

# Contents

- Brief introduction to Image segmentation
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# Introduction

The shape of an object can be described in terms of:

- Its boundary – requires image edge detection
- The region it occupies – requires image segmentation in homogeneous regions, Image regions generally have homogeneous characteristics (e.g. intensity, texture)

# Introduction- cont.d

- The goal of Image Segmentation is to find regions that represent objects or meaningful parts of objects. Major problems of image segmentation are result of noise in the image.
- An image domain  $X$  must be segmented in  $N$  different regions  $R(1), \dots, R(N)$
- The segmentation rule is a logical predicate of the form  $P(R)$

# Introduction- cont.d

- Image segmentation partitions the set  $X$  into the subsets  $R(i)$ ,  $i=1, \dots, N$  having the following properties

$$X = \bigcup_{i=1, \dots, N} R(i)$$

$$R(i) \cap R(j) = \emptyset \text{ for } i \neq j$$

$$P(R(i)) = \text{TRUE for } i = 1, 2, \dots, N$$

$$P(R(i) \cup R(j)) = \text{FALSE for } i \neq j$$

## Introduction- cont.d

- The segmentation result is a logical predicate of the form  $P(R,x,t)$
- $x$  is a feature vector associated with an image pixel
- $t$  is a set of parameters (usually thresholds) A simple segmentation rule has the form:

$$P(R) : I(r,c) < T$$

## Introduction- cont.d

- In the case of color images the feature vector  $x$  can be three RGB image components  $\{IR(r,c), IG(r,c), IB(r,c)\}$
- A simple segmentation rule may have the form:  
$$P(R,x,t) : (IR(r,c) < T(R)) \ \&\& \ (IG(r,c) < T(G)) \ \&\& \ (IB(r,c) < T(B))$$

# Introduction- cont.d

- A region is called connected if : .....
- A pixel  $(x,y)$  is said to be adjacent to the pixel  $(a,b)$  if it belongs to its immediate neighborhood
- The 4-neighbourhood of a pixel  $(x,y)$
- The 8-neighbourhood of  $(x,y)$

# Types

- By Histogram Thresholding
- By Region Growing and Shrinking
- By Clustering in the color space



# Region Growing

- A simple approach to image segmentation is to start from some pixels (seeds) representing distinct image regions and to grow them, until they cover the entire image
- For region growing we need a rule describing a growth mechanism and a rule checking the homogeneity of the regions after each growth step

## Region Growing – cont.d

- The growth mechanism – at each stage  $k$  and for each region  $R_i(k)$ ,  $i = 1, \dots, N$ , we check if there are unclassified pixels in the 8-neighbourhood of each pixel of the region border
- Before assigning such a pixel  $x$  to a region  $R_i(k)$ , we check if the region homogeneity:  $P(R_i(k) \cup \{x\}) = \text{TRUE}$ , is valid

# Region Growing – cont.d

- The arithmetic mean  $m$  and standard deviation  $sd$  of a class  $R_i$  having  $n$  pixels:

$$M = \frac{1}{n} \sum_{(r,c) \in R(i)} I(r,c)$$

$$s.d. = \sqrt{\frac{1}{n} \sum_{(r,c) \in R(i)} (I(r,c) - M)^2}$$

Can be used to decide if the merging of the two regions  $R_1, R_2$  is allowed, if

$|M_1 - M_2| < (k)s.d(i)$  ,  $i = 1, 2$  , two regions are merged

## Region Growing – cont.d

- Homogeneity test: if the pixel intensity is close to the region mean value

$$|I(r,c) - M(i)| \leq T(i)$$

- Threshold  $T_i$  varies depending on the region  $R_n$  and the intensity of the pixel  $I(r,c)$ . It can be chosen this way:

