

Real plane sextic curves with smooth real part

Alex Degtyarev

(Bilkent University)

Joint w/ Ilia Itenberg

Topology of algebraic varieties

Fix a deformation family \mathcal{X} of complex varieties.

Consider a generic member $X \in \mathcal{X}$ “well understood.”

Try to study “topological” (\approx deformation invariant) properties of specific members $X \in \bar{\mathcal{X}}$, with extra structures.

Ultimate goal: **classification** up to appropriate deformation.

E.g., $\bar{\mathcal{X}} =$ degree d curves in \mathbb{P}^2 , with $\mathcal{X} =$ smooth curves.

singular curves/
equisingular deformation

smooth real curves/
equivariant deformation

↓ ↓
singular real curves/equisingular equivariant deformation

Real = with an anti-holomorphic involution $\sigma: X \rightarrow X$.

Equisingular \approx stratum $\mu = \text{const.}$ No question for **A–D–E**.

→ Topology of algebraic varieties

Degree	Singular complex	Smooth real
$d = 2$	Ancient Greeks (?)	Ancient Greeks (?)
$d = 3$	Newton (?)	Newton (?)
$d = 4$	Klein (?)	Klein (?)
$d = 5$	D–, 1987	Kharlamov, 1981 (used nodal real)
$d = 6$!!	<u>Akyol, 2012</u> (*)	Gudkov (topological) Nikulin, 1979; Kharlamov
$d = 7$??	?? Viro (topological)
$d = 8$??	?? Korchagin, Orevkov, Shustin, ...

*Artal, Carmona, Cogolludo, Tokunaga, ...; Eyral, Oka; ...

*Persson, Urabe, Yang, Shimada, D–, ... ($K3$ -theoretic)

*A–D–E-singularities; non-simple: easier D–, 1989

→ Topology of algebraic varieties

Singular complex vs. smooth real curves: totally different, but:
compatible difficulty,
often similar tools.

Singular and real curves are less studied:

- Gudkov *et al.*, 1966: irreducible quartics.
- Gudkov *et al.*: rational quintics (sets of singularities) ??
- Kharlamov, 1981: one-nodal quintics (to do nonsingular).
- Jaramillo–Puentes, 2021: nodal rational quintics.
- Itenberg, 1991: one-nodal sextics (**problem discovered**).
- Josi, 2017: nodal rational sextics (**same problem**).

The magic of $K3$ -surfaces

The degree $\deg = 6$ seems a natural threshold for curves in \mathbb{P}^2 .
(Similar, $\deg = 4$ is a threshold for surfaces in \mathbb{P}^3 .)

- $\deg < 6$: everything is classical and straightforward.
- $\deg > 6$: nothing is known; there are no tools.
- $\deg = 6$: classical means do not work well, but using the “magic of $K3$ -surfaces” any “reasonable” geometric question can be reduced to an arithmetical problem.

Remarkable fact: these arithmetical problems are very difficult, but they turn out feasible as long as they are $K3$ -related.

Remark 1 *If $C \subset \mathbb{P}^2$ is a sextic with at worst A–D–E-singularities, the (minimal resolution of singularities of) the double covering $X \rightarrow \mathbb{P}^2$ ramified over C is a $K3$ -surface.*

→ The magic of $K3$ -surfaces

- The global Torelli theorem [Pjateckiĭ–Šapiro–Šafarevič, 1971].
- Surjectivity of the period map [Kulikov, 1977].
- Projective models of $K3$ -surfaces [Saint-Donat, 1974].
- The Riemann–Roch theorem (for $K3$):
every (-2) -class is a (unique) algebraic curve!
- Discriminant forms and embeddings of lattices [Nikulin, 1979]
extended in [Miranda–Morrison, 1985, 1986, 2009].
- Groups generated by reflections [Vinberg, 1972].

See also [Beauville, Dolgachev, Huybrechts, ...].

→ The magic of $K3$ -surfaces

In a nutshell: we record the geometric data in the homology

$$H_2(X) \cong L := 2E_8 \oplus 3U$$

and call this the *homological type*.

