The phase transition in random graphs – a simple proof

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Abstract

The classical result of Erdős and Rényi asserts that the random graph G(n,p) experiences sharp phase transition around $p = \frac{1}{n}$ – for any $\epsilon > 0$ and $p = \frac{1-\epsilon}{n}$, all connected components of G(n,p) are typically of size $O_{\epsilon}(\log n)$, while for $p = \frac{1+\epsilon}{n}$, with high probability there exists a connected component of size linear in n. We provide a very simple proof of this fundamental result; in fact, we prove that in the supercritical regime $p = \frac{1+\epsilon}{n}$, the random graph G(n,p)contains typically a path of linear length. We also discuss applications of our technique to other random graph models and to positional games.

1 Introduction

In their groundbreaking paper [8] from 1960, Paul Erdős and Alfréd Rényi made the following fundamental discovery: the random graph G(n, p) undergoes a remarkable phase transition around the edge probability $p(n) = \frac{1}{n}$. For any constant $\epsilon > 0$, if $p = \frac{1-\epsilon}{n}$, then G(n, p) has \mathbf{whp}^1 all connected components of size at most logarithmic in n, while for $p = \frac{1+\epsilon}{n}$ whp a connected component of linear size, usually called the giant component, emerges in G(n, p) (they also showed that whp there is a unique linear sized component). The Erdős-Rényi paper, which launched the modern theory of random graphs, has had enormous influence on the development of the field and is generally considered to be a single most important paper in Probabilistic Combinatorics, if not in all of Combinatorics.

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¹We say that an event \mathcal{E}_n occurs with high probability, or **whp** for brevity, in the probability space G(n,p) if $\lim_{n\to\infty} \Pr[G \sim G(n,p) \in \mathcal{E}_n] = 1.$

There are now several proofs available for this result. Erdős and Rényi (who actually worked in the model G(n,m) of random graphs) used counting arguments. Some of later proofs relied on the machinery of branching processes. As one can expect for a result of this magnitude of importance, there have been countless ramifications and extensions proven over the years, and by now the evolution of random graphs is very well understood. We refer the reader to the standard sources in the theory of random graphs [10], [7] for a detailed account.

In 1981, Ajtai, Komlós and Szemerédi proved [1] that in the supercritical regime $p = \frac{1+\epsilon}{n}$, not only the random graph G(n, p) contains **whp** a linear sized connected component, but it typically has a path of length linear in n.

The purpose of this note is to present a very simple and self-contained proof of the Erdős-Rényi result, as well of the result of Ajtai, Komlós and Szemerédi. We do not strive to derive the best possible absolute constants, aiming rather for simplicity.

Our notation is fairly standard. We set $N = \binom{n}{2}$. Floor and ceiling signs will be systematically omitted for the sake of clarity of presentation.

2 Main result

Our argument will utilize the notion of the Depth First Search (DFS). This is a well known graph exploration algorithm, and we thus will describe it rather briefly.

Recall that the DFS (Depth First Search) is a graph search algorithm that visits all vertices of a (directed or undirected) graph G = (V, E) as follows. It maintains three sets of vertices, letting S be the set of vertices whose exploration is complete, T be the set of unvisited vertices, and $U = V \setminus (S \cup T)$, where the vertices of U are kept in a stack (the last in, first out data structure). It is also assumed that some order σ on the vertices of G is fixed, and the algorithm prioritizes vertices according to σ . The algorithm starts with $S = U = \emptyset$ and T = V, and runs till $U \cup T = \emptyset$. At each round of the algorithm, if the set U is non-empty, the algorithm queries T for neighbors of the last vertex v that has been added to U, scanning T according to σ . If v has a neighbor uin T, the algorithm deletes u from T and inserts it into U. If v does not have a neighbor in T, then v is popped out of U and is moved to S. If U is empty, the algorithm chooses the first vertex of T according to σ , deletes it from T and pushes it into U. In order to complete the exploration of the graph, whenever the sets U and T have both become empty (at this stage the connected component structure of G has already been revealed), we make the algorithm query all remaining pairs of vertices in S = V, not queried before.

Observe that the DFS algorithm starts revealing a connected component C of G at the moment the first vertex of C gets into (empty beforehand) U and completes discovering all of C when Ubecomes empty again. We call a period of time between two consecutive emptyings of U an *epoch*, each epoch corresponds to one connected component of G.

