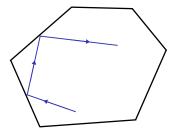
# Orbifolds and systolic inequalities

Christian Lange

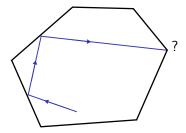
Ludwig Maximilian University of Munich

Symplectic Zoominar - January 13, 2023

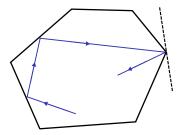
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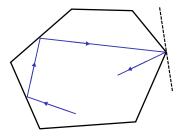


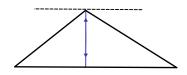


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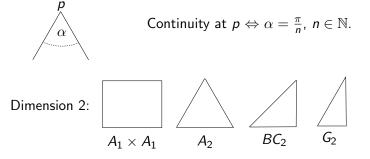
#### Question

Which polyhedral convex bodies admit a continuous billiard dynamic?

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# From billiards to orbifolds

Question: Which polyhedral convex bodies admit a continuous billiard dynamic?



#### Theorem

A polyhedral convex body in  $\mathbb{R}^n$  admits a continuous billiard dynamic if and only if it is a Riemannian orbifold.

cf. L., On continuous billiard and quasigeodesic flows characterizing alcoves and isosceles tetrahedra.

# Riemannian orbifolds

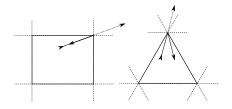
A polyhedral convex body in  $\mathbb{R}^n$  admits a continuous billiard flow if and only if it is a Riemannian orbifold.

#### Definition

A *Riemannian orbifold* of dimension *n* is a metric length space O such that for each point  $x \in O$  there exists

- an open neighborhood U of x in  $\mathcal{O}$
- ▶ a Riemannian *n*-manifold *M*
- a finite group G that acts by isometries on M

for which U and M/G are isometric.



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# Systolic geometry





# Systolic geometry



The so-called Calabi–Croke sphere  $\Delta \cup_{\partial \Delta} \Delta$  is a Riemannian orbifold.



Theorem (Croke, 1988)

Let  $L_{\min}$  be the length of the shortest nontrivial closed geodesic on a Riemannian 2-sphere S<sup>2</sup>. Then  $\rho(S^2) := \frac{L_{\min}^2}{\operatorname{area}} < 32$ .

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$$\rho(S_{\text{round}}^2) = \pi < 2\sqrt{3} = \rho(S_{\text{Calabi-Croke}}^2).$$

#### Observation

The Calabi–Croke sphere is the global maximizer for the systolic ratio among Riemannian orbifolds of type  $S^2(3,3,3)$ .

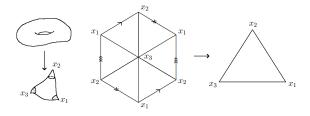
## Loewner's theorem and Calabi-Croke's sphere

Theorem (Loewner, 1949)

The systole, i.e. the length of a shortest non-contractible closed geodesic, of a Riemannian 2-torus  $T^2$  satisfies

$$\operatorname{sys}^2 \leq \frac{2}{\sqrt{3}} \operatorname{area}(\mathbb{T}^2)$$

with equality if and only if  $\mathbb{T}^2$  is an equilateral torus. Proof (that the Calabi–Croke metric maximizes  $\rho$  on  $S^2(3,3,3)$ )



 $\operatorname{area}(\mathbb{T}^2) = \operatorname{3area}(S^2(3,3,3)), \quad L_{\min}(S^2(3,3,3)) \leq \operatorname{sys}(\mathbb{T}^2) \square.$ 

# Local maximizers and Zoll metrics

Theorem (Abbondandolo, Bramham, Hryniewicz, Salomão '18) Zoll metrics on  $S^2$  are local maximizers of the systolic ratio  $\rho$  with respect to the  $C^3$  topology.

Zoll means that all geodesics are closed and have the same length (picture by K. Polthier & M. Schmies).