State simple necessary conditions: they turn out sufficient.

Hence, we have

$$\{\text{homological types}\}/\cong = \{\text{geometric objects}\}/\sim$$

It remains to classify the homological types.

Remark 2 *Extracting geometric invariants back from the homological type may still be difficult.*

Even more difficult is writing down the defining equations.

→ The magic of $K3$ -surfaces

Singular complex sextics:

polarization $h \in H_2(X) \supset \mathbf{S}$ exceptional divisors

Algebraic geometry is in the *lattice type* $\tilde{\mathbf{S}}_h := (\mathbf{S} \oplus \mathbb{Z}h)^\sim$:
this is the “typical” Néron–Severi lattice.

Conditions: \mathbf{S} is a root lattice, $h^2 = 2$, and $h \perp \mathbf{S}$;
besides, there are **no** “bad” vectors $e \in \tilde{\mathbf{S}}_h$ s.t.

$$e^2 = -2, \quad e \cdot h = 0, \quad e \notin \mathbf{S} \quad \text{or} \quad e^2 = 0, \quad e \cdot h = 1.$$

Smooth real sextics:

polarization $h \in H_2(X) \circlearrowleft \theta := \sigma_*$ real structure

Conditions (\mathbf{L}_\pm are the ± 1 -eigenlattices of θ):

$$h^2 = 2, \quad \theta^2 = \text{id}, \quad h \in \mathbf{L}_-, \quad \sigma_+(\mathbf{L}_-) = 2.$$

(By Nikulin, everything is in the 2-elementary lattice \mathbf{L}_- .)

→ The magic of $K3$ -surfaces

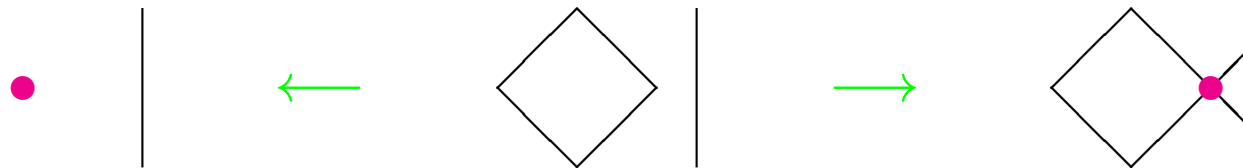
Singular real sextics

We combine the two, recording h , \mathbf{S} , and θ .

The extra condition is that \mathbf{S} must be θ -invariant and, moreover, \mathbf{S} must have a θ -skew-invariant Weyl chamber (??)

The result is called the *real homological type*.

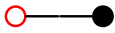
However, this does not determine the deformation class!



Here, the two nodes are indistinguishable homologically!

Remark 3 *Everything is in the homology; we need extra data: a distinguished fundamental polyhedron of a certain group. Difficult to compute, often infinite; hence, try to avoid. In the smooth case, that would be the one containing h .*

Real sextics with smooth real part

The **problem** is due to the **real** singular points: 
(First observed by Josi in the **nodal** case.)

Theorem 4 *Two real simple sextics without real singular points are in the same equisingular equivariant deformation class if and only if their real homological types are isomorphic.*

Hence, we have a complete list of such sextics.

(The arithmetical problem is doable due to its $K3$ -origin.)

Observations: (to be discussed later)

- lack of “obvious” topological invariants;
- extremal congruences for singular curves/surfaces;
- “dominance” of type I real schemes.

→ **Real** sextics with smooth real part

Proof of Theorem 4

Since we want to compare several surfaces, $H_2(X)$ will not do.
The classical approach:

1. Consider *abstract homological types* $(h \in \mathbf{L} \supset \mathbf{S}, \theta)$.
2. Work with *marked* surfaces $(X, \varphi: H_2(X) \xrightarrow{\sim} \mathbf{L})$.
3. Use (1) to define the *period space* Ω of **marked** surfaces.
4. This space is **disconnected**:
it has *walls* $H_v \approx v^\perp \cap \Omega$, where $v \in \mathbf{L}$, $v^2 = -2$, $v \cdot h = 0$.
5. (!!) Prove that (wall crossing) = (change of marking).
It is this part that fails for *real* singular points.