The following properties of the DFS algorithm will be relevant to us:

- at each round of the algorithm one vertex moves, either from T to U, or from U to S;
- at any stage of the algorithm, it has been revealed already that the graph G has no edges between the current set S and the current set T;
- the set U always spans a path (indeed, when a vertex u is added to U, it happens because u is a neighbor of the last vertex v in U; thus, u augments the path spanned by U, of which v is the last vertex).

We will run the DFS on a random input $G \sim G(n, p)$, fixing the order σ on V(G) = [n] to be the identity permutation. When the DFS algorithm is fed with a sequence of i.i.d. Bernoulli(p) random variables $\bar{X} = (X_i)_{i=1}^N$, so that is gets its *i*-th query answered positively if $X_i = 1$ and answered negatively otherwise, the so obtained graph is clearly distributed according to G(n, p). Thus, studying the component structure of G can be reduced to studying the properties of the random sequence \bar{X} . In particular, observe crucially that as long as $T \neq \emptyset$, every positive answer to a query results in a vertex being moved from T to U, and thus after t queries and assuming $T \neq \emptyset$ still, we have $|S \cup U| \ge \sum_{i=1}^{t} X_i$. (The last inequality is strict in fact as the first vertex of each connected component is moved from T to U "for free", i.e., without need to get a positive answer to a query.) On the other hand, since the addition of every vertex, but the first one in a connected component, to U is caused by a positive answer to a query, we have at time t: $|U| \le 1 + \sum_{i=1}^{t} X_i$.

The probabilistic part of our argument is provided by the following quite simple lemma.

Lemma 1 Let $\epsilon > 0$ be a small enough constant. Consider the sequence $\bar{X} = (X_i)_{i=1}^N$ of i.i.d. Bernoulli random variables with parameter p.

- 1. Let $p = \frac{1-\epsilon}{n}$. Let $k = \frac{7}{\epsilon^2} \ln n$. Then whp there is no interval of length kn in [N], in which at least k of the random variables X_i take value 1.
- 2. Let $p = \frac{1+\epsilon}{n}$. Let $N_0 = \frac{\epsilon n^2}{2}$. Then whp $\left|\sum_{i=1}^{N_0} X_i \frac{\epsilon(1+\epsilon)n}{2}\right| \le n^{2/3}$.

Proof. 1) For a given interval I of length kn in [N], the sum $\sum_{i \in I} X_i$ is distributed binomially with parameters kn and p. Applying the standard Chernoff-type bound (see, e.g., Theorem A.1.11 of [2]) to the upper tail of B(kn, p), and then the union bound, we see that the probability of the existence of an interval violating the assertion of the lemma is at most

$$(N-k+1)Pr[B(kn,p) \ge k] < n^2 \cdot e^{-\frac{\epsilon^2}{3}(1-\epsilon)k} < n^2 \cdot e^{-\frac{\epsilon^2(1-\epsilon)}{3}\frac{7}{\epsilon^2}\ln n} = o(1),$$

for small enough $\epsilon > 0$.

2) The sum $\sum_{i=1}^{N_0} X_i$ is distributed binomially with parameters N_0 and p. Hence, its expectation is $N_0 p = \frac{\epsilon n^2 p}{2} = \frac{\epsilon (1+\epsilon)n}{2}$, and its standard deviation is of order n. Applying the Chebyshev inequality, we get the required estimate.

Now we are ready to formulate and to prove our main result.

Theorem 1 Let $\epsilon > 0$ be a small enough constant. Let $G \sim G(n, p)$.

- 1. Let $p = \frac{1-\epsilon}{n}$. Then whp all connected components of G are of size at most $\frac{7}{\epsilon^2} \ln n$.
- 2. Let $p = \frac{1+\epsilon}{n}$. Then whp G contains a path of length at least $\frac{\epsilon^2 n}{5}$.

In both cases, we run the DFS algorithm on $G \sim G(n, p)$, and assume that the sequence $\bar{X} = (X_i)_{i=1}^N$ of random variables, defining the random graph $G \sim G(n, p)$ and guiding the DFS algorithm, satisfies the corresponding part of Lemma 1.

