

Sets with few distinct distances do not have heavy lines *

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Abstract

Let P be a set of n points in the plane that determines at most $n/5$ distinct distances. We show that no line can contain more than $O(n^{43/52}\text{polylog}(n))$ points of P . We also show a similar result for rectangular distances, equivalent to distances in the Minkowski plane, where the distance between a pair of points is the area of the axis-parallel rectangle that they span.

The problem and its background

Given a set P of n points in \mathbb{R}^2 , let $D(P)$ denote the number of distinct distances that are determined by pairs of points from P , and put $D(n) = \min_{|P|=n} D(P)$; that is, $D(n)$ is the minimum number of distinct distances that any set of n points in \mathbb{R}^2 must always determine. In his celebrated 1946 paper [5], Erdős derived the bound $D(n) = O(n/\sqrt{\log n})$ by considering a $\sqrt{n} \times \sqrt{n}$ integer lattice. Recently, after 65 years and a series of progressively larger lower bounds¹, Guth and Katz [10] provided an almost matching lower bound $D(n) = \Omega(n/\log n)$.

While the problem of finding the asymptotic value of $D(n)$ is almost completely solved, hardly anything is known about which point sets determine a small number of distinct distances. Consider a set P of n points in the plane, such that $D(P) = O(n/\sqrt{\log n})$. Erdős conjectured [7] that any such set “has lattice structure.” Informally, this should mean that, on one hand, there have to exist (many) lines that contain many points of P , and, on the other hand, no line should contain too many points of P . Progress on the former aspect of

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¹For a comprehensive list of the previous bounds, see [9] and http://www.cs.umd.edu/~gasarch/erdos_dist/erdos_dist.html.

the conjecture has been rather minimal: The only significant result is a variant of an old proof of Szemerédi, which implies that there exists a line that contains $\Omega(\sqrt{\log n})$ points of P (Szemerédi’s proof was communicated by Erdős in [6] and can be found in [14, Theorem 13.7]).

In contrast, some recent works have advanced the latter aspect. Specifically, a recent result of Pach and de Zeeuw [15] implies that any constant-degree curve that contains no lines and circles cannot be incident to more than $O(n^{3/4})$ points of P (see also Sharir et al. [17] for a precursor of this work). Another recent result, by Sheffer, Zahl and de Zeeuw [19], implies that no line can contain $\Omega(n^{7/8})$ points of P , and no circle can contain $\Omega(n^{5/6})$ such points.

We note that all these papers do not make use of the specific bound for $D(P)$. What they show is that the existence of a curve, line, or circle that contains more than the prescribed number of points of P implies that $D(P) = \Omega(n)$. This is also the approach used in this paper.

Our results

In this paper we significantly improve the bound of Sheffer et al. [19] for points on a line, and establish the following result (we use the $O^*(\cdot)$ notation to hide polylogarithmic factors).

Theorem 1. *Let P be a set of n points in the plane, such that $D(P) \leq n/5$. Then, for any line ℓ in the plane, we have*

$$|P \cap \ell| = O^*\left(n^{43/52}\right) \approx O(n^{0.827}).$$

We also consider a version of this problem in which a different notion of distance is used. Given two points $p = (p_x, p_y)$ and $q = (q_x, q_y)$ in the plane, the *rectangular area* or *rectangular distance* determined by p and q is the quantity

$$R(p, q) = (p_x - q_x)(p_y - q_y).$$

That is, $R(p, q)$ is the signed area of the axis parallel rectangle with p and q at opposite corners, where the area is positive (resp., negative) if p and q are the northeast and southwest (resp., northwest and southeast) corners of the rectangle. Let $\mathcal{R}(P) := |\{R(p, q) \mid p, q \in P\}|$. The interest in rectangular distances comes from the observation that, by rotating the coordinate frame by 45° , $R(p, q)$ becomes half the squared distance between p and q in the *Minkowski plane* [2], namely, where the squared distance is $(p_x - q_x)^2 - (p_y - q_y)^2$. Another motivation for rectangular distances is that they arise in certain problems of the sum-product type; see Roche-Newton and Rudnev [16].

Following in the footsteps of the work of Guth and Katz [10], Roche-Newton and Rudnev [16] have shown that, for a set P of n points in the plane, $\mathcal{R}(P) = \Omega(n/\log n)$, provided that P is not contained inside a single horizontal or vertical line. Note that the latter condition is necessary, since if all the points lie on such a line then all pairs determine rectangular area equal to zero. Indeed, horizontal and vertical lines are somewhat special in this “metric”.

