbb{R}^n.$$

More generally, the *one-sided*  $L_p$ -centroid body, denoted  $Z_p^+(X)$ , was defined in [9] (cf. [10]) by:

$$h_{Z_p^+(X)}(y) = \left( 2 \int_{\mathbb{R}^n} \langle x, y \rangle_+^p g(x) dx \right)^{1/p}, \quad y \in \mathbb{R}^n,$$

where as usual  $a_+ := \max(a, 0)$ . Note that when  $g$  is even then both definitions above coincide, and that when the barycenter of  $X$  is at the origin,  $Z_2(X)$  is the Euclidean ball  $B_2^n$  if and only if  $X$  is isotropic. Observing that the right-hand side of (1.1) is of the order of  $\sqrt{p}$ , we would like to have:

$$\forall 2 \leq p \leq p_0 \quad Z_p^+(X) \supset c\sqrt{p}B_2^n, \quad (1.2)$$

where  $B_2^n = \{x \in \mathbb{R}^n; |x| \leq 1\}$  is the unit Euclidean ball.

Unfortunately, we cannot in general expect to satisfy (1.2) for  $p_0$  which grows with the dimension  $n$ . This is witnessed by  $X$  which is uniformly distributed on the  $n$ -dimensional cube  $[-\sqrt{3}, \sqrt{3}]^n$  (the normalization ensures that  $X$  is isotropic), whose marginals in the directions of the axes are uniform on a constant-sized interval. Consequently, some preprocessing on  $X$  is required, which on one hand transforms it into another random variable  $Y$  whose density  $g$  satisfies (1.2), and on the other enables deducing back the desired concentration properties of  $X$  from those of  $Y$ .

A very common such construction is to convolve with a Gaussian, i.e. define  $Y := (X + G_n)/\sqrt{2}$ , where  $G_n$  denotes an independent standard Gaussian random vector in  $\mathbb{R}^n$ . In [11] (and in subsequent works like [12, 5]), the Gaussian played more of a regularizing role, but in [9], its purpose was to “thicken from inside” the distribution of  $X$ , ensuring that (1.2) is satisfied for all  $p \geq 2$  (see [9, Lemma 2.3]). Regarding the transference of concentration properties, it follows from the argument in the proof of [11, Proposition 4.1] that:

$$\mathbb{P}(|X| \geq (1+t)\sqrt{n}) \leq C\mathbb{P}\left(|Y| \geq \sqrt{\frac{(1+t)^2 + 1}{2}}\sqrt{n}\right) \quad \forall t \geq 0, \quad (1.3)$$

and:

$$\mathbb{P}(|X| \leq (1-t)\sqrt{n}) \leq C\mathbb{P}\left(|Y| \leq \sqrt{\frac{(1-t)^2 + 1}{2}}\sqrt{n}\right) \quad \forall t \in [0, 1], \quad (1.4)$$

for some universal constant  $C > 1$ . The estimate (1.3) is perfectly satisfactory for transferring (after an adjustment of constants) deviation estimates above the expectation from  $|Y|$  to  $|X|$ . However, note that the right-hand side of (1.4) is bounded below by  $P(|Y| \leq \sqrt{n/2})$  (and in particular does not decay to 0 when  $t \rightarrow 1$ ), and so (1.4) is meaningless for transferring *small-ball* estimates from  $|Y|$  to  $|X|$ . Consequently, the strategies employed in [11, 12, 5, 9] did not and could not deduce the concentration properties of  $|X|$  in the small-ball regime. This seems an inherent problem of adding an independent Gaussian: small-ball information is lost due to the “Gaussian-thickening”.