## Theorem (ABHS, 2021)

The systolic ratio of a sphere of revolution in  $\mathbb{R}^3$  does not exceed  $\pi$ . It equals  $\pi$  if and only if S is Zoll.

Let  $L_{contr}$  be the length of shortest nontrivial closed geodesic whose lift to the unit sphere bundle is contractible.

#### Conjecture

$$\rho_{\text{contr}}(S^2) := \frac{L_{\text{contr}}(S^2)^2}{\operatorname{area}(S^2)} \le \rho_{\text{contr}}(S^2_{\text{round}}) = 4\pi$$
 for Riemannian  $S^2$ .

## Theorem (L., Soethe, 2023)

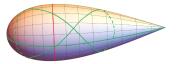
The contractible systolic ratio of a rotationally symmetric Riemannian 2-sphere S does not exceed  $4\pi$ . It equals  $4\pi$  if and only if S is Zoll.

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Theorem (L., Soethe, 2023) Let  $\mathcal{O} = S^2(m, n)$  be a rotationally symmetric spindle orbifold. Then

 $\rho_{\text{contr}}(\mathcal{O}) \leq 2(m+n)\pi$ 

with equality if and only if  $\mathcal{O}$  is Besse.



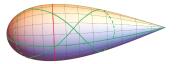
Besse  $\mathcal{O} = S^2(3, 1)$ orbifold in  $\mathbb{R}^3$  (picture K. P.

Besse means that all geodesics are periodic. In this case there exists a common period due to a theorem by Wadsley.

Theorem (L., Soethe, 2023) Let  $\mathcal{O} = S^2(m, n)$  be a rotationally symmetric spindle orbifold. Then

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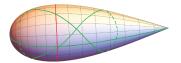
Besse: the geodesic flow is periodic.

For k ∈ N we set L<sub>k</sub> to be the infimum of all lengths l > 0 such that there are at least k closed geodesics of length ≤ l and ρ<sub>k</sub> = L<sup>2</sup><sub>k</sub>/area.

Theorem (L., Soethe, 2023) Let  $\mathcal{O} = S^2(m, n)$  be a rotationally symmetric spindle orbifold. There are  $k = k(m + n) \in \mathbb{N}$  and C = C(m + n) > 0 such that

a) 
$$ho_{ ext{contr}}(\mathcal{O}) \leq 2(m+n)\pi$$
 and b)  $ho_k(\mathcal{O}) \leq \mathcal{C},$ 

each with equality if and only if  $\mathcal{O}$  is Besse.



Besse  $\mathcal{O} = S^2(3, 1)$ orbifold in  $\mathbb{R}^3$  (picture K. P.

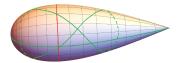
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each with equality if and only if  $\mathcal{O}$  is Besse.



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Remark

certain Weyl Besse  $S^2(m, n)$  orbifolds

Finsler 2-spheres of constant flag curvature 1

see L.-Mettler, Deformations of the Veronese Embedding and Finsler 2-Spheres of Constant Curvature.

# Besse $S^2(3,1)$ Tannery surface



Figure: Picture by Konrad Polthier and Markus Schmies.

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# Systolic ratio for contact manifolds

- (M, λ) closed contact (2n − 1)-manifold, i.e. λ ∧ dλ<sup>n−1</sup> is a volume form.
- Volume of  $(M, \lambda)$ : vol $(M, \alpha) = \int_M \lambda \wedge d\lambda^{n-1}$ .
- Reeb vector field  $R_{\lambda}$ :  $\iota_{R_{\lambda}} d\lambda = 0$ ,  $\iota_{R_{\lambda}} \lambda = 1$ .
- Systolic ratio of  $(M, \lambda)$ :

$$\rho(M,\lambda) = \frac{T_{\min}(\lambda)^n}{\operatorname{vol}(M,\alpha)}.$$

 $T_{\min}$  := minimum of all periods of closed orbits of  $R_{\lambda}$  (if such exist like for 2n - 1 = 3 by Taubes' theorem).