In this context, we can observe a subtle difference between these two notions of distance, since the analogue of Theorem 1 is not quite true if Euclidean distance is replaced with rectangular area. Let $\varepsilon > 0$ be fixed, and suppose for simplicity that $n^{1-\varepsilon}$ and n^ε are integers. An unbalanced rectangular lattice $\{1, \dots, n^{1-\varepsilon}\} \times \{1, \dots, n^\varepsilon\}$, consisting of n points, will determine a sublinear number of distinct rectangular areas. Indeed, the size of the set of rectangular areas is approximately the same as that of the product set $\{1, \dots, n^{1-\varepsilon}\} \cdot \{1, \dots, n^\varepsilon\}$. The fact that the size of this set is $o(n)$ is a classical result in number theory and precise estimates for its cardinality can be found in Ford [8]. On the other hand, this lattice point set contains rich horizontal lines with $n^{1-\varepsilon}$ points thereon. A symmetric construction yields a point set which determines a sublinear number of rectangular areas, but for which there exist vertical lines which support $n^{1-\varepsilon}$ points. By contrast, it was established in [3, Theorem 2.1] that a rectangular lattice needs to be only very slightly unbalanced in order to determine $\Omega(n)$ distinct (Euclidean) distances.

However, we show that these are the only problematic directions. Specifically, we prove the following result.

Theorem 2. *Let P be a set of n points in the plane, such that $\mathcal{R}(P) \leq n/5$. Then, for any line ℓ which is not horizontal or vertical, we have*

$$|P \cap \ell| = O^*\left(n^{43/52}\right).$$

Preliminary results

The proofs of Theorems 1 and 2 closely follow the structure of the main result in Sheffer et al. [19]. The quantitative improvements obtained here come as a result of calling upon two results which are quantitatively better than those used in [19]. The first of these is the following incidence theorem.

Theorem 3 (Agarwal et al., Theorem 6.6 [1]). *Let C be a family of distinct pseudo-parabolas that admit a 3-parameter representation, and let P be a set of distinct points in the plane. Denote by $I(P, C)$ the number of incidences between P and C . Then*

$$I(P, C) = O(|P|^{2/3}|C|^{2/3} + |P|^{6/11}|C|^{9/11} \log^{2/11} |C| + |P| + |C|).$$

(The bound in [1] is slightly weaker; the improvement, manifested in the factor $\log^{2/11} n$, which replaces a slightly larger factor in [1], is due to Marcus and Tardos [13].) In the language of [1], a family of *pseudo-parabolas* is a family of graphs of everywhere defined continuous functions, so that each pair intersect in at most two points. The collection C *admits a 3-parameter representation* if the curves have three degrees of freedom, and can thus be identified with points in \mathbb{R}^3 in a suitable manner. A full definition of this property is given at the beginning of Section 5 in [1].

The important observation for us is that a family of hyperbolas of the form $(x - a)^2 - (y - b)^2 = c$, where a, b and c are real numbers with $c \neq 0$, is a family of pseudo-parabolas which admit a 3-parameter representation, and so the bound in Theorem 3 applies to such a family. (Technically, some transformations are needed to make this family have the desired properties. Specifically, we rotate the coordinate frame by 90° , and treat each branch of

each hyperbola as a separate curve.) Such families of hyperbolas arise in the proofs of our theorems.

A crucial assumption in Theorem 3 is that the curves in C are all *distinct*. Suppose next that they are not necessarily distinct, but that the maximum coincidence multiplicity of any curve in C is at most k . A standard argument, similar to the one used by Székely [20], shows that in this case we have

$$I(P, C) = O\left(k^{1/3}|P|^{2/3}|C|^{2/3} + k^{2/11}|P|^{6/11}|C|^{9/11}\log^{2/11}|C| + k|P| + |C|\right). \quad (1)$$

One way of seeing this is to use a pruning argument, where we leave just one curve out of any family of coinciding ones, assuming that all multiplicities are between t and $t/2$ for some t . This leaves us with a subset C' of $\Theta(|C|/t)$ curves, all distinct. Applying Theorem 3 to P and C' , and multiplying the resulting bound by t , the asserted bound follows, with t instead of k , and with C standing for the subset of curves whose multiplicity is roughly t . To complete the analysis, we sum the bounds over the geometric sequence of ranges of t , up to k .

The other result that will be called upon, which is a sharper variant of a result in [12], is the following.

Theorem 4. *Let f be a continuous strictly convex or concave function on \mathbb{R} , and let $U, V \subset \mathbb{R}$ be finite sets. Then*

$$|U - V|^5 |f(U) + V|^6 = \Omega\left(\frac{|U|^{11}|V|^3}{\log^2|U|}\right). \quad (2)$$

This result represents a quantitative improvement on an earlier work Elekes, Nathanson and Ruzsa [4], which was used in the work of [19]. As noted, this was not the precise form in which the bound originally appeared. In [12], it was assumed that the sets U and V were of comparable size, and so the numerator on the right-hand side of (2) was simply written as $|U|^{14}$. However this assumption was in fact completely unnecessary. By working through the original proof without this needless assumption, the result is Theorem 4. Since the exact result that will be used has not appeared in the literature, the proof is included here as an appendix.