The purpose of this note is to introduce a different inner-thickening step, which does not have the above mentioned drawback. Before formulating it, recall that  $X$  (or its density) is said to be “ $\psi_\alpha$  with constant  $D > 0$ ” if:

$$Z_p(X) \subset Dp^{1/\alpha}Z_2(X) \quad \forall p \geq 2. \quad (1.5)$$

We will simply say that “ $X$  is  $\psi_\alpha$ ”, if it is  $\psi_\alpha$  with constant  $D \leq C$ , and not specify explicitly the dependence of the estimates on the parameter  $D$ . By a result of Berwald [1] (or applying Borell’s Lemma [3] as in [21, Appendix III]), it is well known that any  $X$  with log-concave density satisfies:

$$1 \leq p \leq q \quad \Rightarrow \quad Z_p(X) \subset Z_q(X) \subset C \frac{q}{p} Z_p(X). \quad (1.6)$$

In particular, such an  $X$  is always  $\psi_1$  with some universal constant, and so we only gain additional information when  $\alpha > 1$ .

**Theorem 1.1.** *Let  $X$  denote an isotropic random vector in  $\mathbb{R}^n$  with a log-concave density, which is in addition  $\psi_\alpha$  ( $\alpha \in [1, 2]$ ), and let  $X'$  denote an independent copy of  $X$ . Given  $U \in O(n)$ , the group of orthogonal linear maps in  $\mathbb{R}^n$ , denote:*

$$Y_\pm^U := \frac{X \pm U(X')}{\sqrt{2}}.$$

*Then:*

1. *For any  $U \in O(n)$ , the concentration properties of  $|Y_\pm^U|$  are transferred to  $|X|$  as follows:*

$$P(|X| \geq (1+t)\sqrt{n}) \leq (2 \max(P(|Y_+^U| \geq (1+t)\sqrt{n}), P(|Y_-^U| \geq (1+t)\sqrt{n})))^{1/2} \quad \forall t \geq 0,$$

*and:*

$$P(|X| \leq (1-t)\sqrt{n}) \leq (2 \max(P(|Y_+^U| \leq (1-t)\sqrt{n}), P(|Y_-^U| \leq (1-t)\sqrt{n})))^{1/2} \quad \forall t \in [0, 1].$$

2. *For any  $U \in O(n)$ :*

$$Z_p^+(Y_\pm^U) \subset Cp^{1/\alpha}B_2^n \quad \forall p \geq 2. \quad (1.7)$$

3. There exists a subset  $A \subset O(n)$  with:

$$\mu_{O(n)}(A) \geq 1 - \exp(-cn) ,$$

where  $\mu_{O(n)}$  denotes the Haar measure on  $O(n)$  normalized to have total mass 1, so that if  $U \in A$  then:

$$Z_p^+(Y_\pm^U) \supset c_1 \sqrt{p} B_2^n \quad \forall p \in [2, c_2 n^{\frac{\alpha}{2}}] . \quad (1.8)$$

**Remark 1.2.** Note that when the density of  $X$  is even, then  $Y_+^U$  and  $Y_-^U$  in Theorem 1.1 are identically distributed, which renders the formulation of the conclusion more natural. However, we do not know how to make the formulation simpler in the non-even case.

**Remark 1.3.** Also note that  $Y_\pm^U$  are isotropic random vectors, and that by the Prékopa–Leindler Theorem (e.g. [7]), they have log-concave densities.

As our main application, we manage to extend the strategy in the second named author’s previous work with O. Guédon [9] to the small-ball regime, and obtain:

**Corollary 1.4.** *Let  $X$  denote an isotropic random vector in  $\mathbb{R}^n$  with log-concave density, which is in addition  $\psi_\alpha$  ( $\alpha \in [1, 2]$ ). Then:*

$$\mathbb{P}(|X| - \sqrt{n} \geq t\sqrt{n}) \leq C \exp(-cn^{\frac{\alpha}{2}} \min(t^{2+\alpha}, t)) \quad \forall t \geq 0 , \quad (1.9)$$

and:

$$\mathbb{P}(|X| \leq \varepsilon\sqrt{n}) \leq (C\varepsilon)^{cn^{\frac{\alpha}{2}}} \quad \forall \varepsilon \in [0, 1/C] . \quad (1.10)$$