Proof. 1) Assume to the contrary that G contains a connected component C with more than $k = \frac{7}{\epsilon^2} \ln n$ vertices. Let us look at the epoch of the DFS when C was created. Consider the moment inside this epoch when the algorithm has found the (k + 1)-st vertex of C and is about to move it to U. Denote $\Delta S = S \cap C$ at that moment. Then $|\Delta S \cup U| = k$, and thus the algorithm got exactly k positive answers to its queries to random variables X_i during the epoch, with each positive answer being responsible for revealing a new vertex of C, after the first vertex of C was put into U in the beginning of the epoch. At that moment during the epoch only pairs of edges touching $\Delta S \cup U$ have been queried, and the number of such pairs is therefore at most $\binom{k}{2} + k(n-k) < kn$. It thus follows that the sequence \overline{X} contains an interval of length at most kn with at least k 1's inside – a contradiction to Property 1 of Lemma 1.

2) Assume that the sequence \bar{X} satisfies Property 2 of Lemma 1. We claim that after the first $N_0 = \frac{\epsilon n^2}{2}$ queries of the DFS algorithm, the set U contains at least $\frac{\epsilon^2 n}{5}$ vertices (with the contents of U forming a path of desired length at that moment). Observe first that $|S| < \frac{n}{3}$ at time N_0 . Indeed, if $|S| \geq \frac{n}{3}$, then let us look at a moment t where $|S| = \frac{n}{3}$ (such a moment surely exists as vertices flow to S one by one). At that moment $|U| \leq 1 + \sum_{i=1}^{t} X_i < \frac{n}{3}$ by Property 2 of Lemma 1. Then $|T| = n - |S| - |U| \geq \frac{n}{3}$, and the algorithm has examined all $|S| \cdot |T| \geq \frac{n^2}{9} > N_0$ pairs between S and T (and found them to be non-edges) – a contradiction. Let us return to time N_0 . If $|S| < \frac{n}{3}$ and $|U| < \frac{\epsilon^2 n}{5}$ then, we have $T \neq \emptyset$. This means in particular that the algorithm is still revealing the connected components of G, and each positive answer it got resulted in moving a vertex from T to U (some of these vertices may have already moved further from U to S). By Property 2 of Lemma 1 the number of positive answers at that point is at least $\frac{\epsilon(1+\epsilon)n}{2} - n^{2/3}$. Hence we have $|S \cup U| \geq \frac{\epsilon(1+\epsilon)n}{2} - n^{2/3}$. If $|U| \leq \frac{\epsilon^2 n}{5}$, then $|S| \geq \frac{\epsilon n}{2} + \frac{3\epsilon^2 n}{10} - n^{2/3}$. All $|S||T| \geq |S| \left(n - |S| - \frac{\epsilon^2 n}{5}\right)$ pairs between S and T have been probed by the algorithm (and answered in the negative). We

thus get:

$$\begin{aligned} \frac{\epsilon n^2}{2} &= N_0 \ge |S| \left(n - |S| - \frac{\epsilon^2 n}{5} \right) \ge \left(\frac{\epsilon n}{2} + \frac{3\epsilon^2 n}{10} - n^{2/3} \right) \left(n - \frac{\epsilon n}{2} - \frac{\epsilon^2 n}{2} + n^{2/3} \right) \\ &= \frac{\epsilon n^2}{2} + \frac{\epsilon^2 n^2}{20} - O(\epsilon^3) n^2 > \frac{\epsilon n^2}{2} \end{aligned}$$

(we used the assumption $|S| < \frac{n}{3}$), and this is obviously a contradiction, completing the proof.

3 Discussion

1. Observe that using a Chernoff-type bound for the tales of the binomial random variable instead of the Chebyshev inequality would allow to claim in the second part of Lemma 1 that the sum $\sum_{i=1}^{N_0} X_i$ is close to $\frac{\epsilon(1+\epsilon)n}{2}$ with probability exponentially close to 1. This would show in turn, employing the argument of Theorem 1, that G(n,p) with $p = \frac{1+\epsilon}{n}$ contains a path of length linear in n with exponentially high probability, namely, with probability $1 - \exp\{-c(\epsilon)n\}$.