Proof of Theorem 1

Let ℓ be a line for which $|P \cap \ell|$ is maximal, denote this value as m , and put $A := P \cap \ell$. Assume for simplicity that ℓ is the x -axis. We face a setup where we have two sets A and P , where A consists of m points on the x -axis. We want to show that m cannot be too large, given our assumption that the number of distinct distances in P is at most $n/5$. The strategy is to show that if m is too large then either $D(A)$, the number of distinct distances in A , or $D(A, P)$, the number of distinct distances in $A \times P$, is large. The main part of the analysis focuses on the latter quantity.

Following the by now usual strategy, as applied in several recent works (e.g., see [15, 17, 18]), we consider the set of quadruples

$$Q := \{(a, b, p, q) \in A^2 \times P^2 \mid \|p - a\| = \|q - b\|\},$$

and double count its cardinality. A lower bound is easy to obtain, via the Cauchy-Schwarz inequality. That is, enumerate the $D(A, P)$ distinct distances in $A \times P$ as $\delta_1, \dots, \delta_{D(A, P)}$, write, for each i ,

$$M_i = |\{(a, p) \in A \times P \mid \|p - a\| = \delta_i\}|,$$

and note that

$$mn = \sum_{i=1}^{D(A, P)} M_i \leq \left(\sum_i M_i^2 \right)^{1/2} D(A, P)^{1/2} = |Q|^{1/2} D(A, P)^{1/2},$$

or, since $D(A, P) \leq n/5$,

$$|Q| \geq \frac{m^2 n^2}{D(A, P)} \geq 5m^2 n. \quad (3)$$

We partition Q into two parts: $Q^{(1)}$ contains the quadruples $(a, b, p, q) \in Q$ for which $p_y^2 = q_y^2$ and $Q^{(2)} = Q \setminus Q^{(1)}$. We first bound $|Q^{(1)}|$, noting that for any choice of the points a, b, p , there are at most four choices of q such that $(a, b, p, q) \in Q^{(1)}$. Hence, $|Q^{(1)}| \leq 4m^2 n$. Using (3), we get

$$|Q^{(2)}| \geq m^2 n. \quad (4)$$

For an upper bound on $|Q^{(2)}|$, we again follow the standard approach. That is, we map each pair $(p, q) \in P^2$, with $p_y^2 \neq q_y^2$, into the curve

$$\gamma_{p, q} = \{(x, y) \in \mathbb{R}^2 \mid \|p - (x, 0)\|^2 = \|q - (y, 0)\|^2\},$$

and observe that $|Q^{(2)}|$ is equal to the number of incidences between the curves $\gamma_{p, q}$ and the points of $\Pi := A^2$, where each ordered pair of points in A is interpreted as (the x - and y -coordinates of) a point in a suitable parametric plane.

The curves are in fact hyperbolas. Specifically, the equation of $\gamma_{p, q}$, for $p = (p_x, p_y)$ and $q = (q_x, q_y)$, is

$$\begin{aligned} (x - p_x)^2 + p_y^2 &= (y - q_x)^2 + q_y^2, & \text{or} \\ x^2 - y^2 - 2p_x x + 2q_x y &= q_x^2 + q_y^2 - p_x^2 - p_y^2. \end{aligned} \quad (5)$$

The requirement that $p_y^2 \neq q_y^2$ ensures that $\gamma_{p, q}$ is a non-degenerate hyperbola (i.e., not the union of two lines); in particular, the quadratic polynomial defining $\gamma_{p, q}$ is irreducible. We also note that each hyperbola has three degrees of freedom (as required in Theorem 3)—it can be specified by the parameters p_x , q_x , and $q_y^2 - p_y^2$.

Let Γ denote the multiset of these hyperbolas. As in the previously cited works, the main difficulty in the analysis is the possibility that many hyperbolas in Γ coincide, in which case the known machinery for deriving incidence bounds (such as the bound in Theorem 3) breaks down, and the bounds themselves become too weak. Indeed, the hyperbolas might coincide; let k denote the maximum coincidence multiplicity of any hyperbola in Γ . Then, repeating the bound in (1), we have

$$|Q^{(2)}| = I(\Pi, \Gamma) = O\left(k^{1/3} |\Pi|^{2/3} |\Gamma|^{2/3} + k^{2/11} |\Pi|^{6/11} |\Gamma|^{9/11} \log^{2/11} |\Gamma| + k |\Pi| + |\Gamma|\right). \quad (6)$$

