

## Inverse Problems

Fredholm Integral of the first kind

$$g(x, y) = \int_0^1 \int_0^1 k(x - x', y - y') f(x', y') dx' dy' = K f(x, y)$$

Fourier Transform

$$\begin{aligned}\widehat{g} &= \widehat{K} \widehat{f} \\ \widehat{f} &= \widehat{K}^{-1} \widehat{g}\end{aligned}$$

So

$$f = \mathcal{F}^{-1} \left\{ \frac{\mathcal{F}(g)}{\mathcal{F}(K)} \right\}$$

example: atmospheric turbulence

$$k(x, y) = C e^{-\frac{x^2 + y^2}{2\gamma^2}}$$

telescope

$$k(x, y) = \left| \mathcal{F}^{-1} \{ A e^{i\varphi} \} \right|^2$$

A=aperture       $\varphi$  is the phase

Given  $k$  and  $g$  find  $x$

Problems:

- $K$  is ill-conditioned
- Noise

**Definition 1** *Well posed:*

$$(*) \quad K f = g \quad L : H_1 \rightarrow H_2$$

1. for each  $g \in H_2$  there exists  $f \in H_1$  where  $(*)$  holds

2.  $f$  is unique

3. *Stability*

$$\text{If } K f_* = g_*$$

$$K f = g$$

and  $g \rightarrow g_*$  then  $f \rightarrow f_*$

## Tikhonov Regularization

- replace  $*$  by least square minimization. This is equivalent to

$$K^* K f = K^* g$$

- Regularize

$$(K^* K + \alpha I) f = K^* g$$

So

$$f_\alpha = (K^* K + \alpha I)^{-1} K^* g$$

- iterate regularization

More generally we consider

$$f_\alpha = \arg \min \|Kf - g\|^2 + \underbrace{\alpha \|Lf\|^2}_{\text{penalty function}}$$

Even more general

$$f_\alpha = \arg \min \|Kf - g\|^2 + \rho(f)$$

So the penalty function is given by

$$\rho(f)$$

For example

$$\rho(f) = \|Lf\|^2 \quad \text{in some norm}$$

e.g.

$$\rho(f) = \frac{1}{2} \iint \sum_{i=1}^d \left( \frac{\partial f}{\partial x_i} \right)^2 dx_i$$

This penalizes non-smooth functions. Integrate by parts

$$\int \frac{\partial f}{\partial x} \frac{\partial f}{\partial x} dx = - \int f \frac{\partial^2 f}{\partial x^2} dx + \text{boundary terms}$$

Let  $Lf = -\Delta f$ . Then

$$\rho(f) = \frac{1}{2} \iint f Lf dx$$