$$T(i) = \{ 1 - [s.d(i)/M(i)] \} T$$

# Split / Merge

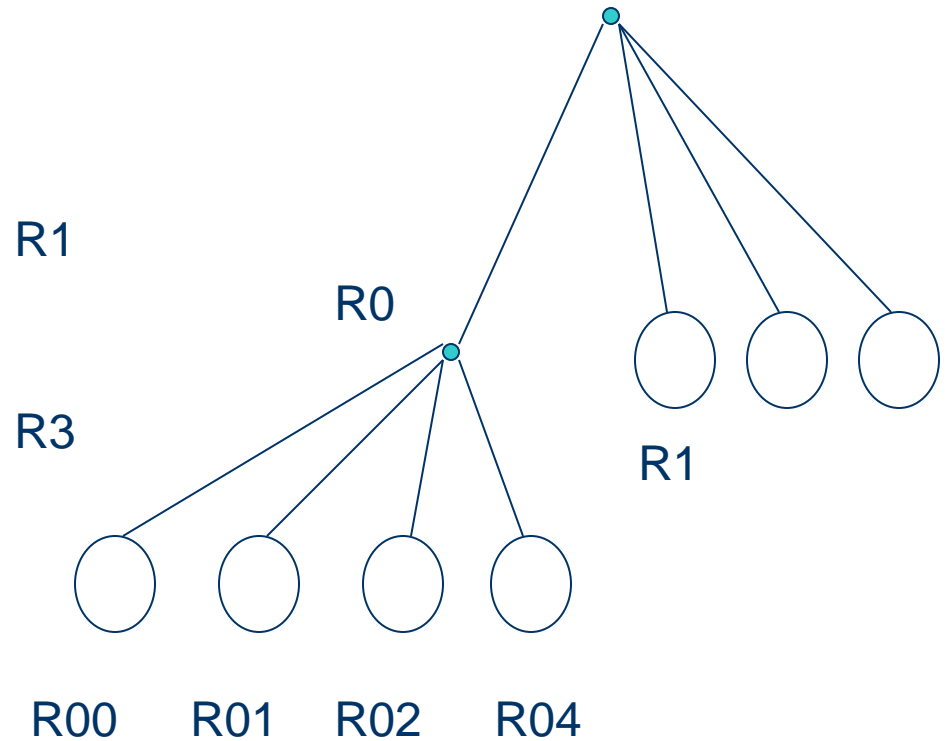
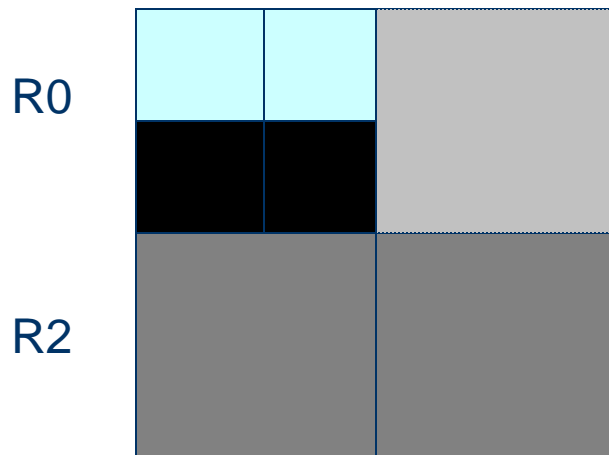
- The opposite approach to region growing is region shrinking ( splitting ).
- It is a top-down approach and it starts with the assumption that the entire image is homogeneous
- If this is not true , the image is split into four sub images
- This splitting procedure is repeated recursively until we split the image into homogeneous regions

# Split / Merge

- If the original image is square  $N \times N$ , having dimensions that are powers of 2 ( $N = 2^n$ ):
- All regions produced by the splitting algorithm are squares having dimensions  $M \times M$ , where  $M$  is a power of 2 as well ( $M = 2^m, M \leq n$ ).
- Since the procedure is recursive, it produces an image representation that can be described by a tree whose nodes have four sons each
- Such a tree is called a Quadtree.

# Split / Merge

Quadtree



# Split / Merge

- Splitting techniques disadvantage, they create regions that may be adjacent and homogeneous, but not merged.
- Split and Merge method – It is an iterative algorithm that includes both splitting and merging at each iteration:



# Split / Merge

- If a region  $R$  is inhomogeneous ( $P(R) = \text{False}$ ) then is split into four sub regions
- If two adjacent regions  $R_i, R_j$  are homogeneous ( $P(R_i \cup R_j) = \text{TRUE}$ ), they are merged
- The algorithm stops when no further splitting or merging is possible

# Split / Merge

- The split and merge algorithm produces more compact regions than the pure splitting algorithm

# Results – Region grow



# Results – Region growing