→ Real sextics with smooth real part

In the problem at hand, periods are

$$\omega := (\omega_+, \omega_-) \in \Omega := \mathcal{C}(\tilde{\mathbf{S}}_h^\perp \cap \mathbf{L}_+) \times \mathcal{C}(\tilde{\mathbf{S}}_h^\perp \cap \mathbf{L}_-),$$

where

$$\mathcal{C}(\mathbf{N}) := \{x \in \mathbf{N} \otimes \mathbb{R} \mid x^2 > 0\} / \mathbb{R}^\times$$

is (the projectivization of) the positive cone.

A wall H_v has codimension 1 iff $v \in \mathbf{L}_+$ or $v \in \mathbf{L}_{-h} := h^\perp \subset \mathbf{L}_-$.
It does intersect the positive cone iff $\mathbf{S} + \mathbb{Z}v$ is negative definite.

(Otherwise, x, h, ω_+, ω_- would be four positive squares.)

We need an autoisometry $r: \mathbf{L} \rightarrow \mathbf{L}$ “reflecting” against H_v
and preserving the structure, i.e., h , \mathbf{S} , and θ .

For example, in the smooth case $\mathbf{S} = 0$, ref_v would do.

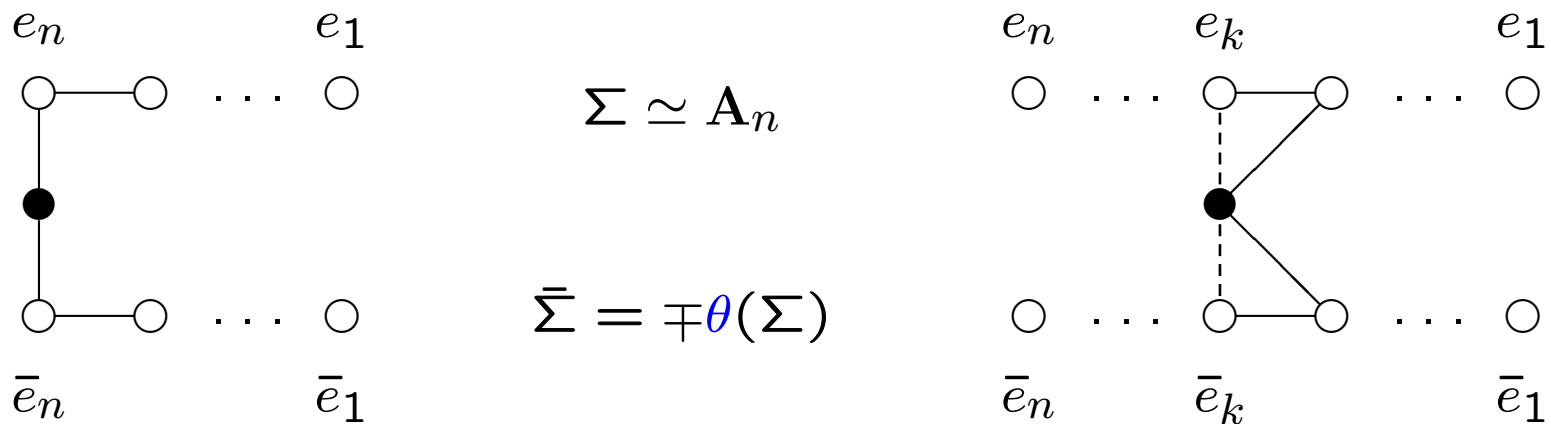
If \circ is a real node and $v = \bullet$ is like $\circ \text{---} \bullet$, there is no hope!

→ **Real** sextics with smooth real part

Thus, (Dynkin basis for **S**) $\cup \{v\}$ must be a “Dynkin diagram” with dotted edges (intersection -1) allowed.