The multiplicity of hyperbolas. The next step applies an argument of the sum-product type, based on Theorem 4, to obtain an upper bound on k . Let $\gamma_{p,q}$ and $\gamma_{p',q'}$ be two coinciding hyperbolas. By (5), we have $p_x = p'_x$, $q_x = q'_x$, and $q_y^2 - p_y^2 = (q'_y)^2 - (p'_y)^2$. In other words, k coinciding hyperbolas γ_{p_i,q_i} , for $i = 1, \dots, k$, are such that all the points p_i lie on the same vertical line, all the points q_i lie on another common vertical line, and the quantities $q_{iy}^2 - p_{iy}^2$ are all equal. The points p_i need not be distinct, but each point can appear at most twice. Indeed, the condition $\gamma_{p,q} = \gamma_{p',q'}$ is equivalent to $q_x = q'_x$ and $q_y^2 = (q'_y)^2$, so, for a given q , there is at most one choice for another point q' . That is, in this situation we have at least $k/2$ distinct points p_i , and at least $k/2$ distinct points q_i .

Consider the following restricted problem. We have a set A of m points on the x -axis, and (with a slight abuse of notation) a set B of at least $k/2$ points on some vertical line (say, we take B to be the set of the points q_i defining our k coinciding hyperbolas), which we may assume to be the y -axis. Consider the sets

$$\begin{aligned} A - A &= \{x - y \mid x, y \in A\} \\ A^2 + B^2 &= \{x^2 + y^2 \mid x \in A, y \in B\}. \end{aligned}$$

Notice that $|A - A|$ is at most twice the number of distinct distances in A , and that $|A^2 + B^2|$ is the number of distinct distances in $A \times B$. By the hypothesis of the theorem, we have that both $|A - A|$ and $|A^2 + B^2|$ are $O(n)$.

We apply Theorem 4 with $U = A$, $V = B^2$, and $f(x) = x^2$, and obtain

$$|A - A|^5 |f(A) + B^2|^6 = |A - A|^5 |A^2 + B^2|^6 = \Omega^*(|A|^{11}|B|^3);$$

that is,

$$|A|^{11}|B|^3 = O^*(n^{11}), \quad \text{or} \quad |B| = O^*\left(n^{11/3}/|A|^{11/3}\right) = O^*\left(n^{11/3}/m^{11/3}\right).$$

In other words, we have shown that no vertical line can contain more than $\nu = O^*(n^{11/3}/m^{11/3})$ points. In particular, we get that the multiplicity bound k that we are after satisfies $k \leq 2\nu = O^*(n^{11/3}/m^{11/3})$. Substituting this into (6), noting that $|\Gamma| \leq n^2$ and $|\Pi| \leq m^2$, we obtain

$$\begin{aligned} |Q^{(2)}| &= I(\Pi, \Gamma) \\ &= O^*\left(k^{1/3}|\Pi|^{2/3}|\Gamma|^{2/3} + k^{2/11}|\Pi|^{6/11}|\Gamma|^{9/11} + k|\Pi| + |\Gamma|\right) \\ &= O^*\left((n^{11/3}/m^{11/3})^{1/3}(m^2)^{2/3}(n^2)^{2/3} + (n^{11/3}/m^{11/3})^{2/11}(m^2)^{6/11}(n^2)^{9/11} \right. \\ &\quad \left. + n^{11/3}/m^{5/3} + n^2\right) \\ &= O\left(m^{1/9}n^{23/9} + m^{14/33}n^{76/33} + n^{11/3}/m^{5/3}\right) \end{aligned}$$

(the term n^2 is subsumed by the first two terms). Recalling that $|Q^{(2)}| \geq m^2n$, we have

$$m^2n = O^*\left(m^{1/9}n^{23/9} + m^{14/33}n^{76/33} + n^{11/3}/m^{5/3}\right),$$

and an easy calculation shows that $m = O^*(n^{43/52})$. This completes the proof of Theorem 1. \square

Remark. The bound on m becomes in fact even (slightly) smaller than $n^{43/52}$ when $D(P) = o\left(n/\log^{2/11} n\right)$. For example, in the extreme case where $D(P) = O\left(n/\sqrt{\log n}\right)$, we get $m = O\left(n^{43/52}/\log^{21/52} n\right)$.

Proof of Theorem 2

Let ℓ be a line in a direction which is not horizontal or vertical and with the property that $|P \cap \ell|$ is maximal over all lines of this type, and put $m := |P \cap \ell|$. Write $A := P \cap \ell$. The proof follows the same structure as that of the proof of Theorem 1, and shows that $m = |A| = O^*(n^{43/52})$.