Corollary 1.4 is an immediate consequence of Theorem 1.1 and the following result, which is the content of [9, Theorem 4.1] (our formulation below is slightly more general, but this is what the proof gives):

**Theorem** (Guédon–Milman). *Let  $Y$  denote an isotropic random vector in  $\mathbb{R}^n$  with a log-concave density, so that in addition:*

$$c_1 \sqrt{p} B_2^n \subset Z_p^+(Y) \subset c_2 p^{1/\alpha} B_2^n \quad \forall p \in [2, c_3 n^{\frac{\alpha}{2}}] , \quad (1.11)$$

for some  $\alpha \in [1, 2]$ . Then (1.9) and (1.10) hold with  $X = Y$  (and perhaps different constants  $C, c > 0$ ).

We thus obtain a preprocessing step which fuses perfectly with the approach in [9], allowing us to treat all deviation regimes *simultaneously* in a single unified framework. We point out that Corollary 1.4 by itself is not new. The *large* positive-deviation estimate:

$$P(|X| \geq (1+t)\sqrt{n}) \leq \exp(-cn^{\frac{\alpha}{2}} t) \quad \forall t \geq C ,$$

was first obtained by G. Paouris in [22]; it is known to be sharp, up to the value of the constants. The more general deviation estimate (1.9) was obtained in [9], improving

when  $t \in [0, C]$  all previously known results due to the first named author and to Fleury [11, 12, 5] (we refer to [9] for a more detailed account of these previous estimates). In that work, the convolution with Gaussian preprocessing was used, and so it was not possible to independently deduce the small-ball estimate (1.10). The latter estimate was first obtained by Paouris in [23], using the reverse Blaschke–Santaló inequality of J. Bourgain and V. Milman [4]. In comparison, our main tool in the proof of Theorem 1.1 is a covering argument in the spirit of V. Milman’s M-position [17, 19, 18] (see also [25]), together with a recent lower-bound on the volume of  $Z_p$  bodies obtained in our previous joint work [14].

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## 2 Key Proposition

In this section, we prove the following key proposition:

**Proposition 2.1.** *Let  $X, X'$  be as in Theorem 1.1, let  $U$  be uniformly distributed on  $O(n)$ , and set:*

$$Y := \frac{X + U(X')}{\sqrt{2}} .$$

*Then there exists a  $c > 0$ , so that:*

$$\forall C_1 > 0 \quad \exists c_1 > 0 \quad \forall p \in [2, cn^{\alpha/2}] \quad \mathbb{P}(Z_p^+(Y) \supset c_1 \sqrt{p} B_2^n) \geq 1 - \exp(-C_1 n) .$$

Here, as elsewhere, “uniformly distributed on  $O(n)$ ” is with respect to the probability measure  $\mu_{O(n)}$ .

We begin with the following estimate due to Grünbaum [8] (see also [6, Formula (10)] or [2, Lemma 3.3] for simplified proofs):

**Lemma 2.2** (Grünbaum). *Let  $X_1$  denote a random variable on  $\mathbb{R}$  with log-concave density and barycenter at the origin. Then  $\frac{1}{e} \leq \mathbb{P}(X_1 \geq 0) \leq 1 - \frac{1}{e}$ .*

Recall that the Minkowski sum  $K + L$  of two compact sets  $K, L \subset \mathbb{R}^n$  is defined as the compact set given by  $\{x + y; x \in K, y \in L\}$ . When  $K, L$  are convex, the support functional satisfies  $h_{K+L} = h_K + h_L$ .