Crucial: the **A–D–E**-components of **S** split into pairs interchanged by θ (no **real** singular points).

Easy to classify: a symmetric graph without induced $\tilde{\mathbf{A}}, \tilde{\mathbf{D}}, \tilde{\mathbf{E}}$.



Both are \mathbf{A}_{2n+1} : $e_{n+1} := v - (e_k + \dots + e_n + \bar{e}_n + \dots + \bar{e}_k)$.

“Reflection” preserving $\{e_i, \mp \bar{e}_i\}$: either $-\theta$ or

$$e_i \leftrightarrow e_{i+n+1}, \quad i = 1, \dots, n, \quad e_{n+1} \mapsto -(e_1 + \dots + e_{2n+1}).$$

Acts trivially on the discriminant \Rightarrow product of reflections. \square

Topological invariants

The classification is topological **by definition**:

distinct deformation families differ **homologically**.

One can try to compute more “visible” invariants:

irreducible components	}	← lattice type
singularities w.r.t. components		
splitting conics $\approx \tilde{\mathbf{S}}_h / (\mathbf{S} \oplus \mathbb{Z}h)$		
components real /conj?	}	← RLT
splitting conics real /conj/...?		
types I/II of the components		
ovals w.r.t. the components		
intersection of halves: number, where		

No fundamental polyhedron \Rightarrow not enough data but

we use heuristic approach + **adjacencies**

Still, **not enough** to distinguish everything!

Interesting phenomena: e.g., differ by **degenerations**.

Some can be explained by the “geometric construction.”

Extremal congruences

Locally irreducible simple singularities: A_{2k} , E_6 , E_8 .

In other words, no 2-torsion in the discriminant.

The *additive Kronecker–Jacobi symbol*

$$J(\mathbf{S}) := \frac{1}{2} - \frac{1}{2} \left(\frac{2}{|\det \mathbf{S}|} \right) = \begin{cases} 0 \bmod 2, & \text{if } \det \mathbf{S} = \pm 1 \bmod 8, \\ 1 \bmod 2, & \text{if } \det \mathbf{S} = \pm 3 \bmod 8. \end{cases}$$

Example 5 $J(\mathbf{S}_1 \oplus \mathbf{S}_2) = J(\mathbf{S}_1) + J(\mathbf{S}_2) \bmod 2$ and

$$J(A_2) = J(A_4) = J(E_6) = 1, \quad J(A_6) = J(A_8) = J(E_8) = 0.$$

Theorem 6 X : a *real* $(M - d)$ -surface, $H_1(X) = 0$ (?),
locally simple singularities $2\mathbf{S}$, none *real*.

- $d = 0 \Rightarrow \chi(X_{\mathbb{R}}) = \sigma(X) + 8J(\mathbf{S}) \bmod 16$;
- $d = 1 \Rightarrow \chi(X_{\mathbb{R}}) = \sigma(X) + 8J(\mathbf{S}) \pm 2 \bmod 16$;
- $d = 2$ & $\chi(X_{\mathbb{R}}) = \sigma(X) + 8J(\mathbf{S}) + 8 \bmod 16 \Rightarrow X$ is type I.

→ Extremal congruences

Example 7 Type I *real* M -schemes of sextics with n ovals:

$$n = 9 : \quad 2A_2 : \quad 2\langle 6 \rangle, 6\langle 2 \rangle$$

$$n = 7 : \quad 2A_4 : \quad 1\langle 5 \rangle, 5\langle 1 \rangle$$

$$4A_2 : \quad 3\langle 3 \rangle$$

$$n = 5 : \quad 6A_2, 2E_6 : \quad 0\langle 4 \rangle$$

$$2A_4 \oplus 2A_2 : \quad 2\langle 2 \rangle$$

Real $(M - 1)$ -schemes:

$$n = 8 : \quad 2A_2 : \quad 1\langle 6 \rangle, 2\langle 5 \rangle, 5\langle 2 \rangle, 6\langle 1 \rangle$$

