Deformation of curves on surfaces

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2 Background

3 Ideas and main theorem

 Object to study: Deformation theoretic properties of algebraic curves on surfaces

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Is the moduli space of nodal plane curves of given degree and genus irreducible?Solved affirmatively by Harris (1986).

Related problem:

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- Non-rational curves in very ample classes on K3 surfaces can be deformed to immersion (Dedieu-Sernesi)

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■ S: surface, K_S : ample, $C \in |pK_S|$, $p \ge 2$. If C is nodal and n is small, then $V_{C,n}$ is smooth of expected dimension at C (Chiantini-Sernesi)

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- S: surface, K_S : ample, $C \in |pK_S|$, $p \ge 2$. If C is nodal and n is small, then $V_{C,n}$ is smooth of expected dimension at C (Chiantini-Sernesi)
- $S \subset \mathbb{P}^3$: general surface, $n \leq \dim(|O_S(m)|)$, Then $V_{m,n}$ has at least one component of expected dimension (Chiantini-Ciliberto)

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- Defect: there is no control on the geometry of deformed curves

Rough statement of our result:

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Here we call φ semiregular if the natural map $H^0(S, K_S) \to H^0(C, \varphi^*K_S)$ is surjective



LIdeas and main theorem

Ideas and main theorem

Cohomological pairings as residues

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- The difference between $\tilde{\varphi}_i$ and $\tilde{\varphi}_j$ naturally gives a section of the normal sheaf \mathcal{N}_{φ} on $U_i \cap U_j$
- These form a Čech 1-cocycle associated with the cover $\{U_i\}$, and φ deforms if and only if the corresponding cohomology class in $H^1(C, \mathcal{N}_{\varphi})$ vanishes

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- The pairing $(\eta, \{\xi_{ij}\})$ is given by

$$\sum_{j} r_{p_{\lambda}}$$

LIdeas and main theorem

 $\varphi \colon C \to S$: map from a smooth curve to a surface

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 $\varphi \colon C \to S$: map from a smooth curve to a surface $\{p_1, \ldots, p_e\}$: Singular points of φ , i.e., $d\varphi_{p_i} = 0$ $Z = (d\varphi)$: ramification divisor of φ

$$0 o \mathcal{H}_{\varphi} o \mathcal{N}_{\varphi} o \bar{\mathcal{N}}_{\varphi} o 0$$

 \mathcal{H}_{arphi} is a torsion sheaf supported at $\{p_1,\ldots,p_e\}$ $ar{\mathcal{N}}_{arphi}$ is locally free

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- We can apply the residue calculation to them

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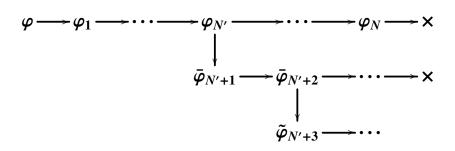
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- In general, the obstruction to deforming φ_N does not vanish
- It means that we cannot deform φ_N no matter how hard we try

$$\varphi \longrightarrow \varphi_1 \longrightarrow \cdots \longrightarrow \varphi_{N'} \longrightarrow \cdots \longrightarrow \varphi_N \longrightarrow \mathsf{X}$$



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- lacktriangle Eventually, we can construct a formal deformation of $oldsymbol{arphi}$

More details

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 $\{p_1,\ldots,p_e\}$: Singular points of φ

At p_i , the pull back of coordinates on S can be written in the form

$$(z_i, w_i) = (s^a, s^b + s^{b+1}g_0(s))$$

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s: a parameter on C around p_i g_0 : a holomorphic function around p_i a < b, assume $a \nmid b$ for simplicity a - 1 is the multiplicity of the singularity p_i , that is, the coefficient of p_i of the divisor $Z = (d\varphi)$ Its deformation can be written as

$$(z_i, w_i) = (s^a + \sum_{j=1}^k \sum_{i=0}^{a-2} t^j c_{a-i,j} s^i, \ s^b + s^{b+1} g_0(s) + \sum_{j=1}^k t^j g_j(s))$$

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It is convenient to consider deformations of the form

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where $c_{a-i} \in t^{a-i}\mathbb{C}[[t]]$

Among such deformations, we consider those of the form

$$(z_i,w_i)=(S^a,\ S^b+S^{b+1}g_0(S)),$$
 where $S=s(1+\sum_{i=1}^{\infty}\prod_{j=0}^{i-1}(\frac{1}{a}-j)\frac{1}{i!}(\sum_{k=2}^{a}\frac{c_k}{s^k})^i)$

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- $lacksquare{S}$ is a reparameterization of C on a *punctured* neighborhood of p_i
- It gives the same image as the original

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- At some order t^N , $S^b + S^{b+1}g_0(S)$ acquires singular terms, and it produces the obstruction
- We modify the value of c_i so that the obstruction vanishes (this is where we use the transversality assumption of the polynomial system)

If the obstruction vanishes, then we can modify the curve in the form $(z_i, w_i) = (S^a, S^b + S^{b+1}g_0(S) + H_i(s))$, and continue the deformation $H_i(s)$ is a meromorphic function around p_i

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- Here, although we are at the order t^N , in general we need to modify c_i in the order lower than t^N
- As we mentioned earlier, this changes the map at the order lower than t^N
- We can check that the new map can be deformed beyond the order t^N

What is the system of polynomial equations?

