

The coarse distance from dynamically convex to convex

Julien Dardennes (joint work with J.Gutt, V.Ramos and J.Zhang)



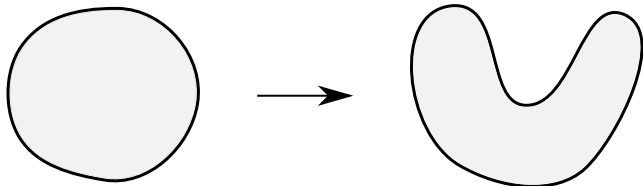
Symplectic convexity

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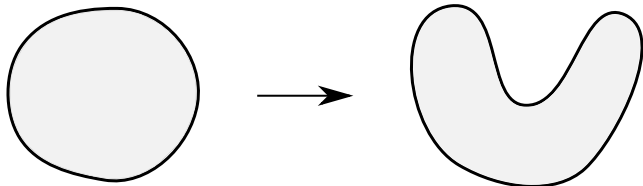
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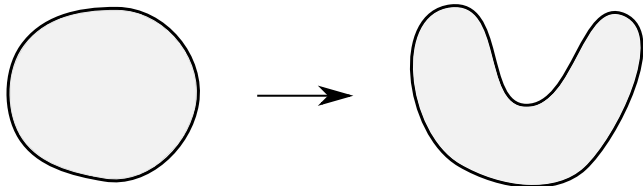


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Definition (symplectically convex domains)

$\mathcal{C}_4 = \{ \text{domains of } \mathbb{R}^4 \text{ which are symplectomorphic to a convex domain} \}$

Dynamical convexity

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Theorem (Chaidez and Edtmair, 2020)

There exists dynamically convex domains of \mathbb{R}^4 which are not symplectically convex.

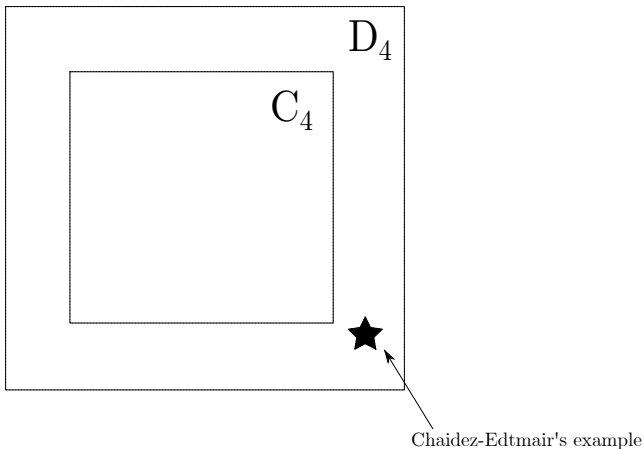


Figure – Relations between C_4 and D_4 .

$C_4 = \{\text{symplectically convex domains of } \mathbb{R}^4\}$

$D_4 = \{\text{dynamically convex domains of } \mathbb{R}^4\}$

Main result

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Theorem (D., Gutt, Ramos and Zhang, 2023)

Dynamically convex domains are arbitrarily far from symplectically convex domains with respect to the coarse symplectic Banach-Mazur distance.

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Remark

These are the first examples of dynamically convex domains which are not symplectically convex without referring to Chaidez-Edtmair's criterion.

Coarse symplectic Banach-Mazur distance

(Ostrover-Polterovich)

For $U, V \subset \mathbb{R}^4$ star-shaped domains, let

$$d_c(U, V) = \inf \left\{ \log \lambda \geq 0 \mid \frac{1}{\lambda} U \hookrightarrow V \hookrightarrow \lambda U \right\}$$

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Open problem

If $d_c(U, V) = 0$, U is symplectomorphic to V ?

A "new" symplectic convexity criterion

Theorem (John, 1948)

Let U be a convex domain of \mathbb{R}^4 , then there exists an ellipsoid $E \subset \mathbb{R}^4$ such that

$$E \subset U \subset o + 4 \cdot (E - o)$$

where o is the center of E .

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Proposition (Symplectic John's ellipsoid theorem)

Let U be a symplectically convex domain of \mathbb{R}^4 , then

$$d_c(U, \mathcal{E}_4) := \inf_{E \in \mathcal{E}_4} d_c(U, E) \leq \log 2$$

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Every toric domain can be written as $X_\Omega = \mu^{-1}(\Omega)$ where $\Omega \subset (\mathbb{R}_{\geq 0})^2$ and

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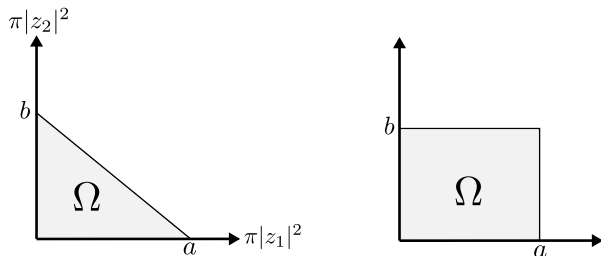


Figure – An ellipsoid $E(a, b)$ and a polydisc $P(a, b)$

Monotone toric domains

Definition

A **monotone toric** domain is a compact toric domain with a smooth boundary such that for every $\mu \in \partial_+ \Omega = \partial \Omega \cap (\mathbb{R}_{>0})^2$ the outward normal vector at μ has non-negative components.

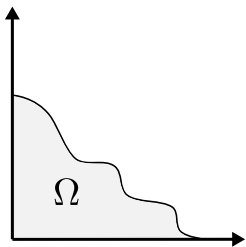


Figure – A monotone toric domain

Proposition (Gutt, Hutchings and Ramos, 2020)

Let $\mathcal{M}_4 = \{\text{Monotone toric domains of } \mathbb{R}^4\} \subset \mathcal{T}_4$

$$\mathcal{M}_4 = \mathcal{D}_4 \cap \mathcal{T}_4$$

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Theorem (D., Gutt and Zhang, 2021)

There exists a family of monotone toric domains of \mathbb{R}^4 which are not symplectically convex.