**Lemma 2.3.** *With the same notations as in Proposition 2.1:*

$$Z_p^+(Y) \supset \frac{1}{2\sqrt{2}e^{1/p}} (Z_p^+(X) + U(Z_p^+(X))) .$$

*Proof.* Given  $\theta \in S^{n-1}$ , denote  $Y_1 = \langle Y, \theta \rangle$ ,  $X_1 = \langle X, \theta \rangle$  and  $X'_1 = \langle U(X'), \theta \rangle$ . By the Prékopa–Leindler theorem (e.g. [7]), all these one-dimensional random variables have log-concave densities, and since their barycenter is at the origin, we obtain by Lemma 2.2:

$$h_{Z_p^+(Y)}^p(\theta) = 2\mathbb{E}(Y_1)_+^p = \frac{2}{2^{p/2}} \mathbb{E}(X_1 + X'_1)_+^p \geq \frac{2}{2^{p/2}} \mathbb{E}(X_1)_+^p \mathbb{P}(X'_1 \geq 0) \geq \frac{2}{e2^{p/2}} \mathbb{E}(X_1)_+^p .$$

Exchanging the roles of  $X_1$  and  $X'_1$  above, we obtain:

$$h_{Z_p^+(Y)}^p(\theta) \geq \frac{1}{e^{2p/2}} \max \left( h_{Z_p^+(X)}^p(\theta), h_{Z_p^+(U(X'))}^p(\theta) \right) .$$

Consequently:

$$h_{Z_p^+(Y)}(\theta) \geq \frac{1}{\sqrt{2}e^{1/p}} \frac{h_{Z_p^+(X)}(\theta) + h_{Z_p^+(U(X'))}(\theta)}{2} ,$$

and since  $Z_p^+(U(X')) = U(Z_p^+(X')) = U(Z_p^+(X))$ , the assertion follows.  $\square$

Next, recall that given two compact subsets  $K, L \subset \mathbb{R}^n$ , the covering number  $N(K, L)$  is defined as the minimum number of translates of  $L$  required to cover  $K$ . The volume-radius of a compact set  $K \subset \mathbb{R}^n$  is defined as:

$$\text{V.Rad.}(K) = \left( \frac{\text{Vol}(K)}{\text{Vol}(B_2^n)} \right)^{\frac{1}{n}} ,$$

measuring the radius of the Euclidean ball whose volume equals the volume of  $K$ . A convex compact set with non-empty interior is called a convex body, and given a convex body  $K$  with the origin in its interior, its polar  $K^\circ$  is the convex body given by:

$$K^\circ := \{y \in \mathbb{R}^n; \langle x, y \rangle \leq 1 \quad \forall x \in K\} .$$

Finally, the mean-width of a convex body  $K$ , denoted  $W(K)$ , is defined as  $W(K) = 2 \int_{S^{n-1}} h_K(\theta) d\mu_{S^{n-1}}(\theta)$ , where  $\mu_{S^{n-1}}$  denotes the Haar probability measure on  $S^{n-1}$ . The following two lemmas are certainly well-known; we provide a proof for completeness.

**Lemma 2.4.** *Let  $K \subset \mathbb{R}^n$  be a convex body with barycenter at the origin, so that:*

$$N(K, B_2^n) \leq \exp(A_1 n) \quad \text{and} \quad \text{V.Rad.}(K) \geq a_1 > 0 .$$

*Then:*

$$N(K^\circ, B_2^n) \leq \exp(A_2 n) ,$$

*where  $A_2 \leq A_1 + \log(C/a_1)$ , and  $C > 0$  is a universal constant.*

*Proof.* Set  $K_s = K \cap -K$ . By the covering estimate of H. König and V. Milman [15], it follows that:

$$N(K^\circ, B_2^n) \leq N(K_s^\circ, B_2^n) \leq C^n N(B_2^n, K_s) .$$

Using standard volumetric covering estimates (e.g. [25, Chapter 7]), we deduce:

$$N(K^\circ, B_2^n) \leq C^n \left( \frac{\text{Vol}(B_2^n + K_s/2)}{\text{Vol}(K_s/2)} \right) \leq C^n N(K_s/2, B_2^n) \frac{\text{Vol}(2B_2^n)}{\text{Vol}(K_s/2)} .$$

