Maslov index formula in Heegaard Floer homology

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Symplectic Zoominar 21 April, 2023





Heegaard Floer Homology



2 Maslov index formula



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Setup

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- In our notation (Σ, α, β) is an *(unpointed)* Heegaard diagram.

Remark

In literature, by Heegaard diagram people call the above data together with a collection of k - g + 1 points in different connected regions of $\Sigma \setminus (\alpha \cup \beta)$.

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Generators

Each collection of points $\mathbf{x} = \{x_1, \dots, x_k\}$ where $x_i \in \alpha_i \cap \beta_{\sigma(i)}, \sigma \in S_k$ serves as a generator.

It can be regarded as a point $x \in T_{\alpha} \cap T_{\beta} \subset Sym^{k}(\Sigma)$.



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Differential

• Consider a space $W = \mathbb{R} \times [0, 1] \times \Sigma$ with a *nice* almost complex structure *J*. Let $C_{\alpha} = \mathbb{R} \times \{1\} \times \alpha$ and $C_{\beta} = \mathbb{R} \times \{0\} \times \beta$.

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- For two generators x and y denote by π₂(x, y) the set of homology classes of maps (S, ∂S) → (W, C_α ∪ C_β) converging to x (to y) near the negative punctures (positive punctures) where (S, ∂S) ∈ M.

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- Differential ∂(x) in CF (and its versions) is given by the count of points in M^φ/ℝ for those y and φ satisfying dim(M^φ) = 1 (sometime other dimensions are considered as well).

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- Differential ∂(x) in CF (and its versions) is given by the count of points in *M*^φ/ℝ for those y and φ satisfying dim(*M*^φ) = 1 (sometime other dimensions are considered as well).
- Due to Ozsváth-Szabó $\dim(\mathcal{M}^{\varphi})$ only depends on φ . It is called *Maslov* index of φ and denoted $\mu(\varphi)$.

Heegaard Floer Homology

2 Maslov index formula

Combinatorial proof

Robert Lipshitz found a way to compute $\mu(\varphi)$ for $\varphi \in \pi_2(\mathbf{x}, \mathbf{y})$ in terms of combinatorial data of a Heegaard diagram. This formula is now used everywhere.

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- For a region R the Euler measure e(R) is defined to be $\frac{1}{2\pi}$ times the integral over R of the curvature of the metric. It is equal to the 2-cochain that assigns $\frac{1}{2}(2-n)$ to a 2n-gon region

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Theorem (Lipshitz, 2006)

$$\mu(\varphi) = e(D(\varphi)) + n_{\mathbf{x}}(\varphi) + n_{\mathbf{y}}(\varphi)$$



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Introduce a *combinatorial index* of a domain $D \in \mathcal{D}(\mathbf{x}, \mathbf{y})$ via

$$\widetilde{\mu}(D) := n_x(D) + n_y(D) + e(D)$$

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Combinatorial index and Maslov index share several common properties

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Additivity of index:

(Sarkar, 2006) :
$$\tilde{\mu}(D * D') = \tilde{\mu}(D) + \tilde{\mu}(D')$$
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 Stability: index is preserved under isotopies and empty stabilizations of a Heegaard diagram.



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Theorem 1

There exists a unique index $\overline{\mu} \colon \mathcal{D} \to \mathbb{Z}$ satisfying the following axioms:

- $\bullet \ \overline{\mu} \text{ is additive;}$
- $\ \, \textcircled{} \ \, \overline{\mu} \ \, \text{is stable};$
- $\ \, {\overline{\mu}}(B)=1 \ \text{for any bigon} \ B\in \mathcal{D};$
- $\overline{\mu}(R) = 1$ for any rectangle $R \in \mathcal{D}$.

Moreover, this index agrees with the combinatorial index $\widetilde{\mu},$ and for a Whitney disk φ

 $\mu(\varphi) = \widetilde{\mu}(D(\varphi)).$

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Theorem 2 (Decomposition)

For a given domain D in a Heegaard diagram (Σ, α, β) there is a sequence of finger moves and empty stabilizations such that in the new Heegaard diagram the image of D can be represented as a composition of bigons, rectangles and their negatives.

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Proof of Theorem 1

Aplly Theorem 2 to a $D \in \mathcal{D}(\mathbf{x}, \mathbf{y})$ to get some D'. Decompose $D' = D_1 * \ldots * D_k$ into bigons and rectangles. Apply additivity $\overline{\mu}(D) = \overline{\mu}(D_1) + \ldots + \overline{\mu}(D_k)$.

Sketch for the Decomposition Theorem

Making the boundary embedded



Sketch for the Decomposition Theorem

Making the boundary connected



Reducing to the quadrangle or a bigon boundary



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Sketch for the Decomposition Theorem Quadrangle boundary





Thank you for your attention!