What is the system of polynomial equations? Substituting $S = s(1 + \sum_{i=1}^{\infty} \prod_{j=0}^{i-1} (\frac{1}{a} - j) \frac{1}{i!} (\sum_{k=2}^{a} \frac{c_k}{s^k})^i)$ to $S^b + S^{b+1}g_0(S)$, we have

$$S^b + S^{b+1}g_0(S) = s^b(1 + \sum_{i=1}^{\infty} f_i^{(b)}(c_2, \dots, c_a) \frac{1}{s^i}) + (\text{higher order terms})$$

$$f_{b+j}^{(b)}(c_2,\ldots,c_a) = \sum_{\lambda \in \mathcal{P}(b+j;[2,a])} \begin{pmatrix} \frac{b}{a} \\ \lambda(2) & \cdots & \lambda(a) \end{pmatrix} c_2^{\lambda(2)} \cdots c_a^{\lambda(a)}$$

$$f_{b+j}^{(b)}(c_2,\ldots,c_a) = \sum_{\lambda \in \mathcal{P}(b+j;[2,a])} \left(\frac{\frac{b}{a}}{\lambda(2)} \cdots \frac{\lambda(a)}{\lambda(a)} \right) c_2^{\lambda(2)} \cdots c_a^{\lambda(a)}$$

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$$\begin{pmatrix} \alpha \\ \beta_1 \cdots \beta_k \end{pmatrix} = \frac{\prod_{i=0}^{\beta_1 + \cdots + \beta_k - 1} (\alpha - i)}{\beta_1! \cdots \beta_k!}$$

$$\begin{array}{ll} S^b + S^{b+1}g_0(S) &= (\text{regular part}) + \\ & \frac{f_{b+1}^{(b)}}{s} + \cdots + \frac{f_{b+a-1}^{(b)}}{s^{a-1}} + (\text{higher order terms}) \end{array}$$

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- Roughly, the part $\frac{f_{b+1}^{(i)}}{s} + \cdots + \frac{f_{b+a-1}^{(i)}}{s^{a-1}}$ controls the obstruction
- If $\eta \in H^0(C, \varphi^*K_S(Z))$, then the pairing between the obstruction class and η has contribution from the singular point p_i , given by the residue of

$$\langle \eta, \frac{f_{b+1}^{(b)}}{s} + \dots + \frac{f_{b+a-1}^{(b)}}{s^{a-1}} \rangle$$

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(G) The varieties defined by

$$\begin{cases} \bar{f}_{b+j}^{(b)} = 0, & j \in [1, a-1] \setminus \{k\}, \\ \bar{f}_{b+k}^{(b)} = C \neq 0, \end{cases}$$

have transverse intersection at some point for each ${\it k}$

$$ar{f}_{b+j}^{(b)}$$
 are modified version of $f_{b+j}^{(b)}$

A singular point p_i of φ satisfies the condition (D) if the inequality

$$\dim H^0(C, \varphi^*\omega_X((a_i-1)p)) < \dim H^0(C, \varphi^*\omega_X) + a_i - 1$$

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$$\dim H^0(C, \varphi^*\omega_X((a_i-1)p)) < \dim H^0(C, \varphi^*\omega_X) + a_i - 1$$

holds, where a_i is the coefficient of p_i in $Z=(d\varphi)$ The singularity has a_i-1 parameters c_2,\ldots,c_{a_i} of deformations

So, roughly this condition says the expected dimension of local deformation is positive

Main theorem

Assume φ is semiregular. If the conditions (G) and (D) are satisfied at each $p_i \in \{p_1 \ldots, p_e\}$, then there is a non-trivial deformation of φ .

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- After checking the condition (D), one can completely forget curves and surfaces
- The problem reduces to studying a system of polynomial equations which depends only on two positive integers a and b

Table:

<i>a</i> =3	(G) holds for $4 \le b \le 30$
4	(G) holds for $5 \le b \le 30$ except $b = 6$
5	(G) holds for $6 \le b \le 30$
6	(G) holds for $7 \le b \le 30$
7	(G) holds for $8 \le b \le 20$
8	(G) holds for $9 \le b \le 20$
9	(G) holds for $10 \le b \le 20$
10	(G) holds for $11 \le b \le 15$

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Theorem

 φ deforms if and only if at least one of the following conditions holds.

- There is at least one p_i such that there is no section of $H^0(C, \varphi^*\omega_X(p_i)) \setminus H^0(C, \varphi^*\omega_X)$.
- The set $H^0(C, \bar{\mathcal{N}}_{\varphi})$ is not zero.

For a = 3, condition (G) is reduced to following.

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$$f(X) = {2k + \frac{1}{3} \choose 3k + 1} X^k + {2k + \frac{1}{3} \choose 3k - 2} X^{k-1} + \dots + {2k + \frac{1}{3} \choose 1} X^{k-1}$$

$$g(X) = {2k + \frac{1}{3} \choose 3k + 1} X^k + {2k + \frac{1}{3} \choose 3k - 3} X^{k-1} + \dots + {2k + \frac{1}{3} \choose 0 + 2k + 1}$$

$$\begin{pmatrix} \alpha \\ \beta_1 & \beta_2 \end{pmatrix} = \frac{\prod_{i=0}^{\beta_1 + \beta_2} (\alpha - i)}{\beta_1! \beta_2!}$$

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- lacktriangle the same holds when we exchange f and g.