By a result of V. Milman and A. Pajor [20], it is known that  $\text{Vol}(K_s) \geq 2^{-n} \text{Vol}(K)$ , and hence:

$$N(K^\circ, B_2^n) \leq (8C)^n N(K, B_2^n) \text{V.Rad.}(K)^{-n} \leq (8C/a_1)^n \exp(A_1 n) ,$$

as required.  $\square$

**Lemma 2.5.** *Let  $L$  denote any compact set in  $\mathbb{R}^n$  ( $n \geq 2$ ), so that  $N(L, B_2^n) \leq \exp(A_1 n)$ . If  $U$  is uniformly distributed on  $O(n)$ , then:*

$$P(L \cap U(L) \subset A_3 B_2^n) \geq 1 - \exp(-A_2 n) ,$$

where  $A_2 = A_1 + (\log 2)/2$  and  $A_3 = C' \exp(6A_1)$ , for some universal constant  $C' > 0$ .

*Proof Sketch.* Assume that  $L \subset \cup_{i=1}^{\exp(A_1 n)} (x_i + B_2^n)$ . Set  $R = 4C \exp(6A_1)$ , for some large enough constant  $C > 0$ , and without loss of generality, assume that among all translates  $\{x_i\}, \{x_i\}_{i=1}^N$  are precisely those points lying outside of  $RB_2^n$ . Observe that for each  $i = 1, \dots, N$ , the cone  $\{t(x_i + B_2^n); t \geq 0\}$  carves a spherical cap of Euclidean radius at most  $1/R$  on  $S^{n-1}$ . By the invariance of the Haar measures on  $S^{n-1}$  and  $O(n)$  under the action of  $O(n)$ , it follows that for every  $i, j \in \{1, \dots, N\}$ :

$$P(U(x_i + B_2^n) \cap (x_j + B_2^n) \neq \emptyset) \leq \mu_{S^{n-1}}(B_{2/R}) ,$$

where  $B_\varepsilon$  denotes a spherical cap on  $S^{n-1}$  of Euclidean radius  $\varepsilon$ , and recall  $\mu_{S^{n-1}}$  denotes the normalized Haar measure on  $S^{n-1}$ . When  $\varepsilon < 1/(2C)$ , it is easy to verify that:

$$\mu_{S^{n-1}}(B_\varepsilon) \leq (C\varepsilon)^{n-1} ,$$

and so it follows by the union-bound that:

$$P(L \cap U(L) \subset (R+1)B_2^n) \geq P(\forall i, j \in \{1, \dots, N\} \quad U(x_i + B_2^n) \cap (x_j + B_2^n) = \emptyset) \geq 1 - N^2 (2C/R)^{n-1} .$$

Since  $N \leq \exp(2A_1(n-1))$ , our choice of  $R$  yields the desired assertion with  $C' = 5C$ .  $\square$

It is also useful to state:

**Lemma 2.6.** *For any density  $g$  on  $\mathbb{R}^n$  and  $p \geq 1$ :*

$$Z_p^+(g) \subset 2^{1/p} Z_p(g) \subset Z_p^+(g) - Z_p^+(g) . \quad (2.1)$$

*Proof.* The first inclusion is trivial. The second follows since  $a^{1/p} + b^{1/p} \geq (a+b)^{1/p}$  for  $a, b \geq 0$ , and hence for all  $\theta \in S^{n-1}$ :

$$h_{Z_p^+(g) - Z_p^+(g)}(\theta) = h_{Z_p^+(g)}(\theta) + h_{Z_p^+(g)}(-\theta) \geq 2^{1/p} h_{Z_p(g)}(\theta) .$$

$\square$

The next two theorems play a crucial role in our argument. The first is due to Paouris [22], and the second to the authors [14]:

**Theorem (Paouris).** *With the same assumptions as in Theorem 1.1:*

$$W(Z_p(X)) \leq C\sqrt{p} \quad \forall p \in [2, cn^{\alpha/2}] . \quad (2.2)$$