2. The dependencies on ϵ in both parts of Theorem 1 are of the correct order of magnitude – for $p = \frac{1-\epsilon}{n}$ a largest connected component of G(n, p) is known to be **whp** of size $\Theta(\epsilon^{-2}) \log n$ (see, e.g., Cors. 5.8 and 5.11 of [7]), while for $p = \frac{1+\epsilon}{n}$ a longest cycle of G(n, p) is **whp** of length $\Theta(\epsilon^2)n$ (see, e.g., Th. 5.17 of [10]); the standard trick of sprinkling further random edges with edge probability $p' = o(n^{-1})$ shows that if G(n, p) contains **whp** a path of length αn for some constant $\alpha > 0$, then G(n, p + p') contains **whp** a cycle of length at least $(\alpha - o(1))n$. Note also that although we stated our result in Theorem 1 for a constant $\epsilon > 0$, our argument is in fact valid for $\epsilon = \epsilon(n) \to 0$ as well, with a bit more careful treatment of the error terms in our proofs. Actually, we can take $\epsilon(n)$ to be as low as $\epsilon \gg n^{-1/3} \log^{1/3} n$ in our arguments (including the theorem in the next remark) – which nearly borders the critical window $\epsilon = \Theta(n^{-1/3})$.

3. The giant component itself in the regime $p = \frac{1+\epsilon}{n}$, $\epsilon > 0$ a constant, is known to be substantially larger typically than a longest path – it has **whp** $\Theta(\epsilon)n$ vertices (see, e.g., Th. 5.4 of [10]). Using very similar techniques, we can show the probable existence of a connected component of size $\Omega(\epsilon)n$ in this range, as given by the following theorem.

Theorem 2 Let $p = \frac{1+\epsilon}{n}$, for $\epsilon > 0$ a small enough constant. Let $G \sim G(n,p)$. Then whp G has a connected component with at least $\frac{\epsilon n}{2}$ vertices.

Proof. The proof is quite similar to that of Theorem 1, and therefore we will allow ourselves to be rather concise. Here too we run the DFS algorithm on $G \sim G(n, p)$ and feed it with a sequence \bar{X} of i.i.d. Bernoulli(p) random variables $\bar{X} = (X_i)_{i=1}^N$. Denote as before $N_0 = \frac{\epsilon n^2}{2}$. We will need the following typical properties of the sequence \bar{X} , slightly generalizing those stated in Part 2. of Lemma 1 and provable using the same Chernoff-type estimates:

- 1. $\sum_{i=1}^{n^{7/4}} X_i \le n^{5/6};$
- 2. For every $n^{7/4} \le t \le N_0$, $\left|\sum_{i=1}^t X_i (1+\epsilon)\frac{t}{n}\right| \le n^{2/3}$.

Let us assume now that the sequence \bar{X} satisfies the above stated properties. We claim that after the first N_0 queries of the DFS algorithm, we are in the midst of revealing a connected component whose size is at least $\frac{\epsilon n}{2}$. Just as in the proof of Theorem 1 we have that $|S| < \frac{n}{3}$ at time N_0 , and Tis still non-empty. It follows that at any moment $n^{7/4} \le t \le N_0$ we have: $|S \cup U| \ge (1+\epsilon)\frac{t}{n} - n^{2/3}$. If at some moment t in this interval the set U becomes empty, the algorithm has asked all queries between the set S and its complement T = [n] - S, implying:

$$\begin{aligned} t &\geq |S|(n-|S|) \geq \left((1+\epsilon)\frac{t}{n} - n^{2/3}\right) \left(n - (1+\epsilon)\frac{t}{n} + n^{2/3}\right) \geq (1+\epsilon)t - (1+\epsilon)^2 \frac{t^2}{n^2} - 2n^{5/3} \\ &\geq (1+\epsilon)\left(1 - (1+\epsilon)\frac{\epsilon}{2}\right)t - 2n^{5/3} = (1+\epsilon)\left(1 - \frac{\epsilon}{2} - \frac{\epsilon^2}{2}\right)t - 2n^{5/3} > t \end{aligned}$$

– a contradiction, for small enough $\epsilon > 0$. (We used $|S| < \frac{n}{3}$ in the above estimate.) Hence U is never empty in the interval $[n^{7/4}, N_0]$. It follows that all vertices added to U during this interval (of which some may have migrated further to S) are in the same connected component, and their number is, by the properties of \bar{X} stated above,

$$\sum_{i=n^{7/4}}^{N_0} X_i \ge (1+\epsilon)\frac{N_0}{n} - n^{2/3} - n^{5/6} \ge (1+\epsilon)\frac{\epsilon n}{2} - 2n^{5/6} \ge \frac{\epsilon n}{2}.$$

All these vertices belong to the same connected component – whose size is then at least $\frac{\epsilon n}{2}$, completing the proof.