#### Example

The unit tangent bundle  $T^1\mathcal{O}$  of a Riemannian orbifold  $\mathcal{O}$  with isolated singularities (like  $S^2(m, n)$ ) equipped with the Liouville  $\lambda_L$  form. Here  $R_{\lambda_L}$  = geodesic vector field,  $\operatorname{vol}(T^1\mathcal{O}, \lambda_L) = 2\pi \operatorname{vol}(\mathcal{O})$ .

## Systolic inequalities for Reeb flows

Alvarez Paiva, Balacheff, 2014: Local maximizers of  $\rho$  are Zoll.

Theorem (ABHS '18 for  $S^3$ , Benedetti–Kang for  $M^3$  '21, Abbondandolo–Benedetti, 2019)

A Zoll contact form  $\lambda_0$  on a connected closed (2n-1)-manifold M has a  $C^3$  neighborhood  $\mathcal{U}$  such that  $\rho(\lambda) \leq \rho(\lambda_0)$  for all  $\lambda \in \mathcal{U}$  with equality if and only if  $\lambda$  is Zoll.

#### Corollary (local sharp Viterbo conjecture)

There is a  $C^3$ -neigborhood  $\mathcal{U}$  of the smooth ball in the space of smooth convex bounded open subsets of  $\mathbb{R}^{2n}$  such that

$$T_{\min}(\lambda_0|_{\partial C})^n (= c_{\mathrm{EHZ}}^n) \leq \mathrm{vol}(C, (d\lambda_0)) \;\; \forall C \in \mathcal{U}$$

with equality if and only if C is symplectomorphic to a ball.

Higher systolic inequalities and Besse Reeb flows

For a (2n-1)-contact manifold  $(M, \lambda)$  we define higher systolic ratios for  $k \in \mathbb{N}$ :

$$\rho_k(\lambda) = \frac{\tau_k(\lambda)^n}{\operatorname{vol}(M, \lambda \wedge d\lambda)}$$

where

 $au_k(\lambda) = \inf\{t \mid \exists \ge k \text{ closed Reeb orbits of period } < t\}$ 

if there exists a closed Reeb orbit.

Observation: Local maximizers of  $\rho_k$  are Besse, i.e. all Reeb orbits are closed and have a common period.

### Besse Reeb flows

#### Examples

► The standard Liouville 1-form  $\lambda_0 = \frac{1}{2} \sum_{j=1}^n (x_j dy_j - y_j dx_j)$  restricted to the boundary of the solid ellipsoid

$$E(p_1,...,p_n) = \left\{ z \in \mathbb{C}^n \left| \left| \sum_{j=1}^n \frac{|z_j|^2}{p_j} \leq \frac{1}{\pi} \right. 
ight\} \subset \mathbb{C}^n = \mathbb{R}^{2n}.$$

for coprime integers  $p_1, \ldots, p_n \in \mathbb{N}$ .

- Unit cotangent bundles of Besse orbifolds with isolated singularities.
- ► Ustilovsky '99: For n ≥ 3 there are infinitely many pairwise non-contactomorphic Besse contact spheres (S<sup>2n-1</sup>, λ).

### Spectral characterizations of contact Besse manifolds

Action spectrum:  $\sigma(M, \lambda) = \{T(\gamma) \mid \gamma \text{ periodic Reeb orbit}\}$ with  $T(\gamma)$  the period of a periodic Reeb orbit  $\gamma$  of  $(M, \lambda)$ . Theorem (Cristofaro-Gardiner, Mazzucchelli, 2019) A closed contact manifold  $(M^3, \lambda)$  is Besse if and only if  $\sigma(M, \lambda) \subset r\mathbb{N}$  for some r > 0.

