## Conservation Laws

Let u be a density and f be a flux. We define a conservation law (1D) as

$$\frac{\partial u}{\partial t} + \frac{\partial f(u)}{\partial x} = 0$$

Integrating with respect to x we get

$$\frac{d}{dt}\int_{a}^{b} u(x,t)dx = -\int_{a}^{b} \frac{\partial f(u)}{\partial x}dx = f(a) - f(b)$$

Hence, the change in the total "mass" changes only through fluxes that enter and leave the boundary. In several dimensions this generalizes to

$$\frac{\partial u}{\partial t} + div(f) = 0$$

and

$$\frac{d}{dt} \int \int_D u(\vec{x}, t) d\vec{x} = -\int \int div(f) d\vec{x} = \oint f ds$$

## Generalized solution

For a linear problem discontinuities occur only across characteristics. For nonlinear problems we can have discontinuities anywhere. We need to define a solution when it is discontinuous

$$\int_{x_L}^{x_R} \left( \frac{\partial u}{\partial t} + \frac{\partial f}{\partial x} \right) \, dx = \frac{d}{dt} \int_{x_L}^{x_R} \frac{\partial u}{\partial t} \, dx + f_R - f_L$$

Hence, space derivatives no longer appear. More generally let  $\phi \in C^{\infty}$  (compact support and infinite number of derivatives). Then

(\*) 
$$\int_{-\infty}^{\infty} \left( \frac{\partial u}{\partial t} + \frac{\partial f}{\partial x} \right) \phi \, dx = \int_{-\infty}^{\infty} \frac{\partial u}{\partial t} \phi \, dx - \int_{-\infty}^{\infty} \frac{\partial \phi}{\partial x} f \, dx$$

 $Def\colon$  A solution is a generalized solution if (\*) is true for every  $\phi$  in some class of functions

*Note*: A classical solution is a generalized solution but not necessarily conversely. Uniqueness may be lost when including generalized solutions !!

## **Rankine-Hugoniot**

Define:

$$I(t) = \int_{a}^{b} u(x,t)dx = \int_{a}^{y(t)} u(x,t)dx + \int_{y(t)}^{b} u(x,t)dx$$

Denote:

$$u_l = u(y^-) \quad u_r = u(y^+) \quad s = \frac{dy}{dt}$$

$$\frac{dI}{dt} = \int_{a}^{y} \frac{\partial u}{\partial t}(x,t)dx + u_{l}s + \int_{y}^{z} \frac{\partial u}{\partial t}(x,t)dx - u_{r}s$$

but  $\frac{du}{dt} = \frac{\partial f}{\partial x}$  . So

$$\frac{dI}{dt} = -\int_{a}^{y} \frac{\partial f}{\partial x}(x,t)dx - \int_{y}^{b} \frac{\partial f}{\partial x}(x,t)dx + (u_{l} - u_{r})s$$
$$= f_{a} - f_{l} - f_{b} + f_{r} + (u_{l} - u_{r})s$$

but  $\frac{dI}{dt} = \int_a^b \frac{\partial f}{\partial x}(x,t)dx = f_a - f_b$ So

$$f_r - f_l = (u_r - u_l)s$$
$$s [u] = [f]$$

example

$$f(u) = \frac{u^2}{2}$$

$$u_t + \left(\frac{u^2}{2}\right)_x = u_t + u \ u_x = 0$$

So the slope of the characteristic curves are:  $\frac{dt}{dx} = \frac{1}{u}$ .

Choose as initial data

$$u_0(x) = \begin{cases} 1 & x \le 0\\ 1 - x & 0 \le x \le 1\\ 0 & 1 \le x \end{cases}$$

Until t=1 the solution is single valued.

To choose the solution after t=1 we use the Rankine-Hugoniot condition

$$s = \frac{[f]}{[u]} = \frac{\frac{u_r^2}{2} - \frac{u_l^2}{2}}{u_r - u_l} = \frac{\frac{0-1}{2}}{0-1} = \frac{1}{2}$$

So for t > 1 we choose the solution

$$u(x,t) = \begin{cases} 1 & x \le \frac{1+t}{2} \\ 0 & \frac{1+t}{2} \le x \end{cases}$$

## Entropy Condition

Characteristics on either side of the discontinuity in the direction of increasing t intersect the line of discontinuity. Hence, we can connect every point on the discontinity back to the initial line. Equivalently

$$a(u_l) > s > a(u_r)$$
  $a = \frac{\partial f}{\partial u}$ 

An equivalent formulation is

$$u_t^{\varepsilon} + f(u^{\varepsilon})_x = (\varepsilon u_x)_x \text{ and } \varepsilon \to 0$$

example

$$f(u) = \frac{u^2}{2}$$

Choose as initial data

$$u_0(x) = \begin{cases} 0 & x \le 0\\ 1 & x > 1 \end{cases}$$

Instead of characteristics colliding we have a gap. Choose

$$u(x,t) = \begin{cases} 0 & x \le \frac{t}{2} \\ 1 & x > \frac{t}{2} \end{cases}$$

This satisfies the Rankine-Hugoniot condition. Consider r

$$u(x,t) = \frac{x}{t}$$

This also satisfies the R-H condition. However, only the second one satisfies the entropy condition.

Definition: A solution is a shock if it satisfies bothe Rankine-Hugoniot condition and the entropy condition