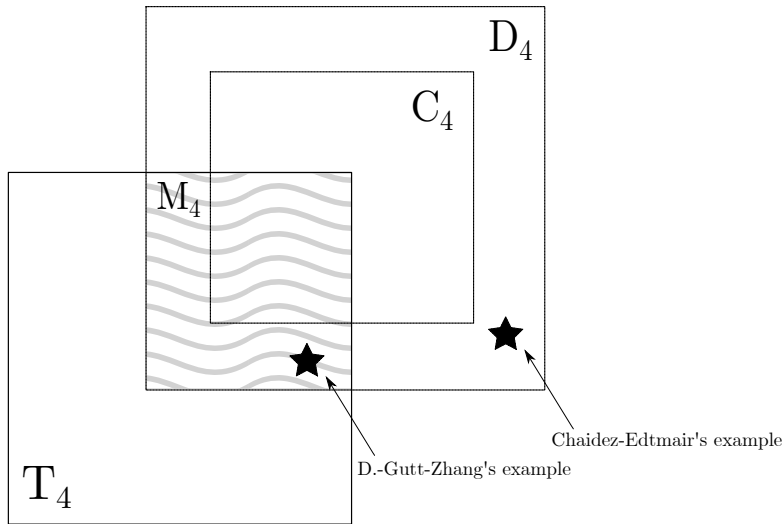


Figure – Relations between T_4 , C_4 , M_4 , and D_4 .

The L^p ball

For $p \in (0, 1]$, let

$$X_{\Omega_p} := \left\{ (z_1, z_2) \in \mathbb{C}^2 \mid \left(\pi |z_1|^2 \right)^p + \left(\pi |z_2|^2 \right)^p < 1 \right\}.$$

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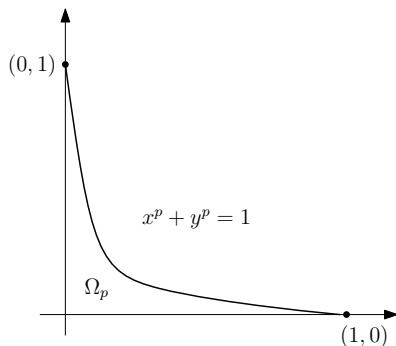


Figure – X_{Ω_p} for $p \in (0, 1]$.

Main result

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Theorem (D., Gutt, Ramos and Zhang, 2023)

For toric domain X_{Ω_p} and $p < \frac{1}{5}$, we have :

$$d_c(X_{\Omega_p}, \mathcal{E}_4) \geq \frac{1}{8} \log \left(\frac{g(p)}{1 + \log 4 + \log g(p)} \right) \quad (1)$$

where $g(p) = 2^{\frac{2}{p}-2} \text{Vol}_{\mathbb{R}^4}(X_{\Omega_p})$.

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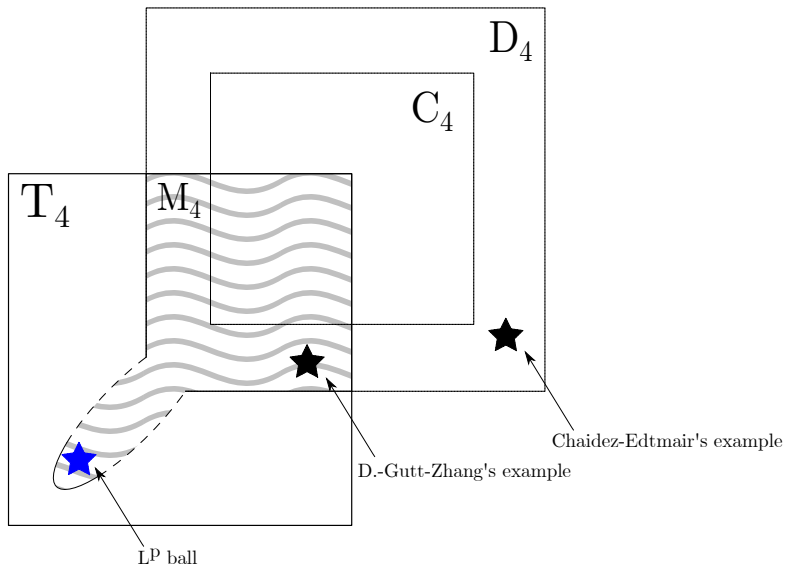
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Corollary

In particular, when p satisfies the condition that

$$\frac{g(p)}{1 + \log 4 + \log g(p)} > 2^8, \quad (2)$$

then X_{Ω_p} is dynamically convex but not symplectically convex.



Tools for the proof

Corollary's proof

Triangular inequality + symplectic John :

$$d_c(X_{\Omega_p}, \mathcal{E}_4) \leq d_c(X_{\Omega_p}, \mathcal{C}_4) + \sup_{U \in \mathcal{C}_4} d_c(U, \mathcal{E}_4)$$

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Theorem's proof : ECH capacities

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Weight decomposition :

$$c_k^{ECH}(X_{\Omega_p}) = c_k^{ECH} \left(\bigsqcup_{i=1}^k B(w_i) \right)$$

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Lemma by Hutchings :

$$c_k^{ECH} \left(\bigsqcup_{i=1}^k B(w_i) \right) \leq 2 \sqrt{k \cdot \text{vol} \left(\bigsqcup_{i=1}^k B(w_i) \right)}$$

Thank you !

Overview