$$n = 7 : \quad 2A_4 : \quad 0\langle 5 \rangle, 1\langle 4 \rangle, 4\langle 1 \rangle, 5\langle 0 \rangle = 6$$

$$4A_2 : \quad 2\langle 3 \rangle, 3\langle 2 \rangle$$

$$n = 4 : \quad 6A_2, 2E_6 : \quad 0\langle 3 \rangle, 3\langle 0 \rangle = 4$$

$$2A_4 \oplus 2A_2 : \quad 1\langle 2 \rangle, 2\langle 1 \rangle$$

Agrees with “modifications of *real* schemes of type I.”

→ Extremal congruences

Remark 8 *Need to distinguish between two “types I”:*

- *the curve itself, or upon smoothing (type I scheme);*
- *the curve upon the normalization (type I component).*

The two coincide if all singularities are locally irreducible.

Example 9 $2A_2$ does *not* appear in $3\langle 3 \rangle$ of type II.

$4A_2$ does *not* appear in $0\langle 4 \rangle$ or $4\langle 0 \rangle = 5$ of type II.

$2A_4$ does *not* appear in $2\langle 2 \rangle$ of type II.

*They *do* appear in all other schemes with the same n .*

Conjecture 10 *A similar statement *should* hold for*

$$A_3, A_7, A_{11}, \dots, D_5, D_7, \dots,$$

*(no rigorous proof or statement yet), but *not* for*

$$A_1, A_5, \dots, D_4, D_6, \dots, E_7.$$

In other words, no hope if $\text{discr } \mathbf{S}$ has $\mathbb{Z}/2$ -summands.

Modifications of **real** schemes of type I

A phenomenon specific to **real** plane sextics (K3):

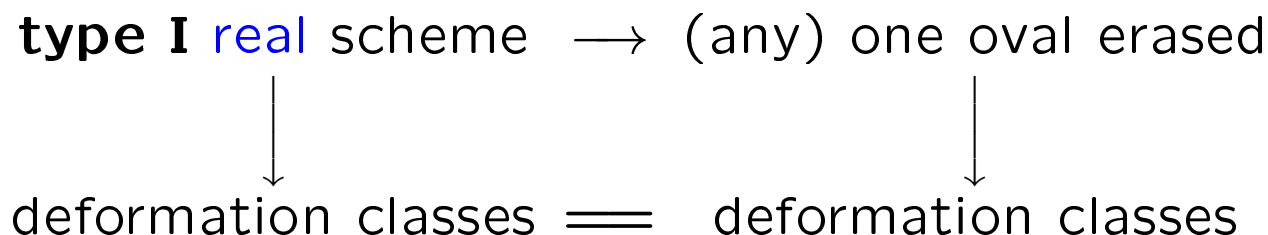
every empty oval can be contracted (and then erased)

Can also be proved in the presence of other **singularities**.

Induces a transformation of the sets of deformation classes.

(May depend on the oval chosen.)

An observation (still needs understanding):



First observed for $\langle\langle 1 \rangle\rangle \rightarrow \langle 1 \rangle$.

For “very” **singular** curves \Leftarrow the “geometric construction.”

The geometric construction

“Very” **singular** sextics have *stable involutions* ($\Leftarrow K3$),
 i.e., involutions $c: \mathbb{P}^2 \rightarrow \mathbb{P}^2$ *persistent throughout the family*

$$\begin{array}{c} C \subset \mathbb{P}^2 \supset O \cup L \\ \downarrow \\ \text{trigonal curve } \bar{C} \subset \Sigma_2 \supset E \cup \bar{L} \text{ except. } + \text{ ord. section} \end{array}$$

The trigonal curve $\bar{C} \subset \Sigma_2$ is *extremal* \approx rigid $\approx \mu(\bar{C}) = 8$.
 Exceptional section: $y = \infty$; ordinary section \bar{L} : a “parabola.”

Also provides **examples** in the non-extremal case:
 involution may exist, but it is no longer stable.