**Theorem** (Klartag–Milman). *With the same assumptions as in Theorem 1.1:*

$$V.\text{Rad.}(Z_p(X)) \geq c\sqrt{p} \quad \forall p \in [2, cn^{\alpha/2}] . \quad (2.3)$$

We are finally ready to provide a proof of Proposition 2.1:

*Proof of Proposition 2.1.* Let  $p \in [2, cn^{\alpha/2}]$ , where  $c > 0$  is some small enough constant so that (2.2) and (2.3) hold. We will ensure that  $c \leq 1$ , so there is nothing to prove if  $n = 1$ . By (2.1), Sudakov’s entropy estimate (e.g. [25]) and (2.2), we have:

$$N(Z_p^+(X)/\sqrt{p}, B_2^n) \leq N(2^{1/p}Z_p(X)/\sqrt{p}, B_2^n) \leq \exp(\tilde{C}nW(2^{1/p}Z_p(X)/\sqrt{p})^2) \leq \exp(Cn) . \quad (2.4)$$

Note that by (2.1) and the Rogers–Shephard inequality [26], we have:

$$2^{n/p}\text{Vol}(Z_p(X)) \leq \text{Vol}(Z_p^+(X) - Z_p^+(X)) \leq 4^n \text{Vol}(Z_p^+(X)) .$$

Consequently, the volume bound in (2.3) also applies to  $Z_p^+(X)$ :

$$V.\text{Rad.}(Z_p^+(X)) \geq c_1\sqrt{p} . \quad (2.5)$$

By Lemma 2.4, (2.4) and (2.5) imply that:

$$N(\sqrt{p}(Z_p^+(X))^\circ, B_2^n) \leq \exp(C_2n) .$$

Consequently, Lemma 2.5 implies that if  $U$  is uniformly distributed on  $O(n)$ , then for any  $C_1 \geq C_2 + (\log 2)/2$ , there exists a  $C_3 > 0$ , so that:

$$\mathbb{P} \left( Z_p^+(X)^\circ \cap U(Z_p^+(X)^\circ) \subset \frac{C_3}{\sqrt{p}}B_2^n \right) \geq 1 - \exp(-C_1n) ,$$

or by duality (since  $T(K)^\circ = (T^{-1})^*(K^\circ)$  for any linear map  $T$  of full rank), that:

$$\begin{aligned} & \mathbb{P} (Z_p^+(X) + U(Z_p^+(X)) \supset C_3^{-1}\sqrt{p}B_2^n) \\ & \geq \mathbb{P} (\text{conv}(Z_p^+(X) \cup U(Z_p^+(X))) \supset C_3^{-1}\sqrt{p}B_2^n) \geq 1 - \exp(-C_1n) . \end{aligned}$$

Lemma 2.3 now concludes the proof. □

### 3 Remaining Details

We now complete the remaining (standard) details in the proof of Theorem 1.1.

*Proof of Theorem 1.1.*



1. For any  $U \in O(n)$  and  $t \geq 0$ , observe that:

$$\begin{aligned}
& 2 \max \left( \mathbb{P} \left( \left| \frac{X + U(X')}{\sqrt{2}} \right| \leq t \right), \mathbb{P} \left( \left| \frac{X - U(X')}{\sqrt{2}} \right| \leq t \right) \right) \\
& \geq \mathbb{P} \left( \left| \frac{X + U(X')}{\sqrt{2}} \right| \leq t \right) + \mathbb{P} \left( \left| \frac{X - U(X')}{\sqrt{2}} \right| \leq t \right) \\
& = \mathbb{P} \left( \frac{|X|^2 + |X'|^2}{2} + \langle X, U(X') \rangle \leq t^2 \right) + \mathbb{P} \left( \frac{|X|^2 + |X'|^2}{2} - \langle X, U(X') \rangle \leq t^2 \right) \\
& \geq \mathbb{P} (|X| \leq t \text{ and } |X'| \leq t \text{ and } \langle X, U(X') \rangle \leq 0) \\
& \quad + \mathbb{P} (|X| \leq t \text{ and } |X'| \leq t \text{ and } \langle X, U(X') \rangle > 0) \\
& = \mathbb{P} (|X| \leq t \text{ and } |X'| \leq t) = \mathbb{P} (|X| \leq t)^2 .
\end{aligned}$$