 $(Y^{2n+1},\lambda) \subset \mathbb{C}^{n+1}$  convex contact sphere.

Ekeland-Hofer action selectors:  $c_k = c_k(Y) \in \sigma(Y, \lambda)$ .

 $\min \sigma(Y,\lambda) = c_1 \leq c_2 \leq c_3 \leq \dots$ 

Theorem (Ginzburg, Gürel, Mazzucchelli, 2019) ( $Y^{2n+1}$ ,  $\lambda$ ) is Besse if and only if  $c_k = c_{k+n}$  for some k.

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## Boothby–Wang construction

 $(M, \lambda)$  Besse contact (2n - 1) manifold.

- Reeb flow induces an almost free (i.e. with finite stabilizers)  $S^1$ -action on M with an orbifold quotient  $\pi: M \to M/S^1$ .
- $M/S^1$  has an integral symplectic form represented by the image  $i(\hat{e}) \in H^2_{S^1}(M; \mathbb{R})$  of the Euler class  $\hat{e} \in H^2_{S^1}(M; \mathbb{Z})$  of  $\pi$  such that  $d\lambda = T_{mc}(\lambda)\pi^*w$ , where  $T_{mc}$  is the minimal common period.
- The Euler class e induces isomorphisms (Gysin sequence)

$$\hat{e} \cup \cdot : H^{i}_{S^{1}}(M;\mathbb{Z}) \to H^{i+2}_{S^{1}}(M;\mathbb{Z})$$
(1)

for all  $i \geq 2n - 1$ .

Remark: The construction can be seen as a special case of a symplectic reduction (applied to  $(M \times \mathbb{R}_{>0}, d(r\lambda))$  with the trivially extended  $S^1$ -action and the Hamiltonian H(x, t) = t). In general a symplectic reduction gives rise to symplectic orbifolds.

# Orbifold cohomology

- ► Every (Riemannian) orbifold O can be realized as the quotient of an almost free (isometric) action of a compact Lie group G on a (Riemannian) manifold M (take the orthonormal frame bundle M = Fr(O) and G = O(n)).
- Then H<sup>\*</sup><sub>orb</sub>(O) := H<sup>\*</sup><sub>G</sub>(M) is independent of the representation M/G of O.
- If M is contractible and G is finite (like for an orbifold chart) then H<sup>\*</sup><sub>G</sub>(M) = H<sup>\*</sup>(G) is nontrivial in infinitely many degrees.

How to recognize manifolds among orbifolds?

#### Theorem (Quillen, 1971)

An n-dimensional orbifold  $\mathcal{O}$  is a manifold if and only if  $H^i_{orb}(\mathcal{O}) = 0$  for all i > n.

# Recognizing manifolds among orbifolds

Some consequences of Quillen's characterization:

#### Theorem (Amann, L., Radeschi, 2021)

Odd-dimensional simply connected Besse orbifolds are manifolds.

Here "simply connected" refers to the orbifold fundamental group.

### Theorem (L., Radeschi, 2022)

An n-connected n-orbifold is a manifold for  $n \ge 1$ . A compact 2n-connected (2n + 1)-orbifold is a manifold for  $n \ge 1$ . A compact (2n - 2)-connected 2n-orbifold is a manifold for  $n \ge 3$ .

Remark: For  $n \ge 4$  there exist compact  $\lfloor n/2 - 1 \rfloor$ -connected bad (i.e. not covered by a manifold) *n*-orbifolds [L., Radeschi, 2022].