4. As we have already mentioned, the DFS algorithm is applicable equally well to directed graphs. Hence essentially the same argument as above, with obvious minor changes, can be applied to the model D(n,p) of random digraphs. In this model, the vertex set is [n], and each of the n(n-1) ordered pairs $(i,j), 1 \le i \ne j \le n$, is a directed edge of $D \sim D(n,p)$ with probability p = p(n) and independently from other pairs. In particular we can obtain the following theorem:

Theorem 3 Let $p = \frac{1+\epsilon}{n}$, for $\epsilon > 0$ constant. Then the random digraph D(n, p) has whp a directed path and a directed cycle of length $\Theta(\epsilon^2)n$.

This recovers the classical result of Karp [11] for the model D(n, p).

5. The technique of Theorem 1 can be applied to further models of random graphs and digraphs. One immediate application is to random subgraphs of graphs of large minimum degree. We have the following theorem. **Theorem 4** Let G be a finite graph with minimum degree at least n. Let $p = \frac{1+\epsilon}{n}$, for $\epsilon > 0$ constant. Form a random subgraph G_p of G by including every edge of G into G_p independently and with probability p. Then whp G_p has a path of length at least $\frac{\epsilon^2 n}{5}$.

The proof is essentially identical to that of Theorem 1. We run the DFS process on G_p and feed it with a sequence \bar{X} of i.i.d. Bernoulli(p) random variables $\bar{X} = (X_i)_{i=1}^N$, where N = |E(G)|. For the proof, we need only to notice that at any time the number of edges of G between S and T can be estimated from below by $|S|(\delta(G) - |S| - |U|) \ge |S|(n - |S| - |U|)$, the rest of the proof is the same. Notice that getting a long cycle appears to be a much more challenging task in this setting – the base graph G can be of girth (much) larger than n, and therefore sprinkling does not necessarily help (immediately) to turn a long path into a long cycle **whp**.

6. Another example of applying our technique is random subgraphs of pseudo-random graphs. Let G be an (n, d, λ) -graph (a d-regular graph on n vertices, in which all eigenvalues of the adjacency matrix, but the first one, are at most λ in their absolute values – see, e.g. [12] for a thorough discussion of this notion). It is well known that requiring $\lambda \ll d$ is enough to guarantee many pseudo-random properties of such a graph. The model of taking a random subgraph G_p of an (n, d, λ) -graph G has been considered by Frieze, Krivelevich and Martin in [9]. It is proven in [9] that, assuming $\lambda \ll d$, for $p = \frac{1+\epsilon}{d}$ the random subgraph G_p of an an (n, d, λ) -graph G has whp the unique connected component of size linear in n. We can apply the technique of Theorem 1 to prove the following:

Theorem 5 Let G be an (n, d, λ) -graph with $\lambda = o(d)$. Let $p = \frac{1+\epsilon}{d}$, for $\epsilon > 0$ constant. Then the random subgraph G_p contains whp a path of length $\Theta(\epsilon^2)n$.

Here is a very brief sketch of the proof. We run the DFS algorithm on G_p till it queries $\frac{\epsilon dn}{2}$ edges of G.

Similarly to Lemma 1, it gets **whp** about $\frac{\epsilon(1+\epsilon)n}{2}$ positive answers during this period, when fed with a string of i.i.d. Bernoulli $\left(\frac{1+\epsilon}{d}\right)$ random variables. In order for the proof analogous to that of Theorem 1 to go through, one only needs to be able to control the number of edges between any two linear sized vertex subsets S, T in G. Such a control is indeed available for (n, d, λ) -graphs – it is known that if G is an (n, d, λ) -graph, then for any two vertex subsets $S, T \subseteq V(G)$ the number $e_G(S, T)$ of edges of G with one endpoint in S and another in T satisfies:

$$\left| e_G(S,T) - \frac{d}{n} |S| |T| \right| \le \lambda \sqrt{|S||T|}$$

(see, e.g. Corollary 9.2.5 of [2] or Theorem 2.11 of [12]). Assuming $\lambda \ll d$ is enough therefore to guarantee that $e_G(S,T) = (1 + o(1))\frac{d}{n}|S|||T|$ in such a graph, and the proof for the random subgraph proceeds as in Theorem 1. Here too sprinkling helps to turn a long path into a long cycle **whp** – we first get **whp** a linearly long path and then argue that due to the above estimate on the edge distribution of G there are $\Theta(dn)$ edges between the prefix and the suffix of the path, and one of them will **whp** fall into a sprinkled graph, thus closing a long cycle.

7. Yet another application of our proof strategy is to positional games. The following game $\mathcal{L}(n, b)$ was considered by Bednarska and Luczak in [3]. The game is played between two players, Maker and Breaker, alternately claiming 1 and b edges, respectively, of the complete graph K_n on n vertices, till all edges of K_n have been claimed by either of the players. Maker's goal is to maximize the number of vertices in a largest connected component in her graph by the end of the game, Breakers aims to make it as small as possible. Bednarska and Luczak discovered the following phase transition phenomenon, obviously reminiscent of the Erdős-Rényi phase transition in random graphs. Let $\epsilon > 0$ be a constant. If $b = (1 + \epsilon)n$ then Breaker has a strategy to keep all of Maker's connected components of size $O(1/\epsilon)$. On the other hand, if $b = (1 - \epsilon)n$, then Maker has a strategy to create a connected component of size $\Theta(\epsilon)n$. We can prove the following result.

Theorem 6 Let $\epsilon > 0$. Then in the game $\mathcal{L}(n, b)$ with $b = (1 - \epsilon)n$, Maker has a strategy to create a path of length $\Theta(\epsilon^2)n$.

The winning strategy of Maker and the proof of its validity are fairly similar to the proof of Theorem 1. Maker maintains three sets S, U, T partitioning [n], starting with $S = \emptyset$, and U being an arbitrary vertex from [n]. She makes sure that the set U always spans a path of her edges at any stage of the game. At each Maker's turn, she finds the last vertex v along the path in U for which there exists an unclaimed edge (v, u) with $u \in T$, shifts all further vertices after v along U into S and claims the edge (v, u), moving u from T to U. If no such vertex is available along the current path in U, Maker moves all of its vertices into S, loads U with an arbitrary vertex u from T and then proceeds as described before. One can observe that, similarly to the analysis of the DFS algorithm, at any stage of the game all edges between the current set S and the current set T have been claimed by Breaker. Now, look at the situation in the game after $\frac{\epsilon n}{2}$ rounds. At that point $|S \cup U| \geq \frac{\epsilon n}{2}$. If one has $|U| \leq \frac{\epsilon^2 n}{5}$, then all

$$|S||T| \ge \left(\frac{\epsilon n}{2} - \frac{\epsilon^2 n}{5}\right) \left(n - \frac{\epsilon n}{2}\right) > \frac{\epsilon n}{2}(1 - \epsilon)n$$

edges between S and T have been claimed by Breaker – a contradiction, for small enough $\epsilon > 0$. The situation with making a cycle is quite different here – it has been shown by Bednarska and Pikhurko [4] that if b = b(n) is such that Maker completes the game with at most n - 1 edges, then Breaker has a strategy to force Maker to end up with a tree; thus $b \ge (1 + o(1))n/2$ is required for Maker to create a cycle of any length.

8. Some of the idea utilized in this paper have already been applied before. In particular, the DFS algorithm has been used by Ben-Eliezer and the authors in [6] to prove the following statement:

if in a graph G on n vertices there is an edge between every pair of disjoint vertex subsets of size k, then G contains a path of length n - 2k + 1. This deterministic statement implies readily that G(n,p) with p = c/n contains **whp** a path of length $(1 - \alpha(c))n$, where $\alpha(c) \to 0$ as $c \to \infty$. Also, Benjamini and Schramm [5] used the idea of coupling a graph search algorithm with a sequence \bar{X} of random bits, serving as answers to the algorithm's queries, to derive some results about percolation in expanding graphs.

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