Since the quantity $\mathcal{R}(P)$ is invariant under translation of the set P , we may assume that ℓ passes through the origin.² Furthermore, since we assume that ℓ is not horizontal or vertical, its equation is $y = \kappa x$, for some $\kappa \neq 0$. It will be convenient to use the notation $A_0 := \{a \mid (a, \kappa a) \in A\}$ for the set of x -coordinates of the points in A .

Let Q denote the set of all quadruples $(s, t, p, q) \in A^2 \times P^2$ which satisfy the equation

$$R(p, s) = R(q, t). \quad (7)$$

By the Cauchy-Schwarz inequality and the conditions of the theorem, we have, similar to the proof of Theorem 1,

$$\frac{n|Q|}{5} \geq \mathcal{R}(A, P)|Q| \geq |A|^2 n^2 = m^2 n^2, \quad (8)$$

where $\mathcal{R}(A, P)$ denotes the number of distinct rectangular distances between the points of A and the points of P . Hence

$$|Q| \geq 5m^2 n. \quad (9)$$

A satisfactory upper bound on $|Q|$ will be sufficient to prove that $\mathcal{R}(P)$ is large. Once again, the set of quadruples Q is partitioned into two subsets: $Q^{(1)}$ contains the set of all quadruples $(s, t, p, q) \in Q$ such that $(q_y - \kappa q_x)^2 = (p_y - \kappa p_x)^2$, and $Q^{(2)} := Q \setminus Q^{(1)}$. Geometrically, in the quadruples of $Q^{(1)}$, p and q lie at the same (absolute) distance from ℓ . For each triple $(s, t, p) \in A^2 \times B$, there exists at most four choices of $q = (q_x, q_y)$ that satisfy both (7) and $(q_y - \kappa q_x)^2 = (p_y - \kappa p_x)^2$, as is easily checked. Therefore, $|Q^{(1)}| \leq 4m^2 n$, and it thus follows from (9) that

$$|Q^{(2)}| \geq m^2 n. \quad (10)$$

Following the proof of Theorem 1, the task of obtaining an upper bound for $|Q^{(2)}|$ can be reformulated as an incidence problem. For $p, q \in P$, write $p = (p_x, p_y)$ and $q = (q_x, q_y)$, and define $\gamma_{p,q}$ to be the curve given by the equation

$$(p_x - x)(p_y - \kappa x) = (q_x - y)(q_y - \kappa y).$$

²Note that $\mathcal{R}(P)$ is not invariant under rotation, which is why we cannot assume that the line ℓ is the x -axis, as we did in the proof of Theorem 1.

After expanding and rearranging, it follows that $\gamma_{p,q}$ is the hyperbola with equation

$$\begin{aligned} \left(x - \frac{p_y + \kappa p_x}{2\kappa}\right)^2 - \left(y - \frac{q_y + \kappa q_x}{2\kappa}\right)^2 &= \frac{q_x q_y - p_x p_y}{\kappa} + \frac{(p_y + \kappa p_x)^2 - (q_y + \kappa q_x)^2}{4\kappa^2} \\ &= \frac{(p_y - \kappa p_x)^2 - (q_y - \kappa q_x)^2}{4\kappa^2}. \end{aligned} \quad (11)$$

Let Γ be the multiset of curves

$$\Gamma := \{\gamma_{p,q} \mid p, q \in P, (p_y - \kappa p_x)^2 \neq (q_y - \kappa q_x)^2\}.$$

The curves of Γ are non-degenerate hyperbolas. As in the proof of Theorem 1, Γ is a family of pseudo-parabolas that admits a 3-parameter representation, except that the curves in Γ can occur with multiplicity. Concretely, $\gamma_{p,q} = \gamma_{p',q'}$ if each of the following conditions holds.

$$p_y + \kappa p_x = p'_y + \kappa p'_x \quad (12)$$

$$q_y + \kappa q_x = q'_y + \kappa q'_x \quad (13)$$

$$(p_y - \kappa p_x)^2 - (q_y - \kappa q_x)^2 = (p'_y - \kappa p'_x)^2 - (q'_y - \kappa q'_x)^2. \quad (14)$$

Recalling the notation $A_0 = \{a \mid (a, \kappa a) \in A\}$, we put $\Pi := A_0 \times A_0$. It is immediate from the definitions that $|Q^{(2)}| = I(\Pi, \Gamma)$. Let k denote the maximum multiplicity of a hyperbola in Γ . Since Γ satisfies the assumptions of Theorem 3, inequality (1) holds for these curves as well, giving

$$I(\Pi, \Gamma) = O\left(k^{1/3} |\Pi|^{2/3} |\Gamma|^{2/3} + k^{2/11} |\Pi|^{6/11} |\Gamma|^{9/11} \log^{2/11} |\Gamma| + k |\Pi| + |\Gamma|\right). \quad (15)$$