Similarly:

$$2 \max \left( \mathbb{P} \left( \left| \frac{X + U(X')}{\sqrt{2}} \right| \geq t \right), \mathbb{P} \left( \left| \frac{X - U(X')}{\sqrt{2}} \right| \geq t \right) \right) \geq \mathbb{P} (|X| \geq t)^2 .$$

This is precisely the content of the first assertion of Theorem 1.1.

2. Given  $\theta \in S^{n-1}$ , denote  $Y_1 = P_\theta Y_+^U$ ,  $X_1 = P_\theta X$  and  $X_2 = P_\theta U(X')$ , where  $P_\theta$  denotes orthogonal projection onto the one-dimensional subspace spanned by  $\theta$ . We have:

$$\begin{aligned}
h_{Z_p(Y_+^U)}(\theta) &= (\mathbb{E}|Y_1|^p)^{\frac{1}{p}} = \left( \mathbb{E} \left| \frac{X_1 + X_2}{\sqrt{2}} \right|^p \right)^{\frac{1}{p}} \\
&\leq \frac{1}{\sqrt{2}} \left( (\mathbb{E}|X_1|^p)^{\frac{1}{p}} + (\mathbb{E}|X_2|^p)^{\frac{1}{p}} \right) = \frac{1}{\sqrt{2}} (h_{Z_p(X)}(\theta) + h_{Z_p(U(X'))}(\theta)) .
\end{aligned}$$

Employing in addition (2.1), it follows that:

$$Z_p^+(Y_+^U) \subset 2^{1/p} Z_p(Y_+^U) \subset \frac{2^{1/p}}{\sqrt{2}} (Z_p(X) + U(Z_p(X))) ,$$

and the second assertion for  $Y_+^U$  follows since  $Z_p(X) \subset Cp^{\frac{1}{\alpha}} B_2^n$  by assumption. Similarly for  $Y_-^U$ .

3. Given a natural number  $i$ , set  $p_i = 2^i$ . Proposition 2.1 ensures the existence of a constant  $c > 0$ , so that for any  $C_1 > 0$ , there exists a constant  $c_1 > 0$ , so that for any  $p_i \in [2, cn^{\frac{\alpha}{2}}]$ , there exists a subset  $A_i \subset O(n)$  with:

$$\mu_{O(n)}(A_i) \geq 1 - \exp(-C_1 n) ,$$

so that:

$$\forall U \in A_i \quad Z_{p_i}(Y_+^U) \supset c_1 \sqrt{p_i} B_2^n .$$

Denoting  $A_0 := \cap \left\{ A_i ; p_i \in [2, cn^{\frac{\alpha}{2}}] \right\}$ , and setting  $A = A_0 \cap -A_0$ , where  $-A_0 := \{-U \in O(n); U \in A_0\}$ , it follows by the union-bound that:

$$\mu_{O(n)}(A) \geq 1 - 2 \log(C_2 + n) \exp(-C_1 n) .$$

By choosing the constant  $C_1 > 0$  large enough, we conclude that:

$$\mu_{O(n)}(A) \geq 1 - \exp(-C_3 n) .$$

By construction, the set  $A$  has the property that:

$$\forall U \in A \quad \forall p_i \in [2, cn^{\frac{\alpha}{2}}] \quad Z_{p_i}(Y_{\pm}^U) \supset c_1 \sqrt{p_i} B_2^n .$$

Using (1.6), it follows that:

$$\forall U \in A \quad \forall p \in [2, cn^{\frac{\alpha}{2}}] \quad Z_p(Y_{\pm}^U) \supset \frac{c_1}{\sqrt{2}} \sqrt{p} B_2^n ,$$

thereby concluding the proof of the third assertion. □

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