### Converse Boothby–Wang construction

Conversely, if  $(\mathcal{O}, \omega)$  is a symplectic (2n - 2)-orbifold with integral symplectic form  $[\omega] \in \operatorname{Im}(H^2_{orb}(\mathcal{O}; \mathbb{Z}) \to H^2_{orb}(\mathcal{O}; \mathbb{R}))$ , then for each integral lift  $\hat{e} \in H^2_{orb}(\mathcal{O}; \mathbb{Z})$  of w for which (cf. L.–Kegel)

$$\hat{e} \cup \cdot : H^{i}_{orb}(\mathcal{O}; \mathbb{Z}) \to H^{i+2}_{orb}(\mathcal{O}; \mathbb{Z})$$
 (2)

is an isomorphism for all  $i \ge 2n - 1$ , there exists a contact (2n - 1)-manifold  $(M, \lambda)$  such that

- $(M, \lambda)$  has Euler class  $\hat{e}$ ,
- the reverse construction above gives rise to  $(\mathcal{O}, \omega)$ .

Dimension 3: An almost free  $S^1$ -action on an orientable 3-manifold M with Euler class  $\hat{e}$  can be realized by a Reeb flow if and only if its Euler number  $e = \langle \hat{e}, [M/S^1] \rangle$  is negative.

## Besse 3-manifolds and higher systolic inequalities

 $(M, \lambda)$  be a closed Besse contact 3-manifold. Recall that for  $k \in \mathbb{N}$  we defined  $\rho_k(M, \lambda) = \frac{\tau_k(\lambda)^2}{\operatorname{vol}(M, \lambda \land d\lambda)}$  with

 $\tau_k(\lambda) = \inf\{t \mid \exists \ge k \text{ closed Reeb orbits of period } < t\}.$ 

► there are finitely many singular Reeb orbits γ<sub>1</sub>,..., γ<sub>h</sub> with multiplicities α<sub>1</sub>,..., α<sub>h</sub>. Set k<sub>0</sub>(λ) = α<sub>1</sub> + ... + α<sub>h</sub> − h + 1.

$$T_{\min} = \tau_1(\lambda) \le \tau_2(\lambda) \le \ldots \le \tau_{k_0}(\lambda) = \tau_{k_0+1}(\lambda) = \ldots$$

Theorem (Abbondandolo, L., Mazzucchelli, 2022)

Let Y be a closed connected orientable 3-manifold and k a positive integer.

i) If a contact form  $\lambda_0$  on Y is a local maximizer of  $\rho_k$ , then  $\lambda_0$  is Besse and  $k_0(\lambda_0) = k$ .

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Besse 3-manifolds and higher systolic inequalities

Theorem (Abbondandolo, L., Mazzucchelli, 2022)

Let Y be a closed, connected, orientable 3-manifold and k a positive integer.

- i) If a contact form λ<sub>0</sub> on Y is a local maximizer of ρ<sub>k</sub>, then λ<sub>0</sub> is Besse and k<sub>0</sub>(λ<sub>0</sub>) = k.
- ii) Every Besse contact form  $\lambda_0$  on Y with  $k_0(\lambda_0) = k$  has a  $C^3$ -neighborhood  $\mathcal{U}$  in the space of contact forms on Y such that

$$\rho_k(\lambda) \leq \rho_k(\lambda_0) = -\frac{1}{e(\lambda_0)}, \quad \forall \lambda \in \mathcal{U},$$

with equality if and only if  $\lambda$  is Besse.

Remarks:

- All ρ<sub>k</sub> ≥ ρ<sub>1</sub> are unbounded on the space of contact forms inducing a given contact structure ξ on Y [Sağlam, 2021].
- ► All  $\rho_k \leq k^2 \rho_1$  are bounded on the space of smooth convex contact spheres.

### Example: Ellipsoids

Let  $p,q \in \mathbb{N}$  be coprime. Consider the boundary of an ellipsoid

$$E(p,q)=\left\{z\in\mathbb{C}^n \ \Big| \ rac{|z_1|^2}{p}+rac{|z_2|^2}{q}\leqrac{1}{\pi}
ight\}\subset\mathbb{C}^=\mathbb{R}^4.$$

equipped with the restriction  $\lambda_{p,q}$  of the standard Liouville 1-form  $\lambda_0 = \frac{1}{2} \sum_{j=1}^{2} (x_j dy_j - y_j dx_j)$ 

One closed orbit of minimal period p, one closed orbit of minimal period q, all other orbits have minimal period pq. Hence,

$$k_0(\lambda_{p,q})=p+q-1.$$

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Moreover, vol(E(p,q)) = pq and hence  $\rho_{k_0}(\lambda_{p,q}) = pq$ .