The next step is to show that k cannot be too large, in order to make use of (15). Once again, this step follows the same argument as the corresponding part of the proof of Theorem 1. The only difference is that a different convex function (in the application of Theorem 4) will be used. Specifically, we claim:

$$k = O^*\left(\frac{n^{11/3}}{m^{11/3}}\right). \quad (16)$$

To prove (16), first suppose that some curve in Γ has multiplicity k . That is, there exist k pairs of points $(p^{(1)}, q^{(1)}), (p^{(2)}, q^{(2)}), \dots, (p^{(k)}, q^{(k)})$ in B^2 , where $p^{(i)} = (p_x^{(i)}, p_y^{(i)})$ and $q^{(i)} = (q_x^{(i)}, q_y^{(i)})$, such that $\gamma_{p^{(1)}, q^{(1)}} = \gamma_{p^{(2)}, q^{(2)}} = \dots = \gamma_{p^{(k)}, q^{(k)}}$. In particular, by (12),

$$p_y^{(1)} + \kappa p_x^{(1)} = p_y^{(2)} + \kappa p_x^{(2)} = \dots = p_y^{(k)} + \kappa p_x^{(k)}.$$

Denoting this common value as c , it follows that all the points $p^{(i)}$ lie on a common line ℓ_2 , given by $y = -\kappa x + c$.

As in the preceding analysis, the points $p^{(i)}$ need not be distinct. Nevertheless, a point p can have at most two points $q^{(1)}, q^{(2)}$ such that $\gamma_{p, q^{(1)}} = \gamma_{p, q^{(2)}}$. Indeed, writining $p = (p_x, p_y)$, $q^{(1)} = (q_x^{(1)}, q_y^{(1)})$, $q^{(2)} = (q_x^{(2)}, q_y^{(2)})$, the above coincidence of hyperbolas is equivalent to

$$(p_y - \kappa p_x)^2 - (q_y^{(1)} - \kappa q_x^{(1)})^2 = (p_y - \kappa p_x)^2 - (q_y^{(2)} - \kappa q_x^{(2)})^2, \quad (17)$$

and

$$q_y^{(1)} + \kappa q_x^{(1)} = q_y^{(2)} + \kappa q_x^{(2)}. \quad (18)$$

Fixing $q^{(1)}$, this gives a system of a linear equation and a quadratic equation in the coordinates of $q^{(2)}$, which has at most two solutions, one of which is $q^{(1)}$ itself.

Hence, ℓ_2 contains at least $k/2$ *distinct* points of B . Write $B_0 := \{x \mid (x, y) \in \ell_2 \cap B\}$ for the set of x -coordinates of $\ell_2 \cap B$, so that $|B_0| = |\ell_2 \cap B| \geq k/2$.

Observe that

$$\mathcal{R}(A) = |\{(a-b)(\kappa a - \kappa b) \mid a, b \in A_0\}| = |\{(a-b)^2 \mid a, b \in A_0\}| \geq \frac{|A_0 - A_0|}{2}. \quad (19)$$

Finally, we have

$$\begin{aligned} \mathcal{R}(A, B) &\geq \mathcal{R}(A, B \cap \ell_2) \\ &= |\{(b-a)(-\kappa b + c - \kappa a) \mid a \in A_0, b \in B_0\}| \\ &= |\{(\kappa a^2 - ca) - (\kappa b^2 - cb) \mid a \in A_0, b \in B_0\}| \\ &= |f(A_0) - f(B_0)|, \end{aligned}$$

where $f(x) = \kappa x^2 - cx$. Since f is a strictly convex function we can apply Theorem 4 with $U = A_0$ and $V = B_0$ to deduce that

$$\begin{aligned} \mathcal{R}(P)^{11} &\geq \mathcal{R}(A)^5 \mathcal{R}(A, B)^6 \\ &\geq \frac{1}{2} |A_0 - A_0|^5 |f(A_0) - f(B_0)|^6 \\ &= \Omega^*(|A_0|^{11} |B_0|^3). \end{aligned}$$

Applying the hypothesis that $\mathcal{R}(P) = O(n)$, it follows that

$$k \leq 2|B_0| = O^* \left(\frac{n^{11/3}}{|A|^{11/3}} \right) = O^* \left(\frac{n^{11/3}}{m^{11/3}} \right),$$

which establishes (16).