→ The geometric construction

This picture shows all “algebraic geometry”, such as

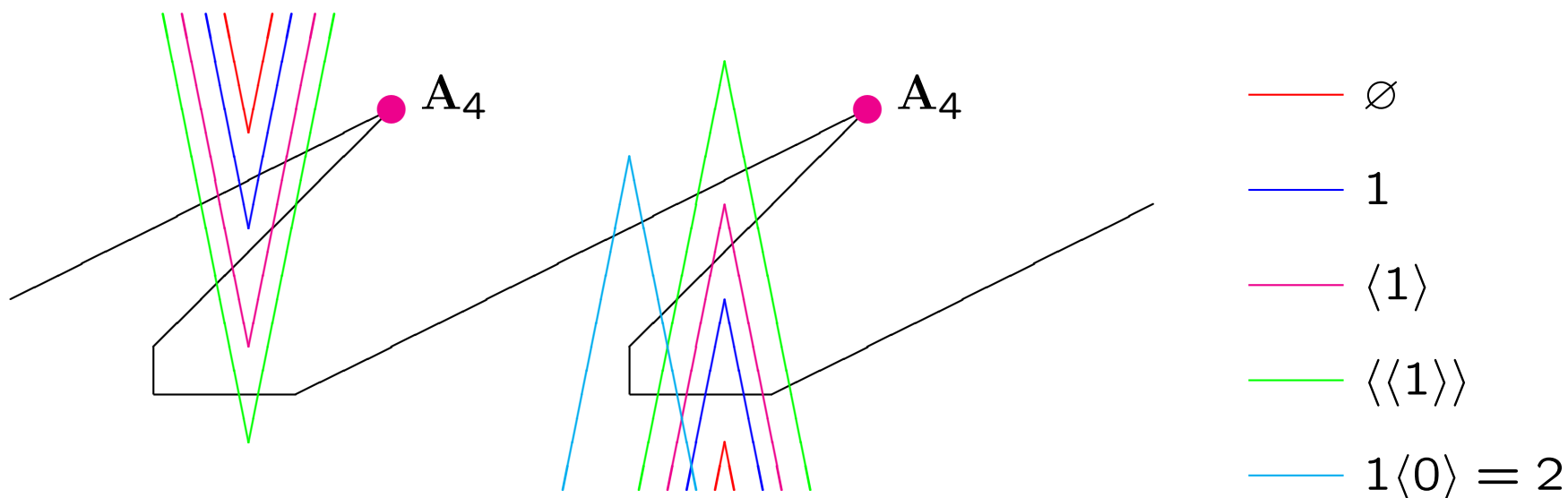
- components of C and the action of σ ,
- splitting conics and the action of σ , etc.,

and a bit of topology (not detectable otherwise), e.g.,

- \bar{C} may have several *real* forms (e.g., if $\text{Sing } \bar{C} = \mathbf{A}_7 \oplus \mathbf{A}_1$),
- “upwards” vs. “downwards” parabolas.

→ The geometric construction

Example 11 The set of *singularities* $4A_4$, with $\text{Sing } \bar{C} = 2A_4$.



Can **always** create an oval inside a nest $\langle 1 \rangle \rightarrow \langle \langle 1 \rangle \rangle$:

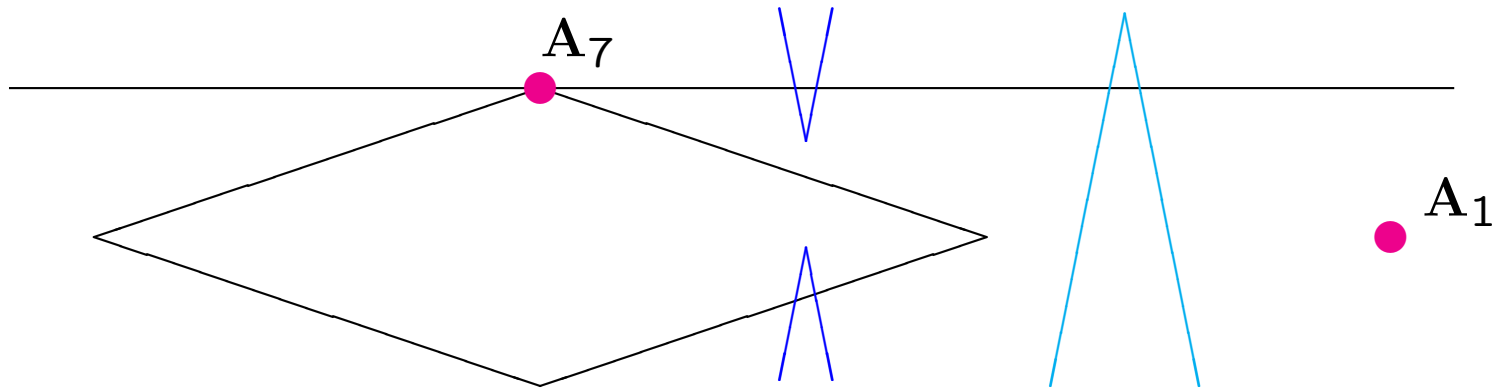
once we see two branches, we also see the third one!

May **not** be able to create an extra oval in $1\langle 0 \rangle = 2$.

Remark 12 Typically, the “upwards”/“downwards” parabolas differ by the action of σ on splitting conics & their pull-backs. The splitting conics are also clearly seen in these pictures: sections passing in a certain way through *singular* points.

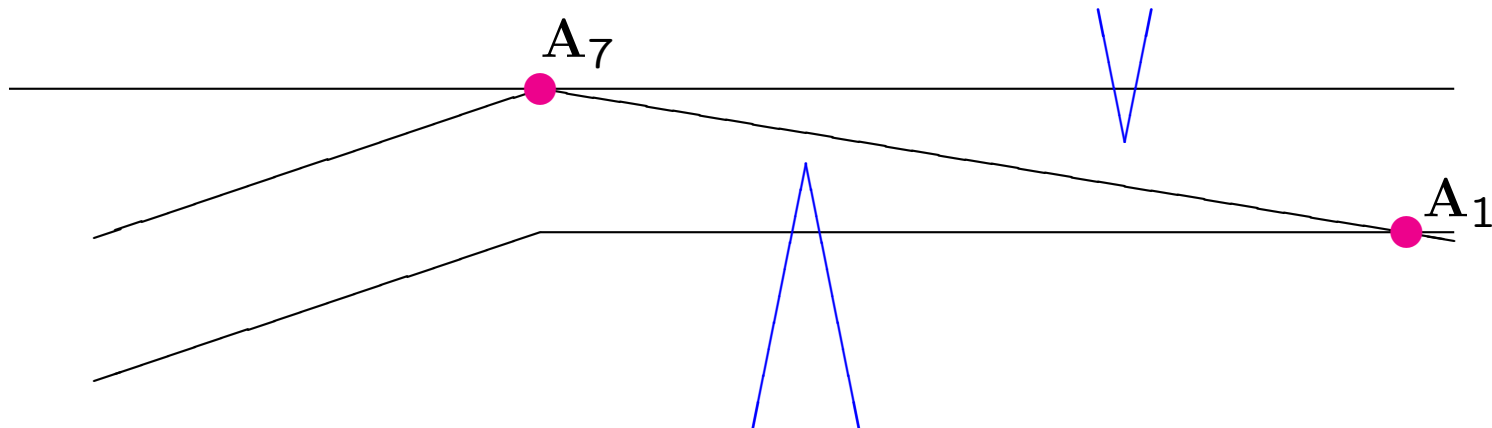
→ The geometric construction

Example 13 $\text{Sing } C = 2A_7 \oplus 2A_1$, with $\text{Sing } \bar{C} = A_7 \oplus A_1$.
 An “ellipse” and a parabola:



May not be able to convert $\mathbf{1}$ to $\langle 1 \rangle$.

There is another *real* form, a “hyperbola” and a parabola;
the distinction upstairs is not clear.



Thank you!