Comments on the proof of ii) - global surfaces of sections

Like in the Zoll case the proof uses global surfaces of sections. For us a global surface of section for a contact 3-manifold  $(Y, \lambda)$  is a smooth map  $\iota : \Sigma \to Y$  from an oriented connected compact surface with non-empty boundary such that

- (Boundary) The restriction  $\iota|_{\partial\Sigma}$  is an immersion positively tangent to the Reeb vector field  $R_{\lambda}$
- (Transversality) The restriction  $\iota|_{int(\Sigma)}$  is an embedding into  $Y \setminus (\partial \Sigma)$  transverse to the Reeb vector field  $R_{\lambda}$ .
- (Globality) Reeb orbits starting in any y ∈ Y intersect Σ in both positive and negative time.

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Comments on the proof of ii) - proof in the Zoll case

For  $S^3$  in the Zoll case the proof works by contradiction:

- 1. Suppose contact forms  $\lambda$  arbitrarily close to a Zoll contact form  $\lambda_0$  violate the systolic inequality.
- 2. Find a global surface of section  $\iota : \Sigma = D^2 \to Y$  for  $\lambda$  bounding a Reeb orbit  $\gamma_m$  of minimal period  $T_{\min}$  of  $\lambda$  such that the first return map  $\phi : \Sigma \to \Sigma$  is close to the identity.
- 3. Find a fixed point of the first return map  $\phi : \Sigma \to \Sigma$  with period  $< T_{min}$ .

Step 2 is problematic in the Besse case if the minimal Reeb orbit of  $\lambda$  bifurcates from the regular orbits but approaches an iterate of a singular orbit of  $\lambda_0$  when  $\lambda$  becomes closer to  $\lambda_0$ .

# Comments on the proof of ii) - problems in the Besse case

Step 2 is problematic in the Besse case if the minimal Reeb orbit of  $\lambda$  bifurcates from the regular orbits but approaches an iterate of a singular orbit of  $\lambda_0$  when  $\lambda$  becomes closer to  $\lambda_0$ .

In this case the topology of  $\Sigma$  jumps in the limit and one cannot control the  $C^k$  norms of the first return map.

Example: Ellipsoid E(2,3)

 A global surface of section bounding an interate of a singular orbit covers D<sup>2</sup>(2) (or D<sup>2</sup>(3)) and is hence a disk.



 A global surface of section bounding a regular orbit covers D<sup>2</sup>(2, 3) and is hence hyperbolic.



Comments on the proof of ii) - strategy in the Besse case

Step 2 is problematic in the Besse case if the minimal Reeb orbit of  $\lambda$  bifurcates from the regular orbits but approaches an iterate of a singular orbit of  $\lambda_0$  when  $\lambda$  becomes closer to  $\lambda_0$ .

Instead we prove

Theorem (Abbondandolo, L., Mazzucchelli, 2022)

If  $(Y, \lambda_0)$  is Besse and  $\gamma$  is any orbit of  $R_{\lambda_0}$ , then there exists a global surface of section with  $\iota(\partial \Sigma) = \gamma$  (with explicit control on the topology).

as well as a stronger fixed point theorem for the Calabi homomorphism  $\operatorname{Cal}: \operatorname{Ham}_0(\Sigma, \iota^*\lambda) \to \mathbb{R}$  that can also be applied if the bounding orbit  $\gamma$  is not minimal. (Here, the condition that  $\partial\Sigma$  covers a single Reeb orbit is needed to assure that a required vanishing flux condition is satisfied.)