Combining (16) with (15), it follows that

$$\begin{aligned} |Q^{(2)}| &= O^*(k^{1/3} m^{4/3} n^{4/3} + k^{2/11} m^{12/11} n^{18/11} + km^2 + n^2) \\ &= O^*(m^{1/9} n^{23/9} + m^{14/33} n^{76/33} + n^{11/3} / m^{5/3}). \end{aligned}$$

Recalling from (10) that $|Q^{(2)}| \geq m^2 n$, we have

$$m^2 n = O^*(m^{1/9} n^{23/9} + m^{14/33} n^{76/33} + n^{11/3} / m^{5/3}),$$

which implies, as before, that $|A| = m = O^*(n^{43/52})$, as required. \square

Appendix: Convexity and sumsets: Unbalanced version

In this appendix we give the proof of Theorem 4, by spelling out³ the details of the analysis in Li and Roche-Newton [12], adapted to the unbalanced case in which $|U|$ and $|V|$ are not necessarily comparable.

³The proofs in the appendix largely follow the work of [12]. The only exception is Lemma 7, the proof of which has been simplified from its original presentation. We are grateful to Misha Rudnev for explaining this simplification.

Preliminary results

One of the tools needed for the proof of Theorem 4 is a generalization of the notion of the energy of a set. The *additive energy* of a finite set $A \subset \mathbb{R}$, denoted $E_2(A)$, is the number of solutions to the equation

$$a - b = c - d, \quad a, b, c, d \in A.$$

This quantity can be rewritten as

$$E_2(A) = \sum_x r_{A-A}^2(x),$$

where $r_{A-A}(x) := |\{(a, b) \in A \times A \mid a - b = x\}|$ is the number of representations of x in $A - A$. Similarly, define, for any positive rational k ,

$$E_k(A) := \sum_x r_{A-A}^k(x), \quad \text{and}$$

$$E_k(A, B) := \sum_x r_{A-B}^k(x).$$

For $k = 2$ we drop the index, and write $E(A)$ for $E_2(A)$ and $E(A, B)$ for $E_2(A, B)$.

We need the following result, which was originally established in Li [11, Lemma 2.4, Lemma 2.5].

Lemma 5. *Let A, B be finite subsets of a field \mathbb{F} . Then*

$$E_{1.5}(A)^2 \cdot |B|^2 \leq E_3(A)^{2/3} \cdot E_3(B)^{1/3} \cdot E(A, A - B).$$

The other tool that will be used is the following well-known variant of the Szemerédi–Trotter Theorem for pseudo-lines (or pseudo-segments), which is a special case of [20, Theorem 8].

Lemma 6. *Let P be a finite set of points and let L be a finite family of simple⁴ curves in \mathbb{R}^2 with the property that any pair of curves intersect in at most one point. Then*

$$I(P, L) = O\left(|P|^{2/3}|L|^{2/3} + |P| + |L|\right).$$

In particular, it follows that, for any integer $t \geq 2$, the set P_t of all points $p \in \mathbb{R}^2$ that are incident to at least t lines of L satisfies

$$|P_t| = O\left(\frac{|L|^2}{t^3} + \frac{|L|}{t}\right).$$

Energy bounds

Lemma 7. *Let f be a continuous, strictly convex (or concave) function on the reals, and $A, B, C \subset \mathbb{R}$ be finite sets. Then, for all $0 < t \leq \min\{|A|, |B|\}$,*

$$|\{x \in \mathbb{R} \mid r_{A-B}(x) \geq t\}| = O\left(\frac{|f(A) + C|^2 |B|^2}{|C| t^3}\right). \quad (20)$$

⁴A planar curve is said to be *simple* if it is an injective image of a continuous map from $[0, 1]$ into \mathbb{R}^2 .

Proof. Define $l_{s,b}$ to be the curve with equation $y = -f(x+b) + s$, and put

$$L := \{l_{s,b} \mid (s,b) \in (f(A) + C) \times B\}.$$

Note that $|L| = |f(A) + C||B|$. Since the lemma is trivially true for $t < 2$ (because the left-hand side is at most $|A - B| \leq |A| \cdot |B|$, which is dominated by the right-hand side), we may assume that $t \geq 2$. Let P_t denote the set of points in \mathbb{R}^2 that are incident to at least t curves from L . The curves in L satisfy the conditions of Lemma 6. Indeed, let $(b, s) \neq (b', s') \in \mathbb{R}^2$. If $b = b'$, then clearly $l_{s,b} \cap l_{s',b'}$ is empty. Otherwise, assume without loss of generality that $b' > b$, and put $h(x) := f(x+b') - f(x+b) + s - s'$. A point $(x, y) \in l_{s,b} \cap l_{s',b'}$ satisfies $h(x) = 0$. It is a consequence of the convexity of f that h is a monotone function, and the equation $h(x) = 0$ has therefore at most one solution. Therefore, Lemma 6 implies that

$$|P_t| = O\left(\frac{|f(A) + C|^2|B|^2}{t^3} + \frac{|f(A) + C||B|}{t}\right). \quad (21)$$

We may assume that the first term in (21) is greater than or equal to one quarter of the second term. Indeed, otherwise we would have

$$t > 2|f(A) + C|^{1/2}|B|^{1/2} \geq 2|f(A)|^{1/2}|B|^{1/2} \geq \min\{|A|, 2|B|\}.$$

Since there does not exist an x with $r_{A-B}(x) > \min\{|A|, |B|\}$, the left-hand side of (20) is 0 in this case, making the bound trivial. We can therefore assume that

$$|P_t| = O\left(\frac{|f(A) + C|^2|B|^2}{t^3}\right). \quad (22)$$

Now, take any $x \in \mathbb{R}$ that satisfies $r_{A-B}(x) \geq t$. Then there exist $(a_1, b_1), \dots, (a_t, b_t) \in A \times B$, such that $x = a_1 - b_1 = \dots = a_t - b_t$. It follows that, for any $c \in C$, and $1 \leq i \leq t$,

$$c = -f(x + b_i) + f(a_i) + c,$$

which implies that $(x, c) \in l_{f(a_i)+c, b_i}$ for all $1 \leq i \leq t$. Therefore $(x, c) \in P_t$ and so

$$|C| \cdot |\{x \mid r_{A-B}(x) \geq t\}| \leq |P_t| = O\left(\frac{|f(A) + C|^2|B|^2}{t^3}\right),$$

which completes the proof. \square

By applying Lemma 7 carefully, we obtain the following corollary.

Corollary 8. *Let f be a continuous, strictly convex or concave function on the reals, and let $A, C, F \subset \mathbb{R}$ be finite sets. Then*

$$E_3(A) = O(|f(A) + C|^2|A|^2|C|^{-1} \log |A|), \quad (23)$$

$$E(A, F) = O(|f(A) + C||F|^{3/2}|A|^{1/2}|C|^{-1/2}). \quad (24)$$

Proof. Applying Lemma 7 with $B = A$, gives

$$\begin{aligned} E_3(A) &= \sum_{j=0}^{\lfloor \log |A| \rfloor} \sum_{\{s \mid 2^j \leq r_{A-A}(s) < 2^{j+1}\}} r_{A-A}^3(s) \\ &= O\left(\sum_{j=0}^{\lfloor \log |A| \rfloor} \frac{|f(A) + C|^2|A|^2}{|C|2^{3j}} \cdot 2^{3j}\right) = O\left(\frac{|f(A) + C|^2|A|^2 \log |A|}{|C|}\right), \end{aligned}$$

which proves (23).

Similarly, applying Lemma 7 with $B = F$ and with any fixed real parameter $\Delta \geq 1$, gives

$$\begin{aligned} E(A, F) &= \sum_{\{s \mid r_{A-F}(s) < \Delta\}} r_{A-F}^2(s) + \sum_{j=0}^{\lfloor \log(|A|/\Delta) \rfloor} \sum_{\{s \mid 2^j \Delta \leq r_{A-F}(s) < 2^{j+1} \Delta\}} r_{A-F}^2(s) \\ &= O \left(\Delta \cdot E_1(A, F) + \sum_{j=0}^{\lfloor \log(|A|/\Delta) \rfloor} \frac{|f(A) + C|^2 |F|^2}{|C| 2^{3j} \Delta^3} \cdot 2^{2j} \Delta^2 \right) \\ &= O \left(\Delta |A| |F| + \frac{|f(A) + C|^2 |F|^2}{|C| \Delta} \right). \end{aligned}$$

Choosing $\Delta = \frac{|f(A) + C| |F|^{1/2}}{|A|^{1/2} |C|^{1/2}}$, which is clearly ≥ 1 , yields (24). \square

Proof of Theorem 4

First, apply Hölder's inequality to bound $E_{1.5}(U)$ from below, as follows.

$$|U|^6 = \left(\sum_{s \in U-U} r_{U-U}(s) \right)^3 \leq \left(\sum_{s \in U-U} r_{U-U}^{1.5}(s) \right)^2 |U - U| = E_{1.5}(U)^2 |U - U|.$$

Therefore, using the above bound and Lemma 5 with $A = B = U$, gives

$$\frac{|U|^8}{|U - U|} \leq E_{1.5}(U)^2 |U|^2 \leq E_3(U) E(U, U - U).$$

Finally, apply (23) and (24), with $A = U$, $C = V$, and $F = U - U$, to conclude that

$$\frac{|U|^8}{|U - U|} = O \left(|f(U) + V|^3 |U - U|^{3/2} |U|^{5/2} |V|^{-3/2} \log |U| \right),$$

and hence

$$|f(U) + V|^6 |U - U|^5 = \Omega \left(\frac{|U|^{11} |V|^3}{\log^2 |U|} \right),$$

as required. \square

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